# Practical Exact Proofs from Lattices: New Techniques to Exploit Fully-Splitting Rings\*

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**Abstract.** We propose a very fast lattice-based zero-knowledge proof system for exactly proving knowledge of a ternary solution  $\vec{s} \in \{-1,0,1\}^n$  to a linear equation  $A\vec{s} = \vec{u}$  over  $\mathbb{Z}_q$ , which improves upon the protocol by Bootle, Lyubashevsky and Seiler (CRYPTO 2019) by producing proofs that are shorter by a factor of 8.

At the core lies a technique that utilizes the module-homomorphic BD-LOP commitment scheme (SCN 2018) over the fully splitting cyclotomic ring  $\mathbb{Z}_q[X]/(X^d+1)$  to prove scalar products with the NTT vector of a secret polynomial.

## 1 Introduction

Zero-knowledge proofs<sup>5</sup> of knowledge are a central building-block in many cryptographic schemes, especially in privacy-preserving protocols (e.g. group signatures). In these protocols there are often underlying basic public-key primitives, such as encryption and signature schemes, and one has to prove certain statements about the ciphertexts and signatures produced by the underlying primitives. In addition to their usefulness in privacy-preserving protocols, zero-knowledge proof systems have also gained a lot of attention in recent years due to their applications in blockchain protocols.

For post-quantum security the underlying public-key primitives have to be built based on quantum-safe computational hardness assumptions, and lattice-based primitives are a leading choice in this regard. Now, when proving statements related to lattice-based primitives, one always ends up proving knowledge of a short solution to a linear system of equations over some prime field  $\mathbb{Z}_q$ . More precisely, we want to be able to prove knowledge of a ternary solution

<sup>\*</sup> This research was supported by the SNSF ERC starting transfer grant FELICITY.

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<sup>&</sup>lt;sup>5</sup> We use the term "proof" instead of the slightly more precise "argument", and mean computationally sound zero-knowledge proof when we just write zero-knowledge proof.

 $\vec{s} \in \{-1, 0, 1\}^n$  to the equation

$$A\vec{s} = \vec{u},\tag{1}$$

where the matrix  $A \in \mathbb{Z}_q^{m \times n}$  and the right hand side  $\vec{u} \in \mathbb{Z}_q^m$  are public. There is no loss of generality in Equation (1) in the sense that it encompasses the situations when the secret vector  $\vec{s}$  has coefficients from a larger interval, or when the equation in fact describes linear relations between polynomials in some polynomial ring  $\mathcal{R}_q$  of higher rank over  $\mathbb{Z}_q$ , which arise in important so-called ring-based constructions. In the first situation the secret coefficients can be expanded in base 3 and thereby the equation transformed to the above form. In the second situation the matrix A has a certain structure that describes the linear relations over  $\mathcal{R}_q$  with respect to some  $\mathbb{Z}_q$ -basis of  $\mathcal{R}_q$ . Then the equation is equivalent to an equation

$$A\vec{s} = \vec{u} \tag{2}$$

with polynomial matrix A, polynomial vector  $\vec{u}$  and short polynomial vector  $\vec{s}$  with coefficients that are ternary polynomials.

We call a proof system that exactly proves knowledge of a ternary vector  $\vec{s}$  as in Equation (1), and hence does not have any knowledge gap, an *exact* proof system. The goal of this paper is to construct an efficient exact lattice-based proof system.

Currently the most efficient lattice-based protocols that include zero-knowledge proofs utilize so-called approximate proof systems which are based on the rejection sampling technique by Lyubashevsky [Lyu09, Lyu12]. Examples are the signature schemes [Lyu12, BG14, DKL<sup>+</sup>18], the group signature schemes [dPLS18, YAZ<sup>+</sup>19, EZS<sup>+</sup>19], and the ring signatures [ESLL19, EZS<sup>+</sup>19]. Efficient approximate proofs work over polynomial rings  $\mathcal{R}_q$  and the prover ends up proving knowledge of a vector  $\vec{s}^*$  over  $\mathcal{R}_q$  fulfilling only the perturbed equation

$$m{A}m{ec{s}}^*=ar{m{c}}m{ec{u}},$$

where  $\bar{c}$  is a short polynomial. Moreover, the coefficients of the polynomials in  $\vec{s}^*$  are from a much larger range then the ternary coefficients in the vector  $\vec{s}$  that the prover actually knows. The most important reason for the practical efficiency of approximate proofs is that they achieve negligible soundness error with only one repetition.

While approximate proofs are sufficient for many applications, their biggest drawback is that one has to account for the longer vector  $\vec{s}^*$  when setting parameters for the underlying schemes so that these schemes are still secure with respect to  $\vec{s}^*$ . Concretely, suppose that as part of a larger protocol one has to encrypt some message and prove linear relations on the message. Then, when using an approximate proof system, one cannot choose a standard and vetted lattice-based encryption scheme such as Kyber [BDK+18], NTRU, or another scheme in round 2 of the NIST PQC standardization effort. This is problematic for both theoretical and practical reasons. Moreover, if some part of the protocol does not require zero-knowledge proofs, then the efficiency of this part

still suffers from the other parts involving zero-knowledge proofs because of the described effect on parameters.

Finally, there are applications for which approximate proof systems are not sufficiently expressive. Natural examples are range proofs for integers and proofs of integer relations, which have applications in blockchain protocols. In these protocols one wants to commit to integers, prove that they lie in certain intervals, and prove additive and multiplicative relations between them. All these problems can be directly solved with an exact proof system that is capable of proving linear equations as above [LLNW18], but approximate proof systems alone are not sufficient for this task. One reason is that one has to commit to the integers in their binary or some other small-base representation and then prove that the committed message really is a binary vector, i.e. that it does not have coefficients from a larger set. This cannot directly be achieved with approximate proofs.

Coming back to exact proof systems, there is a long line of research using Stern's protocol [Ste93] in a lattice setting to exactly prove Equations as in (1) [LLNW17]. But even for the smallest equations, which for example arise when proving a Ring-LWE sample, the proofs produced by this approach have several Megabytes in size and hence are not really practical. The reason behind this is that a single protocol execution has a very large soundness error of 2/3, and thus many protocol repetitions (in the order of hundreds) are required to reach a negligible soundness error.

In [BLS19, YAZ<sup>+</sup>19], the authors use the BDLOP commitment scheme [BDL<sup>+</sup>18] to construct an exact proof system and achieve proof sizes of several hundred Kilobytes for proving Ring-LWE samples. The results in the present paper can be seen as an extension of the results of [BLS19].

Now, for post-quantum security, even when relying on underlying lattice-based primitives, it is of course not necessary to also built the zero-knowledge proof system with lattice techniques, as long as the proof system does not introduce computational assumptions that are known to be insecure against quantum computers. In fact, there are PCP-type proof systems using Kilian's framework [Kil92], such as Ligero [AHIV17] or Aurora [BCR $^+$ 19], that are capable of exactly proving linear equations as above, and that are secure assuming only the security of a hash function. These proof systems are even succinct and produce proofs with sizes that are sublinear or even logarithmic in the size of the witness  $\vec{s}$ , but they have a base cost in the order of 100 KB for Ligero and around 70 KB for Aurora.

The proof system that we present in this paper scales linearly in the witness size but produces proofs of only 47 KB for proving a Ring-LWE sample. So there is a regime of interesting statements where linear-sized proof systems can beat the best logarithmic PCP-type systems in terms of proof size.

For larger equations where we cannot quite achieve proof sizes as small as the PCP-type systems, lattice-based systems still have one big advantage. Namely, they are very computationally lightweight. Implementations of lattice-based cryptography are generally known to be very fast. For example, the fastest lattice-based CCA-secure KEMs have encapsulation and decapsulation times in

the order of a few microseconds on standard laptop processors [LS19] and are thus about one order of magnitude faster than a single elliptic curve scalar multiplication. The reason for this very high speed is essentially twofold. Firstly, there is usually no multi-precision arithmetic needed since efficient lattice-based schemes use finite field moduli q that are below  $2^{32}$ . And secondly, the required arithmetic has a high degree of data-level parallelism that is favourable to modern CPUs, which is especially true for schemes whose arithmetic natively supports the Number Theoretic Transform (NTT). The protocols that we present in this paper are no exception to this; they use single-precision 32-bit moduli, are NTT-friendly, and don't introduce any computational tasks that are not also present in standard lattice-based basic encryption or signature schemes. We demonstrate the fast speed of our protocols with an optimized implementation for Intel CPUs that achieves prover and verifier running times of 3.52 and 0.4 milliseconds, respectively, for the case of proving a ternary solution to a linear equation of dimensions  $1024 \times 2048$  (see [ENS20, Appendix C] for more details).

Contrary to this, existing studies of using logarithmic PCP-type proof systems for proving the linear equations (1) that arise in lattice-based privacy-preserving protocols show that one ends up with prover runtimes in the order of several tens of seconds even for the smallest instances and on very powerful processors [BCOS20]. This also seems to be the case for the logarithmic but not quantum-safe Bulletproofs proof system [dPLS19]. For example, in [BCOS20] the authors construct a lattice-based group signature scheme using Aurora as the proof system. They found that proving a Ring-LWE sample takes 40 seconds on a laptop computer. Even worse, they could not successfully run the full signing algorithm, due to very large memory requirements, even with the help of Google Cloud large-memory compute instances. This is especially problematic since for privacy-preserving protocols to be used in practice, the prover would often need to be run on constraint devices, possibly down to smart cards or TPM chips. We summarize the above comparison in Table 1.

**Table 1.** Proof length comparison for proving knowledge of a Ring-LWE sample in dimension 1024 modulo a prime  $q \approx 2^{32}$ . Here the dimensions of the corresponding Equation as in (1) are m=1024 and n=2048. The sizes for the Stern-type proof is taken from [BLS19]. The sizes for Ligero and the scheme from [Beu20] are taken from [Beu20] and are for the parameter m=512.

Stern-type proofs	$3522~\mathrm{KB}$
[BLS19]	384 KB
[Beu20]	233 KB
Ligero [AHIV17]	157 KB
Aurora [BCR <sup>+</sup> 19, BCOS20]	72 KB
Our work	47 KB

# 1.1 Our Approach

The proof system in the present work extends the system from [BLS19]. On a high level, the approach entails committing to a polynomial  $\check{s} \in \mathcal{R}_q$  whose NTT basis representation is equal to the secret vector  $\vec{s}$ , NTT( $\check{s}$ ) =  $\vec{s}$ . Then, using a product proof protocol that allows to prove multiplicative relations between committed polynomials, the prover shows that  $\check{s}(1-\check{s})(1+\check{s})=0$ . This implies that  $\vec{s}$  has ternary coefficients since the polynomial product is component-wise in the NTT basis,

$$\mathsf{NTT}(\check{s}(\mathbf{1}-\check{s})(\mathbf{1}+\check{s})) = \vec{s} \circ (\vec{1}-\vec{s}) \circ (\vec{1}+\vec{s}),$$

where  $\vec{1} = (1, ..., 1)^T$  is the all-ones vector and  $\circ$  denotes the component-wise product. What remains is the linear part where the prover needs to show that  $\vec{s}$  is a solution to Equation (1). The linear part was the biggest obstacle to smaller proof sizes in [BLS19]. The reason is that while the BDLOP commitment scheme makes it very easy to prove linear relations over the polynomial ring  $\mathcal{R}_q$ , one needs to be able to prove linear relations between the NTT coefficients corresponding to the committed polynomials when using the above encoding of the secret vector.

Essentially there are two ways to commit to vectors using the BDLOP commitment scheme. Either one commits to polynomials whose coefficient vectors are equal to the secret vectors, or one commits to polynomials whose NTT vectors are the secret vectors. The first way makes it easy to prove structured linear equations as in (2) by directly using the homomorphic property of the commitment scheme. The second way allows for efficient range proofs with the help of an efficient product proof. But we need to prove a linear equation and conduct a range proof at the same time.

In [BLS19] the problem is side-stepped by reusing a masked opening z of the committed polynomial  $\check{s}$  with scalar challenge  $c \in \mathbb{Z}_q$ ,

$$z = y + c\check{s},$$

which is sent as part of the product proof. The verifier can apply the NTT to get a masked opening of the secret vector  $\vec{s}$ ,  $\mathsf{NTT}(z) = \hat{y} + c\vec{s}$ , and then check that  $A\mathsf{NTT}(z) = \vec{w} + c\vec{u}$ , where  $\vec{w} = A\hat{y}$  is sent by the prover before seeing the challenge c. This approach crucially requires that the challenge c is an integer from  $\mathbb{Z}_q$  and not a proper polynomial. Otherwise the masked opening  $\mathsf{NTT}(z)$  of  $\vec{s}$  would include a component-wise product that is incompatible with the linear equation. But with only an integer challenge c the protocol is restricted to soundness error 1/q and hence needs to be repeated multiple times.

The main new technique in this paper is a more efficient method to directly prove linear relations among NTT coefficients of the message polynomials in the BDLOP commitment scheme. Then the product proof can make use of proper polynomial challenges and our proof system profits from further improvements in the product proof presented recently in [ALS20].

We now go a bit more into detail and describe our method for the linear proof. For concreteness, let us define  $\mathcal{R}_q = \mathbb{Z}_q[X]/(X^d+1)$ , where d is a power

of two and  $X^d + 1$  splits fully into linear factors over  $\mathbb{Z}_q$ . Then the *i*-th NTT coefficient of a polynomial  $\check{s} \in \mathcal{R}_q$  is equal to the evaluation of  $\check{s}$  at the *i*-th primitive 2d-th root of unity  $r_i$ . Therefore, if  $\vec{s} = \mathsf{NTT}(\check{s})$  and  $\vec{\gamma} \xleftarrow{\$} \mathbb{Z}_q^d$  is a random vector, we have

$$\begin{split} \langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle &= \langle A\vec{s}, \vec{\gamma} \rangle - \langle \vec{u}, \vec{\gamma} \rangle = \langle \vec{s}, A^T \vec{\gamma} \rangle - \langle \vec{u}, \vec{\gamma} \rangle \\ &= \sum_{i=0}^{d-1} \check{\boldsymbol{s}}(r_i) \left( \mathsf{NTT}^{-1} (A^T \vec{\gamma}) \right) (r_i) - \langle \vec{u}, \vec{\gamma} \rangle \\ &= \frac{1}{d} \sum_{i=0}^{d-1} \boldsymbol{f}(r_i) = f_0, \end{split}$$

where  $\mathbf{f} = \mathsf{NTT}^{-1}(dA^T\vec{\gamma})\check{s} - \langle \vec{u}, \vec{\gamma} \rangle \in \mathcal{R}_q$  and  $f_0 \in \mathbb{Z}_q$  is the constant coefficient of  $\mathbf{f}$ . The last equality follows from Lemma 2.1. The idea is then to prove that  $f_0$ , the constant coefficient of  $\mathbf{f}$ , is zero. This proves that  $\langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle = 0$ . For a uniformly random  $\vec{\gamma} \in \mathbb{Z}_q^d$ , the probability that  $\langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle = 0$  when  $A\vec{s} \neq \vec{u}$  is 1/q. Therefore, allowing the verifier to choose a random  $\vec{\gamma} \in \mathbb{Z}_q^d$  as a challenge, proving  $f_0 = 0$  proves that  $A\vec{s} = \vec{u}$  with a soundness error 1/q.

To prove that f has vanishing constant coefficient, the prover initially commits to  $\check{s}$  and a polynomial g with vanishing constant coefficient. The polynomial g will be used to mask f. Upon receiving a challenge  $\vec{\gamma} \in \mathbb{Z}_q^d$ , the prover computes f and sets h = f + g. Using the given information, we show that the verifier can compute a commitment to f (without requiring it to be sent by the prover). This allows to prove that h is of the correct form and the verifier can simply observe that h has a zero constant coefficient.

The above proof system has a soundness error of 1/q, which is not negligibly small for typical choices of q. We show in Section 3.2 how to amplify the soundness of this protocol at a low cost using Galois automorphisms. Informally, consider k uniformly random vectors  $\vec{\gamma}_0, \ldots, \vec{\gamma}_{k-1}$  such that  $1/q^k$  is negligible. Similarly as before, we can write

$$\mathbf{f}_i := d\mathsf{NTT}^{-1}(A^T \vec{\gamma}_i) \check{\mathbf{s}} - \langle \vec{u}, \vec{\gamma}_i \rangle$$

and thus the constant coefficient of  $f_i$  is  $\langle A\vec{s} - \vec{u}, \vec{\gamma}_i \rangle$ . For each  $i = 0, \ldots, k-1$ , we will define maps  $\mathsf{L}_i \colon \mathcal{R}_q \to \mathcal{R}_q$  which satisfies the following property. Denote  $p = \mathsf{L}_i(f_i)$  and  $(p_0, \ldots, p_{d-1})$  to be the coefficient vector of p. Then,  $p_0 = \ldots = p_{i-1} = p_{i+1} = \ldots = p_{k-1} = 0$  and  $p_i = \langle A\vec{s} - \vec{u}, \vec{\gamma}_i \rangle$ . We can observe that if  $A\vec{s} = \vec{u}$  then f defined now as

$$f = L_0(f_0) + ... + L_{k-1}(f_{k-1})$$

has the first k coefficients equal to 0. Therefore, we can construct a protocol for proving this similarly as above. On the other hand, when  $A\vec{s} \neq \vec{u}$  then the probability that all the first k coefficients of f are equal to zero is  $1/q^k$ . The advantage of this approach over the standard way of having k-parallel repetitions is that the size of the commitment part of the non-interactive proof remains the

same as that of a single protocol run. Therefore, the overall cost is significantly reduced.

We believe that this protocol can be useful in other settings, where one wants to switch from the the coefficient basis to the NTT basis.

Another obstacle against practical efficiency (as encountered in [BLS19, YAZ<sup>+</sup>19]) is that a proof of such a non-linear relation as in (1) requires communication of "garbage terms". These garbage terms end up being a substantial cost in the proofs in [BLS19, YAZ<sup>+</sup>19]. In [ALS20], a better product proof is presented that reduces the cost of the garbage terms, also using Galois automorphisms.

Applications. Having an efficient proof system to prove knowledge of  $\vec{s} \in \{-1,0,1\}^n$  satisfying (1) paves the way for various efficient zero-knowledge proofs that can be used in many applications. In order to show the effectiveness of our new techniques, we present two example applications with concrete parameters in the full version of our paper [ENS20]. The first one is to prove knowledge of secrets in LWE samples. This is an important proof system to be used, for example, with fully homomorphic encryption (FHE) schemes. The goal here is to prove that  $\vec{u}$  is a proper LWE sample such that  $\vec{u} = A'\vec{s}' + \vec{e} \mod q$  for  $\vec{s}', \vec{e} \in \{-1,0,1\}^k$ , which is equivalent to proving  $\vec{u} = (A' \parallel I_k) \cdot \vec{s}' \mod q$  for  $\vec{s} = (\vec{s}', \vec{e}) \in \{-1,0,1\}^{2k}$ . As shown in Table 1, our proof system achieves an improvement of  $8 \times$  in terms of proof length over the state-of-the-art result by Bootle, Lyubashevsky and Seiler [BLS19], and is dramatically shorter than the Stern-based proofs.

Our other example application is a proof of plaintext knowledge. In this case, the goal is to create a ciphertext and a zero-knowledge proof to prove that the ciphertext is a proper encryption of a message known by the prover. Proofs of plaintext knowledge have applications, for example, in the settings of verifiable encryption, verifiable secret sharing and group signatures.

Being a very core proof system, there are many other applications beyond the two examples above, where our main protocol and our new techniques can be useful. For example, one can apply our unstructured linear proof to prove that one vector is a NTT representation of a polynomial (written as a vector of coefficients). Indeed, the matrix A in (1) simply becomes a Vandermonde matrix. Furthermore, one can see [YAZ<sup>+</sup>19] for various applications that all build on a similar core proof system.

## 2 Preliminaries

#### 2.1 Notation

Table 2 summarizes the notation and parameters that will appear in this paper. Let q be an odd prime, and  $\mathbb{Z}_q$  denote the ring of integers modulo q. We write  $[a,b[=\{a,a+1,\ldots,b-1\}\subset\mathbb{Z} \text{ for the half-open interval of integers between }a$  and b. For  $r\in\mathbb{Z}$ , we define r mod q to be the unique element in the interval  $[-\frac{q-1}{2},\frac{q-1}{2}]$  that is congruent to r modulo q. We write  $\vec{v}\in\mathbb{Z}_q^m$  to denote vectors over  $\mathbb{Z}_q$  and matrices over  $\mathbb{Z}_q$  will be written as regular capital letters M. By

Parameter	Explanation
d	Degree of the polynomial $X^d + 1$ , power of two
q	Rational prime modulus
$\mathbb{Z}_q = \mathbb{Z}/q\mathbb{Z}$	The field over which the linear system is defined
$m \in \mathbb{Z}$	The number of rows in the linear system
$n \in \mathbb{Z}$	The number of columns in the linear system
$\mathcal{R} = \mathbb{Z}[X]/(X^d + 1)$	The ring of integers in the 2d-th cyclotomic number field
$\mathcal{R}_q = \mathbb{Z}_q[X]/(X^d + 1)$	The ring of integers $\mathcal{R}$ modulo $q$
$k \in \mathbb{Z}$	Repetition rate
$\sigma = \sigma_{2d/k+1}$	Automorphism in $Aut(\mathcal{R}_q)$ of order $k$
$\mathcal{C}\subset\mathcal{R}$	Challenge set
C	Probability distribution over $\mathcal{C}$ for challenges
T	Bound for honest prover's $c\vec{r}$ in the infinity norm
$\delta_1$	width of the uniform distribution for sampling $\vec{y}$
λ	M-LWE dimension
$\kappa$	M-SIS dimension
χ	Error distribution on $\mathcal{R}$ in the M-LWE problem

Table 2. Overview of Parameters and Notation

default, all vectors are column vectors. We write  $\vec{v} \parallel \vec{w}$  for the concatenation of  $\vec{v}$  and  $\vec{w}$  (which is still a column vector).

Let d be a power of two and denote  $\mathcal{R}$  and  $\mathcal{R}_q$  to be the rings  $\mathbb{Z}[X]/(X^d+1)$  and  $\mathbb{Z}_q[X]/(X^d+1)$ , respectively. Bold lower-case letters  $\boldsymbol{p}$  denote elements in  $\mathcal{R}$  or  $\mathcal{R}_q$  and bold lower-case letters with arrows  $\vec{\boldsymbol{b}}$  represent column vectors with coefficients in  $\mathcal{R}$  or  $\mathcal{R}_q$ . We also use bold upper-case letters for matrices  $\boldsymbol{B}$  over  $\mathcal{R}$  or  $\mathcal{R}_q$ . For a polynomial denoted as a bold letter, we write its i-th coefficient as the corresponding regular font letter with subscript i, e.g.  $f_0 \in \mathbb{Z}_q$  is the constant coefficient of  $\boldsymbol{f} \in \mathcal{R}_q$ .

We write  $x \stackrel{\$}{\leftarrow} S$  when  $x \in S$  is sampled uniformly at random from the finite set S and similarly  $x \stackrel{\$}{\leftarrow} D$  when x is sampled according to the distribution D.

Norms and Sizes. For an element  $w \in \mathbb{Z}_q$ , we write |w| to mean  $|w \mod q|$ . Define the  $\ell_{\infty}$  and  $\ell_2$  norms for  $w \in \mathcal{R}_q$  as follows,

$$\|\boldsymbol{w}\|_{\infty} = \max_{i} |w_{i}| \text{ and } \|\boldsymbol{w}\|_{2} = \sqrt{|w_{0}|^{2} + \ldots + |w_{d-1}|^{2}}.$$

Similarly, for  $\vec{\boldsymbol{w}} = (\boldsymbol{w}_1, \dots, \boldsymbol{w}_k) \in \mathcal{R}^k$ , we define

$$\left\| ec{oldsymbol{w}} 
ight\|_{\infty} = \max_{i} \left\| oldsymbol{w}_{i} 
ight\|_{\infty} \quad ext{and} \quad \left\| ec{oldsymbol{w}} 
ight\|_{2} = \sqrt{\left\| oldsymbol{w}_{1} 
ight\|_{2}^{2} + \ldots + \left\| oldsymbol{w}_{k} 
ight\|_{2}^{2}}.$$

#### 2.2 Prime Splitting and Galois Automorphisms

Let l be a power of two dividing d and suppose  $q-1 \equiv 2l \pmod{4l}$ . Then,  $\mathbb{Z}_q$  contains primitive 2l-th roots of unity but no elements with order a higher power

of two, and the polynomial  $X^d + 1$  factors into l irreducible binomials  $X^{d/l} - \zeta$  modulo q where  $\zeta$  runs over the 2l-th roots of unity in  $\mathbb{Z}_q$  [LS18, Theorem 2.3].

The ring  $\mathcal{R}_q$  has a group of automorphisms  $\mathsf{Aut}(\mathcal{R}_q)$  that is isomorphic to  $\mathbb{Z}_{2d}^{\times}$ ,

$$i \mapsto \sigma_i \colon \mathbb{Z}_{2d}^{\times} \to \operatorname{Aut}(\mathcal{R}_q),$$

where  $\sigma_i$  is defined by  $\sigma_i(X) = X^i$ . In fact, these automorphisms come from the Galois automorphisms of the 2d-th cyclotomic number field which factor through  $\mathcal{R}_a$ .

The group  $\operatorname{Aut}(\mathcal{R}_q)$  acts transitively on the prime ideals  $(X^{d/l} - \zeta)$  in  $\mathcal{R}_q$  and every  $\sigma_i$  factors through field isomorphisms

$$\mathcal{R}_q/(X^{d/l}-\zeta) \to \mathcal{R}_q/(\sigma^i(X^{d/l}-\zeta)).$$

Concretely, for  $i \in \mathbb{Z}_{2d}^{\times}$  it holds that

$$\sigma_i(X^{d/l} - \zeta) = (X^{id/l} - \zeta) = (X^{d/l} - \zeta^{i^{-1}})$$

To see this, observe that the roots of  $X^{d/l} - \zeta^{i^{-1}}$  (in an appropriate extension field of  $\mathbb{Z}_q$ ) are also roots of  $X^{id/l} - \zeta$ . Then, for  $f \in \mathcal{R}_q$ ,

$$\sigma_i\left(f \bmod (X^{d/l} - \zeta)\right) = \sigma_i(f) \bmod (X^{d/l} - \zeta^{i^{-1}}).$$

The cyclic subgroup  $\langle 2l+1\rangle < \mathbb{Z}_{2d}^{\times}$  has order d/l [LS18, Lemma 2.4] and stabilizes every prime ideal  $(X^{d/l}-\zeta)$  since  $\zeta$  has order 2l. The quotient group  $\mathbb{Z}_{2d}^{\times}/\langle 2l+1\rangle$  has order l and hence acts simply transitively on the l prime ideals. Therefore, we can index the prime ideals by  $i \in \mathbb{Z}_{2d}^{\times}/\langle 2l+1\rangle$  and write

$$(X^d+1) = \prod_{i \in \mathbb{Z}_{2d}^{\times}/\langle 2l+1 \rangle} (X^{d/l} - \zeta^i)$$

Now, the product of the  $k \mid l$  prime ideals  $(X^{d/l} - \zeta^i)$  where i runs over  $\langle 2l/k + 1 \rangle / \langle 2l + 1 \rangle$  is given by the ideal  $(X^{kd/l} - \zeta^k)$ . So, we can partition the l prime ideals into l/k groups of k ideals each, and write

$$\left(X^d+1\right) = \prod_{j \in \mathbb{Z}_{2d}^\times/\langle 2l/k+1\rangle} \left(X^{kd/l} - \zeta^{jk}\right) = \prod_{j \in \mathbb{Z}_{2d}^\times/\langle 2l/k+1\rangle} \prod_{i \in \langle 2l/k+1\rangle/\langle 2l+1\rangle} \left(X^{\frac{d}{l}} - \zeta^{ij}\right).$$

Another way to write this, which we will use in our protocols, is to note that  $\mathbb{Z}_{2d}^{\times}/\langle 2l/k+1\rangle \cong \mathbb{Z}_{2l/k}^{\times}$  and the powers  $(2l/k+1)^i$  for  $i=0,\ldots,k-1$  form a complete set of representatives for  $\langle 2l/k+1\rangle/\langle 2l+1\rangle$ . So, if  $\sigma=\sigma_{2l/k+1}\in \operatorname{Aut}(\mathcal{R}_q)$ , then

$$(X^d+1) = \prod_{j \in \mathbb{Z}_{2l/k}^{\times}} \prod_{i=0}^{k-1} \sigma^i \left( X^{\frac{d}{l}} - \zeta^j \right),$$

and the prime ideals are indexed by  $(i,j) \in I = \{0,\ldots,k-1\} \times \mathbb{Z}_{2l/k}^{\times}$ .

The fully splitting case. In this paper our main attention lies on the setup where  $q \equiv 1 \pmod{2d}$  and hence q splits completely. In this case there is a primitive 2d-th root of unity  $\zeta \in \mathbb{Z}_q$  and

$$(X^d+1) = \prod_{i \in \mathbb{Z}_{2d}^{\times}} (X-\zeta^i).$$

Then, for a divisor k of d and  $\sigma = \sigma_{2d/k+1}$  of order k, we have the partitioning

$$(X^d+1) = \prod_{j \in \mathbb{Z}_{2d}^{\times}/\langle 2d/k+1 \rangle} \prod_{i \in \langle 2d/k+1 \rangle} (X-\zeta^{ij}) = \prod_{j \in \mathbb{Z}_{2d/k}^{\times}} \prod_{i=0}^{k-1} \sigma^i (X-\zeta^j)$$

#### 2.3 The Number Theoretic Transform

The Number Theoretic Transform (NTT) of a polynomial  $f \in \mathcal{R}_q$  is defined by

$$\mathsf{NTT}(\boldsymbol{f}) = (\hat{\boldsymbol{f}}_i)_{i \in \mathbb{Z}_{2l}^\times} \in \prod_{i \in \mathbb{Z}_{2l}^\times} \mathbb{Z}_q[X]/(X^{d/l} - \zeta^i) \cong (\mathbb{F}_{q^{d/l}})^l$$

where  $\hat{f}_i = f \mod (X^{d/l} - \zeta^i)$ . We write  $\mathsf{NTT}^{-1}(\hat{f}) = f$  for the inverse map, which exists due to the Chinese remainder theorem. Note that for  $f, g \in \mathcal{R}_q$ ,  $\mathsf{NTT}(fg) = \mathsf{NTT}(f) \circ \mathsf{NTT}(g)$  where  $\circ$  denotes the coefficient-wise multiplication of vectors.

The (scaled) sum of the NTT coefficients of a polynomial  $\mathbf{f} \in \mathcal{R}_q$  is equal to its first d/l coefficients. This will be later used when proving unstructured linear relations over  $\mathbb{Z}_q$ .

**Lemma 2.1.** Let  $\mathbf{f} \in \mathcal{R}_q$ . Then  $\frac{1}{l} \sum_{i \in \mathbb{Z}_{2l}^{\times}} \hat{\mathbf{f}}_i = f_0 + f_1 X + \dots + f_{d/l-1} X^{d/l-1}$ , when we lift the  $\hat{\mathbf{f}}_i$  to  $\mathbb{Z}_q[X]$ .

*Proof.* Write  $\mathbf{f}(X) = \mathbf{f}_0(X^{d/l}) + \mathbf{f}_1(X^{d/l})X + \cdots + \mathbf{f}_{d/l-1}(X^{d/l})X^{d/l-1}$  Then, it suffices to prove

$$\frac{1}{l} \sum_{i \in \mathbb{Z}_{2l}^{\times}} \mathbf{f}_j(\zeta^i) = f_j$$

for all  $j=0,\ldots,d/l-1$ , which is the sum over the coefficients of a fully splitting length-l NTT. We find

$$\sum_{i \in \mathbb{Z}_{2l}^{\times}} \mathbf{f}_{j}(\zeta^{i}) = \sum_{i \in \mathbb{Z}_{2l}^{\times}} \sum_{\nu=0}^{l-1} f_{\nu d/l+j} \zeta^{i\nu} = \sum_{\nu=0}^{l-1} f_{\nu d/l+j} \sum_{i \in \mathbb{Z}_{2l}^{\times}} \zeta^{i\nu}$$

and it remains to show that for every  $\nu \in \{1, \dots, l-1\}$ ,  $\sum_{i \in \mathbb{Z}_{2l}^{\times}} \zeta^{i\nu} = 0$ . Indeed,

$$\sum_{i \in \mathbb{Z}_{2l}^{\times}} \zeta^{i\nu} = \sum_{i=0}^{l-1} \zeta^{(2i+1)\nu} = \zeta^{\nu} \sum_{i=0}^{l-1} \zeta^{2i\nu} = \zeta^{\nu} \frac{\zeta^{2l\nu} - 1}{\zeta^{2\nu} - 1} = 0$$

since  $\zeta^{2l\nu} = 1$ .

## 2.4 Challenge Space

Let  $\mathcal{C} = \{-1,0,1\}^d \subset \mathcal{R}_q$  be the set of ternary polynomials, which have coefficients in  $\{-1,0,1\}$ . We define  $C: \mathcal{C} \to [0,1]$  to be the probability distribution on  $\mathcal{C}$  such that the coefficients of a challenge  $\mathbf{c} \xleftarrow{\$} \mathcal{C}$  are independently identically distributed with  $\Pr(0) = 1/2$  and  $\Pr(1) = \Pr(-1) = 1/4$ .

In [ALS20] it is shown that if  $\mathbf{c} \stackrel{\$}{\leftarrow} C$  then the distribution of  $\mathbf{c} \mod X^{kd/l} - \zeta^k$  is almost uniform.

**Lemma 2.2.** Let  $c \stackrel{\$}{\leftarrow} C$ . The coefficients of  $c \mod X^{kd/l} - \zeta^k$  are independently identically distributed, say with distribution X. Then, for  $x \in \mathbb{Z}_q$ ,

$$\Pr(X = x) \le \frac{1}{q} + \frac{2l/k}{q} \sum_{j \in \mathbb{Z}_q^*/\langle \zeta^k \rangle} \prod_{i=0}^{l/k-1} \left| \frac{1}{2} + \frac{1}{2} \cos(2\pi j \zeta^{ki}/q) \right|.$$
 (3)

For example, by numerical computing the probability in Lemma 2.2, one finds for d=128,  $q\approx 2^{32}$  fully splitting, i.e. l=d, and k=4, that the maximum probability for the coefficients of  $\boldsymbol{c} \mod X^4 - \zeta^4$  is bounded by  $2^{-31.4}$ .

#### 2.5 Module-SIS and Module-LWE Problems

We employ the computationally binding and computationally hiding commitment scheme from [BDL<sup>+</sup>18] in our protocols, and rely on the well-known Module-LWE (MLWE) and Module-SIS (MSIS) [PR06, LPR10, LS15] problems to prove the security of our constructions. Both problems are defined over a ring  $\mathcal{R}_q$  for a positive modulus  $q \in \mathbb{Z}^+$ . For the Module-SIS problem we use the variant with respect to the infinity norm.

**Definition 2.3** (MSIS<sub>n,m,\beta\_{SIS}</sub>). The goal in the Module-SIS problem with parameters n, m > 0 and  $\beta_{SIS} > q$  is to find, for a given matrix  $\mathbf{A} \stackrel{\$}{\leftarrow} \mathcal{R}_q^{n \times m}$ ,  $\vec{x} \in \mathcal{R}_q^m$  such that  $\mathbf{A}\vec{x} = \vec{\mathbf{0}}$  over  $\mathcal{R}_q$  and  $0 < ||\vec{x}||_{\infty} \le \beta_{SIS}$ . We say that a PPT adversary  $\mathcal{A}$  has advantage  $\epsilon$  in solving MSIS<sub>n,m,\beta\_{SIS}</sub> if

$$\Pr\left[0 < \|\vec{\boldsymbol{x}}\|_{\infty} \leq \beta_{\mathrm{SIS}} \, \wedge \, \boldsymbol{A}\vec{\boldsymbol{x}} = \vec{\boldsymbol{0}} \, \, \textit{over} \, \mathcal{R}_q \, \middle| \, \boldsymbol{A} \overset{\$}{\leftarrow} \mathcal{R}_q^{n \times m}; \, \vec{\boldsymbol{x}} \leftarrow \mathcal{A}(\boldsymbol{A}) \right] \geq \epsilon.$$

**Definition 2.4** (MLWE<sub>n,m,\chi\)</sub>. In the Module-LWE problem with parameters n, m > 0 and an error distribution  $\chi$  over  $\mathcal{R}$ , the PPT adversary  $\mathcal{A}$  is asked to distinguish  $(\mathbf{A}, \mathbf{t}) \stackrel{\$}{\leftarrow} \mathcal{R}_q^{m \times n} \times \mathcal{R}_q^m$  from  $(\mathbf{A}, \mathbf{A} \vec{s} + \vec{e})$  for  $\mathbf{A} \stackrel{\$}{\leftarrow} \mathcal{R}_q^{m \times n}$ , a secret vector  $\vec{s} \stackrel{\$}{\leftarrow} \chi^n$  and error vector  $\vec{e} \stackrel{\$}{\leftarrow} \chi^m$ . We say that  $\mathcal{A}$  has advantage  $\epsilon$  in solving MLWE<sub>n,m,\chi\</sub> if

$$\left| \Pr \left[ b = 1 \, \middle| \, \boldsymbol{A} \stackrel{\$}{\leftarrow} \mathcal{R}_{q}^{m \times n}; \, \vec{\boldsymbol{s}} \stackrel{\$}{\leftarrow} \chi^{n}; \, \vec{\boldsymbol{e}} \stackrel{\$}{\leftarrow} \chi^{m}; \, b \leftarrow \mathcal{A}(\boldsymbol{A}, \boldsymbol{A}\vec{\boldsymbol{s}} + \vec{\boldsymbol{e}}) \right] \right.$$

$$\left. - \Pr \left[ b = 1 \, \middle| \, \boldsymbol{A} \stackrel{\$}{\leftarrow} \mathcal{R}_{q}^{m \times n}; \, \vec{\boldsymbol{t}} \stackrel{\$}{\leftarrow} \mathcal{R}_{q}^{m}; \, b \leftarrow \mathcal{A}(\boldsymbol{A}, \vec{\boldsymbol{t}}) \, \middle| \right] \ge \epsilon.$$

$$(4)$$

For our practical security estimations of these two problems against known attacks, the parameter m in both of the problems does not play a crucial role. Therefore, we sometimes simply omit m and use the notations  $\mathsf{MSIS}_{n,B}$  and  $\mathsf{MLWE}_{n,\chi}$ . The parameters  $\kappa$  and  $\lambda$  denote the *module ranks* for  $\mathsf{MSIS}$  and  $\mathsf{MLWE}$ , respectively.

## 2.6 Error Distribution, Discrete Gaussians and Rejection Sampling

For sampling randomness in the commitment scheme that we use, and to define the particular variant of the Module-LWE problem that we use, we need to specify the error distribution  $\chi^d$  on  $\mathcal{R}$ . In general any of the standard choices in the literature is fine. So, for example,  $\chi$  can be a narrow discrete Gaussian distribution or the uniform distribution on a small interval. In the numerical examples in Section 4.2 we assume that  $\chi$  is the computationally simple centered binomial distribution on  $\{-1,0,1\}$  where  $\pm 1$  both have probability 5/16 and 0 has probability 6/16. This distribution is chosen (rather than the more "natural" uniform one) because it is easy to sample given a random bitstring by computing  $a_1 + a_2 - b_1 - b_2 \mod 3$  with uniformly random bits  $a_i, b_i$ .

Rejection Sampling. In our zero-knowledge proof, the prover will want to output a vector  $\vec{z}$  whose distribution should be independent of a secret randomness vector  $\vec{r}$ , so that  $\vec{z}$  cannot be used to gain any information on the prover's secret. During the protocol, the prover computes  $\vec{z} = \vec{y} + c\vec{r}$  where  $\vec{r}$  is the randomness used to commit to the prover's secret,  $c \stackrel{\$}{\leftarrow} C$  is a challenge polynomial, and  $\vec{y}$  is a "masking" vector. To remove the dependency of  $\vec{z}$  on  $\vec{r}$ , we use the rejection sampling technique by Lyubashevsky [Lyu08, Lyu09, Lyu12]. In the two variants of this technique the masking vector is either sampled uniformly from some bounded region or using a discrete Gaussian distribution.

Although the Gaussian variant allows to sample  $\vec{y}$  from narrower distributions for acceptable rejection rates, we use the uniform variant in this paper. The reasons for this are that, firstly, uniform sampling is much faster in implementations and much easier to protect against side-channel attacks, and, secondly, uniform sampling allows to be combined with the compression techniques from [BG14, DKL<sup>+</sup>18], which make up for the disadvantage concerning the width of the distribution.

The gist of uniform rejection sampling is the following. Let T be a bound on the infinity norm of  $c\vec{r}$  and let the coefficients of the polynomials of  $\vec{y}$  be sampled from the interval  $[-\delta_1, \delta_1[$ . Then, the conditioned distribution of the coefficients of  $\vec{z}$  given that  $\|\vec{z}\|_{\infty} < \delta_1 - T$  is the uniform distribution on  $] - (\delta_1 - T), \delta_1 - T[$ , independent of  $c\vec{r}$ .

# 2.7 Commitment Scheme

In our protocol, we use a variant of the commitment scheme from [BDL<sup>+</sup>18], which allows to commit to a vector of messages in  $\mathcal{R}_q$ . Suppose that we want to

commit to a message vector  $\vec{m} = (m_1, \ldots, m_l)^T \in \mathcal{R}_q^l$  and that module ranks of  $\kappa$  and  $\lambda$  are required for MSIS and MLWE security, respectively. Then, in the key generation, a uniformly random matrix  $B_0 \stackrel{\$}{\leftarrow} \mathcal{R}_q^{\kappa \times (\lambda + \kappa + l)}$  and vectors  $\vec{b}_1, \ldots, \vec{b}_l \stackrel{\$}{\leftarrow} \mathcal{R}_q^{\lambda + \kappa + l}$  are generated and output as public parameters. In practice, one may choose to generate  $B_0, \vec{b}_1, \ldots, \vec{b}_l$  in a more structured way as in [BDL<sup>+</sup>18] since it saves some computation. However, for readability, we write the commitment matrices in the "Knapsack" form as above. In our case, the hiding property of the commitment scheme is established via the duality between the Knapsack and MLWE problems. We refer to [EZS<sup>+</sup>19, Appendix C] for a more detailed discussion.

To commit to the message  $\vec{m}$ , we first sample  $\vec{r} \stackrel{\$}{\leftarrow} \chi^{(\lambda+\kappa+l)d}$ . Now, there are two parts of the commitment scheme; the binding part and the message encoding part. Particularly, we compute

$$egin{aligned} ec{m{t}}_0 &= m{B}_0 ec{m{r}}, \ m{t}_i &= \langle ec{m{b}}_i, ec{m{r}} 
angle + m{m}_i & ext{for } i = 1, \dots, l, \end{aligned}$$

where  $\vec{t}_0$  forms the binding part and each  $t_i$  encodes a message polynomial  $m_i$ . The commitment scheme is computationally hiding under the Module-LWE assumption and computationally binding under the Module-SIS assumption; see [BDL<sup>+</sup>18].

The utility of the commitment scheme for zero-knowledge proof systems stems from the fact that one can compute module homomorphisms on committed messages. For example, let  $a_1$  and  $a_2$  be from  $\mathcal{R}_q$ . Then

$$m{a}_1m{t}_1 + m{a}_2m{t}_2 = \langle m{a}_1ec{m{b}}_1 + m{a}_2ec{m{b}}_2, ec{m{r}}
angle + m{a}_1m{m}_1 + m{a}_2m{m}_2$$

is a commitment to the message  $a_1m_1 + a_2m_2$  with matrix  $a_1\vec{b}_1 + a_2\vec{b}_2$ . This module homomorphic property together with a proof that a commitment is a commitment to the zero polynomial allows to prove linear relations among committed messages over  $\mathcal{R}_q$ .

#### 2.8 Opening and Product Proof

We use the opening proof from [ALS20, Figure 2] that we sketch now. Suppose that the prover knows an opening to the commitment

$$egin{aligned} ec{m{t}}_0 &= m{B}_0 ec{m{r}}, \ m{t}_1 &= \langle ec{m{b}}_1, ec{m{r}} 
angle + m{m}_1. \end{aligned}$$

As in previous opening proofs the prover gives an approximate proof for the first equation. To this end, the prover and verifier engage in k parallel executions of a sigma protocol with challenges  $\sigma^i(c)$ ,  $i=0,\ldots,k-1$ , that are the rotations of a global challenge  $c \stackrel{\$}{\leftarrow} C$ . Concretely, in the first flow, the prover samples k short masking vectors  $\vec{y}_i$  from the discrete Gaussian distribution  $D_{\mathfrak{s}}^{(\lambda+\kappa+1)d}$ 

and sends commitments  $\vec{w}_i = B_0 \vec{y}_i$  over to the verifier. The verifier replies with the challenge c. Then the prover applies rejection sampling, and, if this does not reject, sends  $\vec{z}_i = \vec{y}_i + \sigma^i(c)\vec{r}$ . The verifier checks that the  $\vec{z}_i$  are short and the equations  $B_0 \vec{z}_i = \vec{w}_i + \sigma^i(c) \vec{t}_0$ .

Now, unlike in previous protocols, the algebraic setup is such that it is not possible to extract a pair of accepting transcript with invertible challenge difference  $\bar{c} = c - c'$ . Instead, extraction works by piecing together l/k accepting transcripts where for each ideal  $(X^{kd/l} - \zeta^{kj})$ , there is a transcript pair with challenge difference  $\bar{c}_j$  mod  $(X^{kd/l} - \zeta^{kj}) \neq 0$ . For this to work out it is required that the maximum probability p over  $\mathbb{Z}_q$  of the coefficients of c mod  $(X^{kd/l} - \zeta^k)$ , as given by Lemma 2.2, is such that  $p^{kd/l}$  is negligible. For example, if d = 128,  $q \approx 2^{32}$  fully splits so that l = d, and k = 4, then  $p^{kd/l} = p^4 \approx 2^{-128}$ .

Next, the analysis of the protocol given in [ALS20, Theorem 4.4] shows that it is possible to extract a weak opening from a prover with non-negligible high success probability, as given in the following definition.

**Definition 2.5.** A weak opening for the commitment  $\vec{t} = \vec{t}_0 \parallel t_1$  consists of l polynomials  $\sigma^i(\bar{c}_j) \in \mathcal{R}_q$ , a randomness vector  $\vec{r}^*$  over  $\mathcal{R}_q$  and a message  $m_1^* \in \mathcal{R}_q$  such that

$$\begin{aligned} & \left\| \sigma^{i}(\bar{\boldsymbol{c}}_{j}) \right\|_{1} \leq 2d \ and \ \sigma^{i}(\bar{\boldsymbol{c}}_{j}) \ \text{mod} \ \sigma^{i}(X^{d/l} - \zeta^{j}) \neq 0 \ for \ all \ (i, j) \in I, \\ & \left\| \sigma^{i}(\bar{\boldsymbol{c}}_{j})\vec{\boldsymbol{r}}^{*} \right\|_{2} \leq 2\beta \ for \ all \ (i, j) \in I, \\ & \boldsymbol{B}_{0}\vec{\boldsymbol{r}}^{*} = \vec{\boldsymbol{t}}_{0}, \\ & \langle \vec{\boldsymbol{b}}_{1}, \vec{\boldsymbol{r}}^{*} \rangle + \boldsymbol{m}_{1}^{*} = \boldsymbol{t}_{1}. \end{aligned}$$

The commitment scheme is binding with respect to weak openings, c.f. [ALS20, Lemma 4.3]. Furthermore, in the extraction it is also possible to obtain vectors  $\vec{y}_i^*$  such that every accepting transcript satisfies the following

$$\vec{z}_i = \vec{y}^* + \sigma^i(c)\vec{r}^*,$$

when it contains the same prover commitments  $\vec{w}_i$  that were used in the extraction

We also apply the product proof from [ALS20, Figure 4], adapted to the case of a cubic relation, to prove that our secret vector has ternary coefficients. In addition to the opening proof, the product proof only requires two additional commitments to garbage terms.

# 3 Proving Unstructured Linear Relations over $\mathbb{Z}_q^n$

Our goal for this section is to construct an efficient protocol for proving unstructured linear relations among committed  $\mathbb{Z}_q$ -elements. By this we mean that we want to be able to commit to a vector  $\vec{s} \in \mathbb{Z}_q^n$  and prove that it fulfills an arbitrary linear equation  $A\vec{s} = \vec{u}$  for a public matrix  $A \in \mathbb{Z}_q^{m \times n}$  and vector

 $\vec{u} \in \mathbb{Z}_q^m$ . We borrow LWE terminology and call the linear equation "unstructured" to highlight the fact that A can be an arbitrary matrix over  $\mathbb{Z}_q$  that does not necessarily express linear relations over some ring of higher rank.

Proofs of linear relations are useful for applications in lattice cryptography only if it is possible to amend them by a proof of shortness. So, we will also want to be able to prove that the vector  $\vec{s}$  is short. As opposed to the so-called approximate proofs that are ubiquitous in lattice cryptography and where the prover only proves knowledge of a vector that is much longer than the one it actually knows, we are interested in exact proofs of shortness. These have the advantage that the parameters of underlying cryptographic schemes do not have to account for the longer vectors that can be extracted from a prover, i.e. the schemes do not need to be secure with respect to the longer vectors. This results in more efficient schemes. For example, one interesting goal of this line of research is to construct a proof of plaintext knowledge or a verifiable encryption scheme for a standard unmodified lattice-based public-key encryption scheme. In particular, for one of the schemes submitted to the NIST PQC standardization effort.

The most efficient lattice-based exact proofs of shortness work by encoding the vector  $\vec{s}$  in the NTT representations  $\mathsf{NTT}(\check{s}_i)$  of possibly several polynomials  $\check{s}_i \in \mathcal{R}_q$ . In the first step, we restrict to the case where q splits completely in  $\mathcal{R}$ . Then  $\mathsf{NTT}(\check{s}_i)$  is a vector in  $\mathbb{Z}_q^d$ .

Now, for simplicity, assume that n is divisible by d. Suppose the prover  $\mathcal{P}$  knows an opening to a commitment  $\vec{t} = \vec{t}_0 \parallel t_1 \parallel \cdots \parallel t_{n/d}$  to n/d secret polynomials  $\check{s}_1, \ldots, \check{s}_{n/d} \in \mathcal{R}_q$ . More precisely,

$$ec{m{t}}_0 = m{B}_0 ec{m{r}},$$

$$m{t}_i = \langle ec{m{b}}_i, ec{m{r}} \rangle + \check{m{s}}_i ext{ for } i \in \{1, \dots, n/d\}.$$

Then, the goal of  $\mathcal{P}$  is to prove that the vector

$$ec{s} = \mathsf{NTT}(\check{s}_1) \parallel \cdots \parallel \mathsf{NTT}(\check{s}_{n/d}) \in \mathbb{Z}_q^n$$

satisfies the linear equation  $A\vec{s} = \vec{u}$  over  $\mathbb{Z}_q$  where  $A \in \mathbb{Z}_q^{m \times n}$  and  $\vec{u} \in \mathbb{Z}_q^m$  are public.

Firstly, we describe the main ideas and present a protocol which achieves soundness error 1/q. Then, in Section 3.2 and [ENS20, Appendix A] we present two methods to efficiently decrease the soundness error to negligible quantities. The latter one, however, is only interesting when the secret vector  $\vec{s}$  is strictly shorter than d. In that case, we make use of non-fully splitting rings  $\mathcal{R}_q$ .

Although we present all of our protocols so that only non-aborting protocol transcripts are simulatable, there is a standard generic method to simulate aborts of an interactive protocol as given in [BCK+14], which is also used, e.g., in [ESS+19]. In particular, for all but the last move of the prover, the prover sends aCom(M) instead of the transmitted text M for an auxiliary commitment aCom. In the last move, all of these committed texts are revealed unless aborted. In the case of abort, the prover just sends an error message  $\bot$ . The abort can easily

be simulated in this case by relying on the hiding property of aCom. We refer to [BCK<sup>+</sup>14, ESS<sup>+</sup>19] for more details. Also, note that the simulation of aborts is not important for most of the practical applications as the protocol is made non-interactive and the simulation of aborts is not needed in that case.

#### 3.1 Basic Protocol

Let us assume that n=d and denote  $\check{s}:=\check{s}_1$ . We show how to deal with the case n>d in Section 3.3. The first protocol relies on the following simple observation. Suppose that  $A\vec{s}=\vec{u}$ . This means that for all  $\vec{\gamma}\in\mathbb{Z}_q^m$ , we have  $\langle A\vec{s}-\vec{u},\vec{\gamma}\rangle=0$ . On the contrary, if  $A\vec{s}\neq\vec{u}$ , then for a uniformly random  $\vec{\gamma}\in\mathbb{Z}_q^m$ ,  $\langle A\vec{s}-\vec{u},\vec{\gamma}\rangle=0$  only with probability 1/q. Hence,  $\vec{\gamma}$  will become a challenge generated from the verifier. Using Lemma 2.1, we rewrite the inner product,

$$\begin{split} \langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle &= \langle A\vec{s}, \vec{\gamma} \rangle - \langle \vec{u}, \vec{\gamma} \rangle = \langle \vec{s}, A^T \vec{\gamma} \rangle - \langle \vec{u}, \vec{\gamma} \rangle \\ &= \sum_{j \in \mathbb{Z}_{2d}^{\times}} \boldsymbol{s}(\zeta^j) \left( \mathsf{NTT}^{-1}(A^T \vec{\gamma}) \right) (\zeta^j) - \langle \vec{u}, \vec{\gamma} \rangle = \frac{1}{d} \sum_{j \in \mathbb{Z}_{2d}^{\times}} \boldsymbol{f}(\zeta^j) = f_0, \end{split}$$

where  $\mathbf{f} \in \mathcal{R}_q$  is the polynomial defined by  $\mathbf{f} := \mathsf{NTT}^{-1}(dA^T\vec{\gamma})\check{\mathbf{s}} - \langle \vec{u}, \vec{\gamma} \rangle$  and  $f_0 \in \mathbb{Z}_q$  is the constant coefficient of  $\mathbf{f}$ . So, by utilizing the polynomial product in  $\mathcal{R}_q$ , it is possible to compute a scalar product over  $\mathbb{Z}_q$  with a vector encoded in the NTT representation of the polynomial. We observe that the verifier can compute a commitment to  $\mathbf{f}$ . Indeed, note that

$$\mathsf{NTT}^{-1}(dA^T\vec{\gamma})\boldsymbol{t}_1 - \langle \vec{u},\vec{\gamma}\rangle = \langle \mathsf{NTT}^{-1}(dA^T\vec{\gamma})\vec{\boldsymbol{b_1}},\vec{r}\rangle + \boldsymbol{f}.$$

Hence,  $\mathcal{V}$  can compute the commitment

$$\tau = \mathsf{NTT}^{-1}(dA^T\vec{\gamma})t_1 - \langle \vec{u}, \vec{\gamma} \rangle. \tag{5}$$

Now,  $\mathcal{P}$  needs to prove that f has a zero constant coefficient. The idea is to first send a commitment  $\mathbf{t}_2$  to a random polynomial  $\mathbf{g}$  with a zero constant coefficient before  $\vec{\gamma}$  is generated. Intuitively,  $\mathbf{g}$  is introduced to mask  $\mathbf{f}$ . After getting  $\vec{\gamma}$ ,  $\mathcal{P}$  sends  $\mathbf{h} = \mathbf{f} + \mathbf{g}$  and the verifier can check that  $h_0 = 0$ . Note that by knowing  $\tau$ ,  $t_2$  and  $t_2$ , the verifier can compute a commitment  $t_2$  and  $t_2$  to the zero polynomial  $t_2$ . Hence, in the final stage,  $t_2$  needs to prove that this polynomial is indeed a commitment to  $t_2$  in the usual way.

The full protocol is presented as follows. First, the prover  $\mathcal{P}$  generates a random polynomial  $\mathbf{g} \in \mathcal{R}_q$  with zero constant coefficient and computes a commitment to  $\mathbf{g}$  defined as  $\mathbf{t}_2 = \langle \vec{\mathbf{b}}_2, \vec{r} \rangle + \mathbf{g}$ . The prover also starts the opening proof with soundness error 1/q for the commitments and samples a vector of small polynomials  $\vec{\mathbf{y}}$  and computes the commitment  $\vec{\mathbf{w}} = \mathbf{B}_0 \vec{\mathbf{y}}$ . Then,  $\mathcal{P}$  sends  $\mathbf{t}_2$  and  $\vec{\mathbf{w}}$  to the verifier. Next,  $\mathcal{V}$  generates and sends a uniformly random vector  $\vec{\gamma} \in \mathbb{Z}_q^m$ .  $\mathcal{P}$  can then compute the polynomial  $\mathbf{f}$  defined above and  $\mathbf{h} = \mathbf{f} + \mathbf{g}$ .

Furthermore, it sets  $\mathbf{v} = \langle \mathsf{NTT}^{-1}(dA^T\vec{\gamma})\vec{b_1} + \vec{b_2}, \vec{y} \rangle$  and sends  $\mathbf{h}, \mathbf{v}$  to  $\mathcal{V}$ . Then, the verifier generates a challenge  $\mathbf{c} \stackrel{\$}{\leftarrow} C$  and sends it to the prover. Eventually,  $\mathcal{P}$  sends a response  $\vec{z} = \vec{y} + c\vec{r}$ .

The verifier  $\mathcal{V}$  first checks that  $\vec{z}$  consists of small polynomials and that h has constant coefficient equal to 0. Also,  $\mathcal{V}$  checks that  $B_0\vec{z} = \vec{w} + c\vec{t}_0$  and

$$\langle \mathsf{NTT}^{-1}(dA^T \vec{\gamma}) \vec{m{b_1}} + \vec{m{b}_2}, \vec{m{z}} 
angle = m{v} + m{c} \left( m{ au} + m{t}_2 - m{h} 
ight)$$

where  $\tau$  is computed as in Equation (5).

One can observe that if  $A\vec{s} \neq \vec{u}$  then the constant coefficient of f becomes a uniformly random element of  $\mathbb{Z}_q$ , outside the control of the prover. Thus, also the constant coefficient of h = f + g will be uniformly random because the constant coefficient of g is independent of the constant coefficient of f. In particular, it will be non-zero with probability 1-1/q and this can be detected by the verifier. Therefore, the probability that a malicious prover manages to cheat is essentially 1/q.

## 3.2 Boosting Soundness by Mapping Down

More abstractly, in the above protocol we checked  $\langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle = 0$  by investigating whether  $\mathsf{L}(\vec{\gamma})$  has a zero constant coefficient where  $\mathsf{L}: \mathbb{Z}_q^m \to \mathcal{R}_q$  is defined as

$$L(\vec{\gamma}) := \mathsf{NTT}^{-1}(dA^T \vec{\gamma}) \check{s} - \langle \vec{u}, \vec{\gamma} \rangle. \tag{6}$$

As we observed earlier, the constant coefficient of  $L(\vec{\gamma})$  is indeed  $\langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle$ .

Now, suppose we can define k functions  $\mathsf{L}_0,\ldots,\mathsf{L}_{k-1}$  with the following property. For any  $0 \le \mu < k$  and  $\vec{\gamma}_{\mu} \in \mathbb{Z}_q^m$ ,  $\boldsymbol{p} = L_{\mu}(\vec{\gamma}_{\mu}) \in \mathcal{R}_q$  is a polynomial such that  $p_0 = \ldots = p_{\mu-1} = p_{\mu+1} = \ldots = p_{k-1} = 0$  and  $p_{\mu} = \langle A\vec{s} - \vec{u}, \vec{\gamma}_{\mu} \rangle$ . This would mean that for  $0 \le \mu < k$ , the  $\mu$ -th coefficient related to  $X^{\mu}$  of the polynomial

$$f = L_0(\vec{\gamma}_0) + L_1(\vec{\gamma}_1) + \ldots + L_{k-1}(\vec{\gamma}_{k-1})$$

is equal to  $\langle A\vec{s} - \vec{u}, \vec{\gamma_{\mu}} \rangle$ . In particular, if  $A\vec{s} = \vec{u}$ , then  $f_0 = f_1 = \ldots = f_{k-1} = 0$ . Thus, in order to decrease the soundness error, we can let the verifier  $\mathcal{V}$  send k independently uniformly random vectors  $\vec{\gamma}_0, \ldots, \vec{\gamma}_{k-1}$  and then  $\mathcal{P}$  proves that  $f \in \mathcal{R}_q$  has the first k coefficients equal to zero. Note that we still need to find a way for  $\mathcal{V}$  to compute a commitment to f from  $\vec{t}_1$  and  $\vec{\gamma}_0, \ldots, \vec{\gamma}_{k-1}$ .

Constructing  $L_{\mu}$ . Let  $S_q$  be the  $\mathbb{Z}_q$ -submodule of  $\mathcal{R}_q$  generated by  $X^k$ , i.e.

$$\mathcal{S}_q = \{p_0 + p_1 X^k + \dots + p_{d/k-1} X^{d-k} \in \mathcal{R}_q\} \subset \mathcal{R}_q.$$

We have  $S_q \cong \mathbb{Z}_q[X]/(X^{d/k}+1)$ . From Galois theory, there is a corresponding subgroup H of  $\operatorname{Aut}(\mathcal{R}_q)$  of order k such that  $\sigma(\boldsymbol{p})=\boldsymbol{p}$  for all  $\sigma\in H$  if and only if  $\boldsymbol{p}\in S_q$ . It is easy to see that this group is generated by  $\sigma=\sigma_{2d/k+1}\in\operatorname{Aut}(\mathcal{R}_q)$ , which is the same automorphism that we use in the automorphism opening proof. In fact, this follows from the fact that  $\operatorname{ord}(\sigma)=k$  and  $\sigma(X^k)=X^{k(2d/k+1)}=X^k$ .

We have the trace map  $\operatorname{Tr}: \mathcal{R}_q \to \mathcal{S}_q$  given by

$$\mathsf{Tr}(oldsymbol{p}) = \sum_{
u=0}^{k-1} \sigma^{
u}(oldsymbol{p}).$$

Notice that the constant coefficient of Tr(p) is equal to  $kp_0$ . Now define  $L_{\mu}$  by

$$\mathsf{L}_{\mu}(\vec{\gamma}) = \frac{1}{k} X^{\mu} \mathsf{Tr}(\mathsf{L}(\vec{\gamma})) = \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1}(dA^T \vec{\gamma}) \check{s} - \langle \vec{u}, \vec{\gamma} \rangle \right).$$

If  $\boldsymbol{p} = \mathsf{L}_{\mu}(\vec{\gamma})$ , then  $\boldsymbol{p}$  is of the form

$$\mathbf{p} = p_{\mu}X^{\mu} + p_{k+\mu}X^{k+\mu} + \dots + p_{d-k+\mu}X^{d-k+\mu}$$

and thus has the property that the first k coefficients except the  $\mu$ -th coefficient are zero. Moreover, it is clear from above that  $p_{\mu} = \langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle$ .

Finally, given the commitment  $t_1$  to s, the verifier can compute a commitment to  $\mathbf{f} = \mathsf{L}_0(\vec{\gamma}_0) + \cdots + \mathsf{L}_{k-1}(\vec{\gamma}_{k-1})$  via

$$\boldsymbol{\tau} = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1} (dA^{T} \vec{\gamma}_{\mu}) \boldsymbol{t}_{1} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right)$$

$$= \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (dA^{T} \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_{1}, \vec{\boldsymbol{r}} \rangle \right) + \boldsymbol{f}. \tag{7}$$

**The Protocol.** We present the full protocol in Figure 1 with the verification algorithm given in Figure 2.

It is natural to separate the commitment  $(\vec{t}_0, t_1)$  to the secret polynomial  $\check{s}$ from our protocol for proving the linear relation. Then,  $(\vec{t}_0, t_1)$  is given as input to the protocol, which also proves knowledge of an opening to the external commitment. Now, for efficiency reasons, one wants to avoid sending a completely fresh commitment to the masking polynomial g and instead reuse the top part  $\vec{t}_0$  of the commitment to  $\check{s}$ , but this creates a problem with the standard notion of a zero-knowledge proof. Namely, with this approach it is required that the randomness vector  $\vec{r}$ , which is a part of the witness, is really random so that the commitment to g is hiding, but the zero-knowledge definition demands simulatability for any (fixed) witness. Hence, we don't take this approach and also send the commitment to  $\check{s}$  as part of our protocol. Then, our protocol only shows knowledge of a solution  $\vec{s}$  to the linear equation  $A\vec{s} = \vec{u}$ . This in itself is not a solution to a hard problem but our protocol is still useful because it can be combined with a shortness proof that simultaneously shows that  $\vec{s}$  is short (see Section 4). In isolation our protocol is best viewed as a so-called commitand-proof protocol [CLOS02], which is interesting even without involving a hard problem because of the commitment that can later be used outside of the proThe Prover  $\mathcal{P}$  starts by generating a uniformly random polynomial g satisfying  $g_0 = \ldots = g_{k-1} = 0$  and then computes the commitment

$$egin{aligned} ec{m{t}}_0 &= m{B}_0 ec{m{r}} \ m{t}_1 &= \langle ec{m{b}}_1, ec{m{r}} 
angle + ec{m{s}} \ m{t}_2 &= \langle ec{m{b}}_2, ec{m{r}} 
angle + m{g}. \end{aligned}$$

Now the prover needs to start an opening proof with soundness  $1/q^k$ . Also, it is going to prove a relation which involves the k automorphisms  $\sigma^i$ . Therefore, it uses the automorphism opening proof from [ALS20] and samples vectors  $\vec{y}_0, \ldots, \vec{y}_{k-1}$  of short polynomials that are going to be used to mask  $\vec{r}$  k times with challenges of the form  $\sigma^i(c)$ . Also,  $\mathcal{P}$  computes  $\vec{w}_i = B_0 \vec{y}_i$ . The prover sends  $\vec{t}_0, t_1, t_2$  and  $\vec{w}_i$  to  $\mathcal{V}$ .

Next, the verifier selects uniformly random vectors  $\vec{\gamma}_0, \dots, \vec{\gamma}_{k-1} \in \mathbb{Z}_q^m$  and sends them to  $\mathcal{P}$ . Then, the prover computes

$$\boldsymbol{f} = \sum_{\mu=0}^{k-1} \mathsf{L}_{\mu}(\vec{\gamma}_{\mu}) = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) \check{\boldsymbol{s}} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right).$$

By construction,  $f_0 = \ldots = f_{k-1} = 0$ . Note that  $\mathcal{V}$  can compute a commitment  $\boldsymbol{\tau}$  to  $\boldsymbol{f}$  as explained above. Now the prover sets  $\boldsymbol{h} = \boldsymbol{f} + \boldsymbol{g}$  and computes for  $i = 0, \ldots, k-1$ ,

$$\boldsymbol{v}_i = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1}(dA^T \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_1, \vec{\boldsymbol{y}}_{i-\nu \bmod k} \rangle \right) + \langle \vec{\boldsymbol{b}}_2, \vec{\boldsymbol{y}}_i \rangle.$$

It sends  $\boldsymbol{h}$  and  $\boldsymbol{v}_0, \ldots, \boldsymbol{v}_{k-1}$ . The verifier sends a random challenge polynomial  $\boldsymbol{c} \stackrel{\$}{\leftarrow} C$ . Eventually,  $\mathcal{P}$  computes  $\vec{\boldsymbol{z}}_i = \vec{\boldsymbol{y}}_i + \sigma^i(\boldsymbol{c})\vec{\boldsymbol{r}}$  for  $i = 0, \ldots, k-1$  and sends  $\vec{\boldsymbol{z}}_0, \ldots, \vec{\boldsymbol{z}}_{k-1}$ .

The Verifier  $\mathcal{V}$  first checks that for all  $i = 0, \dots, k-1, \vec{z_i}$  is short, and

$$\boldsymbol{B}_0 \vec{\boldsymbol{z}}_i = \vec{\boldsymbol{w}}_i + \sigma^i(\boldsymbol{c}) \vec{\boldsymbol{t}}_0.$$

Then,  $\mathcal{V}$  checks that  $h_0, \ldots, h_{k-1}$  are all equal to zero and computes  $\tau$  as in (7). Finally, the verifier checks whether for all  $i = 0, \ldots, k-1$ ,

$$\begin{split} &\sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_1, \vec{\boldsymbol{z}}_{i-\nu \bmod k} \rangle \right) + \langle \vec{\boldsymbol{b}}_2, \vec{\boldsymbol{z}}_i \rangle \\ &= \boldsymbol{v}_i + \sigma^i(\boldsymbol{c}) (\tau + \boldsymbol{t}_2 - \boldsymbol{h}) \end{split}$$

to test whether  $\tau + t_2 - h$  really is a commitment to zero.

#### Security Analysis.

```
Prover P
                                                                                                                                                                                                                                                                                                                                       Verifier V
   Inputs:
  \check{\boldsymbol{s}} \in \mathcal{R}_q, \vec{s} = \mathsf{NTT}(\check{\boldsymbol{s}})
                                                                                                                                                                                                                                                                                                                                       A, \vec{u}
   A \in \mathbb{Z}_q^{m \times n}
                                                                                                                                                                                                                                                                                                                                       B_0, \vec{b}_1, \vec{b}_2
   \vec{u} = A\vec{s}
   \boldsymbol{B}_0 \in \mathcal{R}_q^{\kappa \times (\lambda + \kappa + 2)}, \vec{\boldsymbol{b}}_1, \vec{\boldsymbol{b}}_2 \in \mathcal{R}_q^{\lambda + \kappa + 2}
   \boldsymbol{g} \stackrel{\$}{\leftarrow} \{ \boldsymbol{g} \in \mathcal{R}_q \mid g_0 = \dots = g_{k-1} = 0 \}
   \vec{r} \stackrel{\$}{\leftarrow} \chi^{(\lambda+\kappa+2)d}
   \vec{t}_0 = B_0 \vec{r}
   oldsymbol{t}_1 = \langle ec{oldsymbol{b}}_1, ec{oldsymbol{r}} 
angle + ec{oldsymbol{s}}
  oldsymbol{t}_2 = \langle ec{oldsymbol{b}}_2, ec{oldsymbol{r}} 
angle + oldsymbol{g}
   \vec{\boldsymbol{t}} = \vec{\boldsymbol{t}}_0 \parallel \boldsymbol{t}_1 \parallel \boldsymbol{t}_2
  For i = 0, ..., k - 1:
           \vec{y}_i \stackrel{\$}{\leftarrow} [-\delta_1, \delta_1]^{(\lambda + \kappa + 2)d}
           \vec{w}_i = B_0 \vec{y}_i
                                                                                                                                                                                                                                                                                         ec{m{t}}, ec{m{w}}_i
                                                                                                                                                                                                                                                                                                                                       \vec{\gamma}_0, \dots, \vec{\gamma}_{k-1} \stackrel{\$}{\leftarrow} \mathbb{Z}_a^m
\begin{split} \boldsymbol{h} &= \boldsymbol{g} + \sum_{\mu=0}^{k-1} \frac{1}{k} \boldsymbol{X}^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1} (d\boldsymbol{A}^T \vec{\gamma}_{\mu}) \check{\boldsymbol{s}} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right) \end{split}
        \begin{split} & \text{For } i = 0, \dots, k-1: \\ & \boldsymbol{v}_i = \sum_{\mu=0}^{k-1} \frac{1}{k} \boldsymbol{X}^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (d\boldsymbol{A}^T \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_1, \vec{\boldsymbol{y}}_{i-\nu \bmod k} \rangle \right) + \langle \vec{\boldsymbol{b}}_2, \vec{\boldsymbol{y}}_i \rangle \end{split}
   For i = 0, ..., k - 1:
          \vec{z}_i = \vec{y}_i + \sigma^i(c)\vec{r}
          If \|\vec{z}_i\|_{\infty} \ge \delta_1 - T, abort
                                                                                                                                                                                                                                                                                                                                       \mathsf{Ver}(\vec{t}, \vec{w}_i, \vec{\gamma}_i, h, v_i, c, \vec{z}_i)
```

Fig. 1. Automorphism proof of knowledge of a solution to an unstructured linear equation over  $\mathbb{Z}_q$ . Verification equations are described in Figure 2.

**Theorem 3.1.** The protocol in Figure 1 is complete, computational honest verifier zero-knowledge under the Module-LWE assumption and computational special sound under the Module-SIS assumption. More precisely, let p be the maximum probability over  $\mathbb{Z}_q$  of the coefficients of  $\mathbf{c} \mod X^k - \zeta^k$  as in Lemma 2.2.

Then, for completeness, unless the honest prover  $\mathcal{P}$  aborts due to the rejection sampling, it always convinces the honest verifier  $\mathcal{V}$ .

For zero-knowledge, there exists a simulator S, that, without access to secret information, outputs a simulation of a non-aborting transcript of the protocol between P and V for every statement  $A\vec{s} = \vec{u}$ . Then for every algorithm A that has advantage  $\varepsilon$  in distinguishing the simulated transcript from an actual transcript, there is an algorithm A' with the same running time that has advantage  $\varepsilon$  in distinguishing  $\mathsf{MLWE}_{\lambda,\chi}$ .

```
 \begin{array}{|c|c|c|c|} \hline \text{Ver}(\vec{t},\vec{w}_i,\vec{\gamma}_i, h, v_i, c, \vec{z}_i) \\ \hline \text{01 For } i = 0, \dots, k-1 \\ \hline \text{02} & \|\vec{z}_i\|_{\infty} \stackrel{?}{<} \beta = \delta_1 - T \\ \hline \text{03} & \pmb{B_0} \vec{z}_i \stackrel{?}{=} \vec{w}_i + \sigma^i(c) \vec{t}_0 \\ \hline \text{04} & h_0 \stackrel{?}{=} \dots \stackrel{?}{=} h_{k-1} \stackrel{?}{=} 0 \\ \hline \text{05} & \pmb{\tau} = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) t_1 - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right) \\ \hline \text{06 For } i = 0, \dots, k-1 \\ \hline \text{07} & \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) b_1, \vec{z}_{i-\nu \bmod k} \rangle \right) + \langle \vec{b}_2, \vec{z}_i \rangle \stackrel{?}{=} v_i + \sigma^i(c) (\pmb{\tau} + t_2 - \pmb{h}) \\ \hline \end{array}
```

Fig. 2. Verification equations for Figure 1.

For soundness, there is an extractor  $\mathcal{E}$  with the following properties. When given rewindable black-box access to a deterministic prover  $\mathcal{P}^*$  that sends the commitment  $\vec{t}$  in the first round and convinces  $\mathcal{V}$  with probability  $\varepsilon \geq q^{-k} + p^k$ ,  $\mathcal{E}$  either outputs a weak opening for  $\vec{t}$  with message  $\check{s}^*$  such that  $ANTT(\check{s}^*) = \vec{u}$ , or a  $MSIS_{\kappa,8d\beta}$  solution for  $\mathbf{B}_0$  in expected time at most  $1/\varepsilon + (d/k)(\varepsilon - p^k)^{-1}$  when running  $\mathcal{P}^*$  once is assumed to take unit time.

*Proof. Completeness.* It follows by careful inspection that the verification equations are always true for the messages sent by  $\mathcal{P}$ .

Zero-Knowledge. We can simulate a non-aborting transcript between the honest prover and the honest verifier in the following way. First, in a non-aborting transcript the vectors  $\vec{z}_i$  are independently uniformly random in  $]-(\delta_1-T), \delta_1 T^{(\lambda+\kappa+2)d}$  and also independent from  $c\vec{r}$ . So the simulator can just sample  $\vec{z}_i \stackrel{\$}{\leftarrow} ] - (\delta_1 - T), \delta_1 - T[^{(\lambda + \kappa + 2)d} \text{ and } c \stackrel{\$}{\leftarrow} C.$  The polynomial h is such that  $h_0 = \cdots = h_{k-1} = 0$  in honest transcripts and the other coefficients are uniformly random because of the additive term g. Hence, the simulator samples  $\mathbf{h} \stackrel{\$}{\leftarrow} {\mathbf{h} \in \mathcal{R}_q \mid h_0 = \cdots = h_{k-1} = 0}$ . Then, the challenges  $\vec{\gamma}_{\mu} \in \mathbb{Z}_q^m$  are independently uniformly random and the simulator samples them in this way. Now, we turn to the commitment  $\vec{t}$ . In the honest execution the randomness vector  $\vec{r}$  is statistically independent from the  $\vec{z}_i$  and the other messages already handled, i.e.  $c, h, \vec{\gamma}_{\mu}$ . So, it follows that the additive term  $B_0 \vec{r} \parallel \langle \vec{b}_1, \vec{r} \rangle \parallel \langle \vec{b}_2, \vec{r} \rangle$ is indistinguishable from uniform given  $\vec{z}_i, c, h, \vec{\gamma_\mu}$  if  $\mathsf{MLWE}_\lambda$  is hard. Hence  $\vec{t}$ is indistinguishable from uniform since the committed polynomials  $\check{s}$  and g are also independent from  $\vec{r}$  in the honest execution. Therefore, we let the simulator sample a uniformly random  $\vec{t} \in \mathcal{R}_q^{\kappa+2}$ . Now, in an honest transcript, the remaining messages  $\vec{w}_i$  and  $v_i$  are all uniquely determined from the already handled messages and the verification equations because of completeness. We see that if the simulator computes these messages so that the verification equations become true, then the resulting transcript is indistinguishable from the honest transcript. More precisely, if there exists some distinguisher that is able to distinguish a simulated transcript from an honest transcript, then it must be able to distinguish the MLWE samples in the commitment  $\vec{t}$  from uniform with the same advantage.

Soundness. First, the extractor opens the commitments  $t_1$  and  $t_2$ . From [ALS20, Theorem 4.4], unless  $\mathcal{E}$  finds an  $\mathsf{MSIS}_{\kappa,8d\beta}$  solution, the extractor can compute vectors  $\vec{y}^*$  and  $\vec{r}^*$  such that for every accepting transcript with first messages  $t_2$  and  $\vec{w}_i$ ,

$$\boldsymbol{z}_i = \vec{\boldsymbol{y}}_i^* + \sigma^i(\boldsymbol{c})\vec{\boldsymbol{r}}^*.$$

The expected runtime for this equals the runtime in the theorem statement. Then let  $\check{s}^* \in \mathcal{R}_q$  and  $g^* \in \mathcal{R}_q$  be the extracted messages, which are defined by

$$oldsymbol{t}_1 = \langle ec{oldsymbol{b}}_1, ec{oldsymbol{r}}^* 
angle + ec{oldsymbol{s}}^* ext{ and } oldsymbol{t}_2 = \langle ec{oldsymbol{b}}_2, ec{oldsymbol{r}}^* 
angle + oldsymbol{g}^*.$$

Now substituting these expressions into  $\tau$  gives

$$\boldsymbol{\tau} = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_1, \vec{\boldsymbol{r}}^* \rangle \right) + \boldsymbol{f}^*,$$

where

$$\boldsymbol{f}^* = \sum_{\mu=0}^{k-1} \frac{1}{k} \boldsymbol{X}^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \mathsf{NTT}^{-1} (d\boldsymbol{A}^T \vec{\gamma}_{\mu}) \boldsymbol{\check{s}}^* - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right).$$

From the discussion in this section we know that  $f_{\mu}^* = \langle A\vec{s}^* - \vec{u}, \vec{\gamma}_{\mu} \rangle$  for  $\mu = 0, \dots, k-1, \vec{s}^* = \mathsf{NTT}(\check{s}^*)$ . Next we find from the last verification equations,

$$\left(\sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \langle \mathsf{NTT}^{-1} (dA^T \vec{\gamma}_{\mu}) \vec{\boldsymbol{b}}_{1}, \vec{\boldsymbol{y}}_{i-\nu \bmod k}^{*} \rangle \right) + \langle \vec{\boldsymbol{b}}_{2}, \vec{\boldsymbol{y}}^{*} \rangle - \boldsymbol{v}_{i} \right) 
= \sigma^{i}(\boldsymbol{c}) \left( \boldsymbol{f}^{*} + \boldsymbol{g}^{*} - \boldsymbol{h} \right).$$
(8)

for all  $i=0,\ldots,k-1$ . The coefficients of these linear polynomials in  $\sigma^i(c)$  are independent from c in a random accepting transcript. We bound the success probability  $\varepsilon$  of the prover under the assumption  $A\vec{s}^* \neq \vec{u}$ . In this case the coefficients  $f_{\mu}^*$  for  $\mu=0,\ldots,k-1$  are uniformly random elements in  $\mathbb{Z}_q$  in a random transcript. Hence,  $f_{\mu}^*+g_{\mu}^*$  is uniformly random since  $g^*$  is independent from the  $\vec{\gamma}_{\mu}$ . Also we know that  $h_{\mu}=0$  in every accepting transcript. So, suppose  $f_{\mu}^*+g_{\mu}^*-h_{\mu}^*=f_{\mu}^*+g_{\mu}^*\neq 0$  for some  $\mu$ . Then there exists some  $j\in\mathbb{Z}_{2d}^{\times}$  with  $f^*+g^*-h$  mod  $(X-\zeta^j)\neq 0$ . Therefore, there is only one possible value modulo  $(X^k-\zeta^{jk})$  for the challenge in such a transcript, otherwise Equation 8 cannot be true for all i. Since the maximum probability of every coefficient of  $c \mod (X^k-\zeta^{jk})$  is less than p we see that the success probability is bounded by

$$\begin{split} \varepsilon &= \Pr\left[\text{accepting}\right] < \left(\frac{1}{q}\right)^k + \Pr\left[\text{accepting} \,\middle|\, f_\mu^* + g_\mu^* \neq 0 \text{ for some } \mu\right] \\ &\leq \left(\frac{1}{q}\right)^k + p^k. \end{split}$$

This is in contradiction to the bound in the theorem statement and thus it must hold  $A\vec{s}^* = \vec{u}$ .

#### 3.3 General Case

Previously, we assumed that n = d so that  $\vec{s} = \mathsf{NTT}(\check{s}) = \mathsf{NTT}(\check{s}_1)$ . When n > d, we slightly modify our approach. We have  $\vec{s} = \mathsf{NTT}(\check{s}_1) \parallel \cdots \parallel \mathsf{NTT}(\check{s}_{n/d})$  and now also define polynomials  $\psi_j$  such that

$$A^T \vec{\gamma} = \mathsf{NTT}(\psi_1) \parallel \cdots \parallel \mathsf{NTT}(\psi_{n/d}).$$

Then the inner product  $\langle A\vec{s},\vec{\gamma}\rangle=\langle \vec{s},A^T\vec{\gamma}\rangle$  can be written as a sum of smaller inner products. We find

$$\begin{split} \langle A\vec{s} - \vec{u}, \vec{\gamma} \rangle &= \sum_{j=1}^{n/d} \langle \mathsf{NTT}(\check{\boldsymbol{s}}_j), \mathsf{NTT}(\psi_j) \rangle - \langle \vec{u}, \vec{\gamma} \rangle \\ &= \sum_{j=1}^{n/d} \sum_{i \in \mathbb{Z}_{2d}^{\times}} \check{\boldsymbol{s}}_j(\zeta^i) \psi_j(\zeta^i) - \langle \vec{u}, \vec{\gamma} \rangle = \frac{1}{d} \sum_{i \in \mathbb{Z}_{2d}^{\times}} \left( \sum_{j=1}^{n/d} d\check{\boldsymbol{s}}_j \psi_j - \langle \vec{u}, \vec{\gamma} \rangle \right) (\zeta^i). \end{split}$$

Next, similarly as before, we incorporate more challenges. So, for  $\vec{\gamma}_0, \dots, \vec{\gamma}_{k-1} \in \mathbb{Z}_q^m$  we write

$$A^T \vec{\gamma}_{\mu} = \mathsf{NTT}(\boldsymbol{\psi}_1^{(\mu)}) \| \cdots \| \mathsf{NTT}(\boldsymbol{\psi}_{n/d}^{(\mu)})$$

and then set

$$\boldsymbol{f} = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \sum_{j=1}^{n/d} d\boldsymbol{\psi}_{j}^{(\mu)} \boldsymbol{s}_{j} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right).$$

It holds that for  $\mu = 0, \dots, k-1$ ,  $f_{\mu} = \langle A\vec{s} - \vec{u}, \vec{\gamma}_{\mu} \rangle$ . Now, note that  $\tau$  defined as

$$\tau = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \sum_{j=1}^{n/d} d\boldsymbol{\psi}_{j}^{(\mu)} \boldsymbol{t}_{j} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right) 
= \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \sum_{j=1}^{n/d} \langle d\boldsymbol{\psi}_{j}^{(\mu)} \vec{\boldsymbol{b}}_{j}, \vec{\boldsymbol{r}} \rangle + d\boldsymbol{\psi}_{j}^{(\mu)} \check{\boldsymbol{s}}_{j} - \langle \vec{u}, \vec{\gamma} \rangle \right) 
= \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \left\langle \sum_{j=1}^{n/d} d\boldsymbol{\psi}_{j}^{(\mu)} \vec{\boldsymbol{b}}_{j}, \vec{\boldsymbol{r}} \right\rangle \right) + \boldsymbol{f}$$

is indeed a commitment to f and can be computed by the verifier.

## 4 Main Protocol

In this section we present our main protocol for proving knowledge of a ternary solution  $\vec{s} \in \{-1,0,1\}^n$  to an arbitrary linear equation  $A\vec{s} = \vec{u}$  over  $\mathbb{Z}_q$ . The

protocol is essentially an amalgamation of the linear proof from Section 3 and the product proof from [ALS20]. We use a fully splitting prime q and automorphisms to boost the soundness. So, at a high level the prover commits to n/d polynomials  $\check{s}_i$  whose NTT coefficients are the coefficients of  $\vec{s}$ . That is,

$$ec{s} = egin{pmatrix} \mathsf{NTT}(\check{s}_1) \ dots \ \mathsf{NTT}(\check{s}_{n/d}) \end{pmatrix}.$$

Then the prover uses a generalization of the product proof to many cubic relations to show that

$$\check{\boldsymbol{s}}_i(\check{\boldsymbol{s}}_i+1)(\check{\boldsymbol{s}}_i-1)=\mathbf{0}$$

for all j. This shows that  $\mathsf{NTT}(\check{s}_j) \in \{-1,0,1\}^d$  since the polynomial product in  $\mathcal{R}_q$  is coefficient-wise in the NTT representation. This is the technique that was used in [BLS19].

In parallel, the prover uses the linear proof for the general case from Section 3.3, to show that the polynomials  $\check{s}_j$  really give a solution to the linear equation. The complete protocol is given in Figure 3 and it is proven secure in Theorem 4.1.

#### 4.1 Security Analysis

**Theorem 4.1.** The protocol in Figure 3 is complete, computational honest verifier zero-knowledge under the Module-LWE assumption and computational special sound under the Module-SIS assumption. More precisely, let p be the maximum probability over  $\mathbb{Z}_q$  of the coefficients of  $\mathbf{c} \mod X^k - \zeta^k$  as in Lemma 2.2.

Then, for completeness, in case the honest prover  $\mathcal{P}$  does not abort due to rejection sampling, it always convinces the honest verifier  $\mathcal{V}$ .

For zero-knowledge, there exists a simulator S, that, without access to secret information, outputs a simulation of a non-aborting transcript of the protocol between P and V for every statement  $A\vec{s} = \vec{u}$ ,  $\vec{s} \in \{-1,0,1\}^n$ . Then for every algorithm A that has advantage  $\varepsilon$  in distinguishing the simulated transcript from an actual transcript, there is an algorithm A' with the same running time that also has advantage  $\varepsilon$  in distinguishing  $MLWE_{\lambda,\chi}$ .

For soundness, there is an extractor  $\mathcal{E}$  with the following properties. When given rewindable black-box access to a deterministic prover  $\mathcal{P}^*$  that convinces  $\mathcal{V}$  with probability  $\varepsilon > (3p)^k$ ,  $\mathcal{E}$  either outputs a solution  $\vec{s}^* \in \{-1,0,1\}^n$  to  $A\vec{s}^* = \vec{u}$ , or a MSIS<sub> $\kappa,8d\beta$ </sub> solution for  $\mathbf{B}_0$  in expected time at most  $1/\varepsilon + (\varepsilon - p^k)^{-1}$  when running  $\mathcal{P}^*$  once is assumed to take unit time.

We provide the proof of this theorem in the full version of this paper [ENS20].

#### 4.2 Proof Size

We now look at the size of the non-interactive proof outputs via the Fiat-Shamir transform of the protocol in Figure 3. First, note that for the non-interactive

```
\underline{\text{Prover }\mathcal{P}}
                                                                                                                                                                                                                                                                                                                                                           Verifier V
Inputs:
                                                                                                                                                                                                                                                                                                                                                           A, \vec{u}, \mathbf{B}_0, \vec{\mathbf{b}}_i
  \check{\boldsymbol{s}}_1,\ldots,\check{\boldsymbol{s}}_{n/d}\in\mathcal{R}_q
  \vec{s} = \mathsf{NTT}(\check{s}_1) \| \cdots \| \mathsf{NTT}(\check{s}_{n/d}) \in \{-1, 0, 1\}^n
  A \in \mathbb{Z}_q^{m \times n}
  \vec{u} = A\vec{s}
  \boldsymbol{B}_0 \in \mathcal{R}_q^{\kappa \times (\lambda + \kappa + n/d + 3)}, \vec{\boldsymbol{b}}_1 \dots, \vec{\boldsymbol{b}}_{n/d + 3} \in \mathcal{R}_q^{\lambda + \kappa + n/d + 3}
  \boldsymbol{g} \stackrel{\$}{\leftarrow} \{ \boldsymbol{g} \in \mathcal{R}_q \mid g_0 = \dots = g_{k-1} = 0 \}
  \vec{r} \stackrel{\$}{\leftarrow} \chi^{(\lambda + \kappa + n/d + 3)d}
  \vec{t}_0 = B_0 \vec{r}
  oldsymbol{t}_{rac{n}{d}+1} = \langle ec{oldsymbol{b}}_{rac{n}{d}+1}, ec{oldsymbol{r}} 
angle + oldsymbol{g}
  For j = 1, \ldots, n/d : \mathbf{t}_j = \langle \vec{\mathbf{b}}_j, \vec{\mathbf{r}} \rangle + \check{\mathbf{s}}_j
  For i = 0, ..., k - 1:
          \vec{\boldsymbol{y}}_i \overset{\$}{\leftarrow} [-\delta_1, \delta_1]^{(\lambda + \kappa + n/d + 3)d}
           \vec{\boldsymbol{w}}_i = \boldsymbol{B}_0 \vec{\boldsymbol{y}}_i
                                                                                                                                                                                                                                                                                    \begin{matrix} \vec{\boldsymbol{t}}_0, \boldsymbol{t}_j, \boldsymbol{t}_{\frac{n}{d}+1}, \vec{\boldsymbol{w}}_i \\ & \boldsymbol{\alpha}_1, \dots, \boldsymbol{\alpha}_{kn/d} \overset{\$}{\leftarrow} \mathcal{R}_q \\ & \boldsymbol{\alpha}_i, \vec{\gamma}_{\mu} & \vec{\gamma}_0, \dots, \vec{\gamma}_{k-1} \overset{\$}{\leftarrow} \mathbb{Z}_q^m \end{matrix}
\boldsymbol{t}_{\frac{n}{d}+2} = \langle \vec{\boldsymbol{b}}_{\frac{n}{d}+2}, \vec{\boldsymbol{r}} \rangle + \langle \vec{\boldsymbol{b}}_{\frac{n}{d}+3}, \vec{\boldsymbol{y}}_{0} \rangle - \sum_{i=0}^{k-1} \sum_{j=1}^{n/d} \boldsymbol{\alpha}_{in/d+j} \sigma^{-i} \left( 3 \check{\boldsymbol{s}}_{j} \langle \vec{\boldsymbol{b}}_{j}, \vec{\boldsymbol{y}}_{i} \rangle^{2} \right)
oldsymbol{t}_{rac{n}{d}+3} = \langle ec{oldsymbol{b}}_{rac{n}{d}+3}, ec{oldsymbol{r}}
angle + \sum_{i=0}^{k-1} \sum_{j=1}^{n/d} oldsymbol{lpha}_{in/d+j} \sigma^{-i} \left( (3ec{oldsymbol{s}}_j^2 - 1) \langle ec{oldsymbol{b}}_j, ec{oldsymbol{y}}_i 
angle 
ight)
oldsymbol{v} = \langle oldsymbol{ec{b}}_{rac{n}{d}+2}, oldsymbol{ec{y}}_0 
angle + \sum_{i=0}^{k-1} \sum_{j=1}^{n/d} oldsymbol{lpha}_{in/d+j} \sigma^{-i} \left( \langle oldsymbol{ec{b}}_j, oldsymbol{ec{y}}_i 
angle^3 
ight)
For \mu = 0, \dots, k-1: A^T \vec{\gamma}_{\mu} = \mathsf{NTT}(\psi_1^{(\mu)}) \| \dots \| \mathsf{NTT}(\psi_{n/d}^{(\mu)})
\boldsymbol{h} = \boldsymbol{g} + \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \sum_{j=1}^{n/d} d\boldsymbol{\psi}_{j}^{(\mu)} \check{\boldsymbol{s}}_{j} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right)
        \boldsymbol{v}_i' = \sum_{\mu=0}^{k-1} \frac{1}{k} \boldsymbol{X}^{\mu} \sum_{\nu=0}^{k-1} \sum_{j=1}^{n/d} \sigma^{\nu} \left( \langle d\boldsymbol{\psi}_j^{(\mu)} \vec{\boldsymbol{b}}_j, \vec{\boldsymbol{y}}_{i-\nu} \rangle \right)
  For i = 0, ..., k - 1:
           \vec{z}_i = \vec{y}_i + \sigma^i(c)\vec{r}
          If \|\vec{z}_i\|_{\infty} \geq \delta_1 - T, abort
                                                                                                                                                                                                                                                                                                                                                           Ver(\boldsymbol{t}_j, \vec{\boldsymbol{w}}_i, \alpha_i, \vec{\gamma}_i,
                                                                                                                                                                                                                                                                                                                                                                           m{h}, m{v}, m{v}_i', m{c}, m{ec{z}}_i)
```

Fig. 3. Proof of knowledge of a ternary solution to an unstructured linear equation over  $\mathbb{Z}_q$ . Verification equations are defined in Figure 4.

```
\mathsf{Ver}(oldsymbol{t}_j, oldsymbol{ec{w}}_i, oldsymbol{lpha}_i, ar{\gamma}_i, oldsymbol{h}, oldsymbol{v}, oldsymbol{v}_i', oldsymbol{c}, ar{oldsymbol{z}}_i)
01 \text{ For } i = 0, \dots, k-1:
                  \|\vec{z}_i\|_2 < \beta = \delta_1 - T
                  oldsymbol{B}_0 ec{oldsymbol{z}}_i \stackrel{?}{=} ec{oldsymbol{w}}_i + \sigma^i(oldsymbol{c}) ec{oldsymbol{t}}_0
04 For i = 0, \dots, k-1:
                   For j = 1, ..., n/d:
                           m{f}_i^{(i)} = \langle m{ec{b}}_j, m{ec{z}}_i 
angle - \sigma^i(m{c}) m{t}_j
07 f_{\frac{n}{d}+2} = \langle \vec{b}_{\frac{n}{d}+2}, \vec{z}_0 \rangle - ct_{\frac{n}{d}+2}
08 f_{\frac{n}{d}+3}^{u}=\langle \vec{b}_{\frac{n}{d}+3},\vec{z}_{0}
angle -ct_{\frac{n}{d}+3}
09 \sum_{i=0}^{k-1} \sum_{j=1}^{n/d} \alpha_{in/d+j} \sigma^{-i} \left( \boldsymbol{f}_{j}^{(i)} (\boldsymbol{f}_{j}^{(i)} + \sigma^{i}(\boldsymbol{c})) (\boldsymbol{f}_{j}^{(i)} - \sigma^{i}(\boldsymbol{c})) \right) + \boldsymbol{f}_{\frac{n}{d}+2} + c \boldsymbol{f}_{\frac{n}{d}+3} \stackrel{?}{=} \boldsymbol{v}
 10 For \mu = 0, \dots, k-1:
                   A^T \vec{\gamma}_{\mu} = \mathsf{NTT}(\psi_1^{(\mu)}) \| \cdots \| \mathsf{NTT}(\psi_{n/d}^{(\mu)})
13 \boldsymbol{\tau} = \sum_{\mu=0}^{k-1} \frac{1}{k} X^{\mu} \sum_{\nu=0}^{k-1} \sigma^{\nu} \left( \sum_{j=1}^{n/d} d\boldsymbol{\psi}_{j}^{(\mu)} \boldsymbol{t}_{j} - \langle \vec{u}, \vec{\gamma}_{\mu} \rangle \right)
14 For i = 0, \dots, k-1:
                   \textstyle\sum_{\mu=0}^{k-1}\frac{1}{k}\boldsymbol{X}^{\mu}\sum_{\nu=0}^{k-1}\sum_{j=1}^{n/d}\sigma^{\nu}\left(d\boldsymbol{\psi}_{j}^{(\mu)}\langle\vec{\boldsymbol{b}}_{j},\vec{\boldsymbol{z}}_{i-\nu\bmod{k}}\rangle\right)+\langle\vec{\boldsymbol{b}}_{n/d+1},\vec{\boldsymbol{z}}_{i}\rangle
                           \stackrel{?}{=} oldsymbol{v}_i' + \sigma^i(oldsymbol{c})(oldsymbol{	au} + oldsymbol{t}_{n/d+1} - oldsymbol{h})
 16
```

Fig. 4. Verification equations for Figure 3.

proof the messages  $w_i$ , v and  $v_i$  need not be included in the output as they are uniquely determined by the remaining components. Further, the challenges can be generated from a small seed of 256 bits, which itself is generated as the hash of some components. Therefore, the contribution of the challenges to the total proof length is extremely small and thus we neglect it.

As "full-sized" elements of  $\mathcal{R}_q$ , we have  $\vec{t}_0$ ,  $t_j$ , and h (in fact, h is missing k coefficients, but that is a negligible consideration). Therefore, we have in total

$$\kappa + n/d + 3 + 1$$

full-sized elements of  $\mathcal{R}_q$ , which altogether costs

$$(\kappa + n/d + 4) d\lceil \log q \rceil$$
 bits.

Now, the only remaining part are the vectors  $\vec{z}_i$ . Since the k vectors  $\vec{z}_i$  of length  $(\lambda + \kappa + n/d + 3)d$  over  $\mathbb{Z}_q$  are bounded by  $\delta_1$  in infinity norm, they require

$$k(\lambda + \kappa + n/d + 3)d\lceil \log 2\delta_1 \rceil$$
 bits

in the proof. It is easy to see that no coefficient of the product  $\sigma^i(\mathbf{c})\vec{r}$  can exceed d for any  $0 \le i \le k-1$ . Hence, we set T=d.

In conclusion, the overall proof length is about

$$(\kappa + n/d + 4) d\lceil \log q \rceil + k (\lambda + \kappa + n/d + 3) d\lceil \log 2\delta_1 \rceil \quad \text{bits}, \tag{9}$$

**Proof length optimizations.** The size of the non-interactive proof can be reduced with a number of standard techniques. The first techniques are the two

compression techniques from the Bai-Galbraith [BG14] and Dilithium [DKL<sup>+</sup>18] signature schemes. They reduce the size of the masked openings  $\vec{z}_i$  and the top part  $\vec{t}_0$  of the commitment. As we have mentioned in Section 2.7, the commitment matrix  $B_0$  can be decomposed as  $B_0 = (B'_0, I)$ , where I is the identity matrix of dimension  $\kappa$ . Then we can similarly decompose  $\vec{r} = \vec{r}_1 \parallel \vec{r}_2$  and write

$$ec{t_0} = B_0 ec{r} = B_0' ec{r_1} + ec{r_2}.$$

Now, we see that when we give an approximate proof for this equation that proves  $\bar{c}\vec{t}_0 = B_0'\bar{z}_1 + \bar{z}_2$ , we are essentially proving knowledge of a short vector  $\bar{z}_1$  such that  $B_1\bar{z}_1$  is close to  $\bar{c}t_0$ . But this can be achieved in zero-knowledge without sending both masked openings  $\vec{z}_1$  and  $\vec{z}_2$  as follows. Let  $\vec{y}$  be the masking vector for  $\vec{r}_1$ ,  $\vec{z} = \vec{y} + c\vec{r}_1$ , and  $\vec{w} = B_0'\vec{y}$ . Then decompose  $\vec{w}$  as quotient and remainder modulo  $\alpha = 2\delta_2 \approx \delta_1$ ,

$$\vec{\boldsymbol{w}} = \alpha \vec{\boldsymbol{w}}_1 + \vec{\boldsymbol{w}}_0$$

where  $\|\vec{w}_0\|_{\infty} \leq \delta_2$ . It follows that

$$\boldsymbol{B}_0'\vec{z} - c\vec{t}_0 = \alpha \vec{w}_1 + \vec{w}_0 - c\vec{r}_2.$$

Hence, when we keep the remainder  $\vec{w}_0$  secret, it can serve as the masking vector for  $\vec{r}_2$ . Moreover, by rejecting if  $\|\vec{w}_0 - c\vec{r}_2\|_{\infty} \geq \delta_2 - T$ , this doesn't leak information about  $\vec{r}_2$  and the equation can be checked by the verifier by decomposing  $B_0'\vec{z} - c\vec{t}_0$ . The second compression technique starts with the same observation that it suffices to prove knowledge of a preimage of  $B_0'$  that is close to  $c\vec{t}_0$ . When we decompose

$$\vec{t}_0 = \vec{t}_{0,1} 2^D + \vec{t}_{0,0},$$

then it is actually sufficient to only send the high bits  $\vec{t}_{0,1}$ , because the low bits only introduce an additional noise term  $\bar{c}\vec{t}_{0,0}$  in the verification equation that can be handled with sending a few hint bits. We defer to the Dilithium paper for the details.

Another optimization we employ is in the calculation of a maximum absolute coefficient in  $\sigma^i(\mathbf{c})\vec{r}$ . In our applications, we aim to minimize d and set d=128. Now in this case, a coefficient of  $\sigma^i(\mathbf{c})\vec{r}$  is the sum of 128 coefficients with i.i.d. P(-1)=P(1)=5/32 and  $P(0)=22/32.^6$  If we calculate the convolution of this distribution, we find that a coefficient is bigger than 78 in absolute value with probability less than  $2^{-114}$ . Hence, by a union bound the probability that any of the coefficients in  $(\sigma^0(\mathbf{c})\vec{r},\ldots,\sigma^{k-1}(\mathbf{c})\vec{r})$  is bigger than 78 will still be negligibly small. Therefore, we can set T=78 instead of T=d=128.

The previous optimization can be combined with the following optimization. Instead of using the k rotations  $\sigma^i(\mathbf{c})$  of one dense challenge for the masked openings  $\vec{z}_i$ , we can write  $\mathbf{c}$  in the subring generated by  $X^k$  and fixed by  $\sigma$ ,

<sup>&</sup>lt;sup>6</sup> Recall that a coefficient of c is zero with probability 1/2 and a coefficient of  $\vec{r}$  is zero with probability 6/16. The probabilities of  $\pm 1$  are always equal to each other.

i.e.  $c = c_0 + c_1 X + \cdots + c_{k-1} X^{k-1}$  where the polynomials  $c_j$  are sparse with only at most d/k nonzero coefficients. Then all the images  $\sigma^i(c)$  are just different linear combinations of the  $c_j$ . So it suffices to use these sparse challenges  $c_j$  in the masked openings that are transmitted and the verifier can then recombine them to obtain the masked openings with challenges  $\sigma^i(c)$  as needed in the protocols.

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