

Quasi-Adaptive NIZK for Linear Subspaces Revisited



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Hoeteck Wee (**ENS**)

non-interactive zero knowledge

[Blum Feldman Micali 88, Groth Sahai 08]

... algebraic relations in a group **impact**  pairing-based crypto

non-interactive zero knowledge

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... algebraic relations in a group **impact**  pairing-based crypto

i. **better** efficiency

— group signatures [G06, G07]

non-interactive zero knowledge

[Blum Feldman Micali 88, Groth Sahai 08]

... algebraic relations in a group  pairing-based crypto

i. **better** efficiency

– group signatures [G06, G07]

ii. **stronger** security

– anonymous credentials [BCLK08, BCKLS09, FI1]

non-interactive zero knowledge

[Blum Feldman Micali 88, Groth Sahai 08]

... algebraic relations in a group  pairing-based crypto

impact

i. **better** efficiency

– group signatures [G06, G07]

ii. **stronger** security

– anonymous credentials [BCLK08, BCKLS09, FI11]

iii. **less** interaction

– two-party protocols [KV11, FLMI11]

non-interactive zero knowledge

[Blum Feldman Micali 88, Groth Sahai 08]

... linear subspaces over a group

quasi-adaptive nizk

[Jutla Roy 13]

- ... linear subspaces over a group, **where**
- crs may depend on linear subspace
- computational soundness (but adaptive)

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constant-size proofs [Libert Peters Joye Yung 14, Jutla Roy 14, Abdalla Benhamouda Pointcheval 15]

- independent of dimensions of subspace

quasi-adaptive nizk

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- computational soundness (but adaptive)

constant-size proofs [Libert Peters Joye Yung 14, Jutla Roy 14, Abdalla Benhamouda Pointcheval 15]

- independent of dimensions of subspace
- extensions to simulation-soundness (OTSS, USS)

quasi-adaptive nizk

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... linear subspaces over a group, **where**

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applications. shorter kdm-cca encryption, cca-secure IBE, ...

this work

better identity-based encryption (IBE)

→ **better** quasi-adaptive nizk

this work

- 1 simpler + improved quasi-adaptive nizk for linear subspaces

$$(\mathbf{xM})\mathbf{K} = \mathbf{x}(\mathbf{MK})$$

this work

- 1 simpler + improved quasi-adaptive nizk for linear subspaces

$$(\mathbf{xM})\mathbf{KA} = \mathbf{x}(\mathbf{MK})\mathbf{A}$$

this work

- 1 simpler + improved quasi-adaptive nizk for linear subspaces

soundness.

| | AS^- | AS | OTSS | USS |
|----------|--------|----|------|-----|
| [LPJY14] | | 3 | 4 | 20 |
| [JR14] | 2 | | | |
| [ABP15] | 2 | 3 | 3 | |

this work

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| [LPJY14] | | 3 | 4 | 20 |
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| [ABP15] | 1 | 2 | 2 | |
| this | 1 | 2 | 2 | 4 |

this work

- 1 simpler + improved quasi-adaptive nizk for linear subspaces

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better assumptions / **shorter** parameters / **fewer** pairings

this work

- 1 simpler + improved quasi-adaptive nizk for linear subspaces

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better assumptions / **shorter** parameters / **fewer** pairings

- 2 ... linearly homomorphic structure-preserving signatures [LPJY13]

this work

private-verifier nizk

(information-theoretic security)

this work

private-verifier nizk

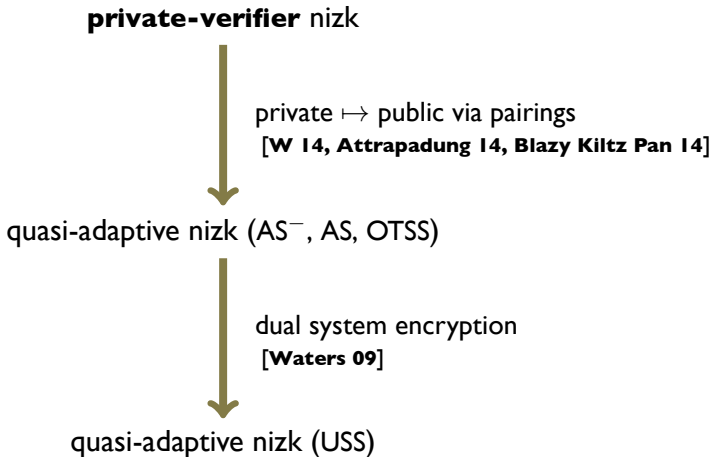


private \mapsto public via pairings

[W 14, Attrapadung 14, Blazy Kiltz Pan 14]

quasi-adaptive nizk (AS^- , AS , $OTSS$)

this work



bilinear groups

def. $\mathbb{G}_1, \mathbb{G}_2, \mathbb{G}_T$ cyclic groups of prime order q

– $e : \mathbb{G}_1 \times \mathbb{G}_2 \rightarrow \mathbb{G}_T, \quad e(g_1^x, g_2^y) = e(g_1, g_2)^{xy}$

bilinear groups

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matrix assumptions [EHKRV13, MRV15]:

– diffie-hellman assumptions (e.g. SXDH, DLIN, k -LIN)

$$\left(\boxed{\mathbf{A}}, \boxed{\mathbf{A}} \boxed{\mathbf{s}} \right) \approx_c \left(\boxed{\mathbf{A}}, \boxed{\$} \right)$$

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$$\text{e.g. } \mathbf{A} = \begin{pmatrix} 1 \\ a_1 \end{pmatrix}; \quad \mathbf{A} = \begin{pmatrix} 1 & 1 \\ a_1 & 0 \\ 0 & a_2 \end{pmatrix}$$

bilinear groups

def. $\mathbb{G}_1, \mathbb{G}_2, \mathbb{G}_T$ cyclic groups of prime order q

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$$\left(\boxed{\mathbf{A}}, \boxed{\mathbf{A}} \boxed{\mathbf{s}} \right) \approx_c \left(\boxed{\mathbf{A}}, \boxed{\$} \right)$$

– kernel assumption (e.g. SDP)

given $[\mathbf{A}]_2$, hard to find $[\mathbf{z}]_1 \neq [\mathbf{0}]_1$ s.t. $\mathbf{zA} = \mathbf{0}$

$$\boxed{\mathbf{z}} \quad \boxed{\mathbf{A}}$$

non-interactive zero knowledge

P

$([\mathbf{M}]_1, [\mathbf{y}]_1) : \mathbf{y} = \mathbf{xM}$

V

non-interactive zero knowledge

P

$$([\mathbf{M}]_1, [\mathbf{y}]_1) : \mathbf{y} = \mathbf{xM}$$

V

public: crs

proof π



non-interactive zero knowledge

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$$([\mathbf{M}]_1, [\mathbf{y}]_1) : \mathbf{y} = \mathbf{xM}$$

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public: crs

proof π



- **completeness.** if $\mathbf{y} = \mathbf{xM}$, then V accepts π
- **soundness.** if $\mathbf{y} \notin \text{span}(\mathbf{M})$, then V rejects w.h.p.
- **zero knowledge.** $(\text{crs}, \pi) \equiv \text{simulator}([\mathbf{M}]_1, [\mathbf{y}]_1)$

non-interactive zero knowledge

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$([\mathbf{M}]_1, [\mathbf{y}]_1) : \mathbf{y} = \mathbf{xM}$

public: crs

V

private: $\mathbf{k} \leftarrow \$$

proof π



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our construction

P

$([M]_1, [y]_1) : y = xM$

public: crs

V

private: $k \leftarrow \$$

proof π



y

=

x

M

our construction

P

$([M]_1, [y]_1) : y = xM$

V

public: $[Mk]_1$

private: $k \leftarrow \$$

proof π



M

k

our construction

P

$([M]_1, [y]_1) : y = xM$

V

public: $[Mk]_1$

private: $k \leftarrow \$$

$\pi := x[Mk]_1$



x

M

k

our construction

P

$([M]_1, [y]_1) : y = xM$

V

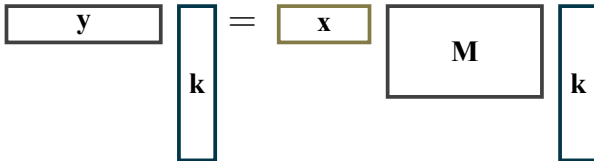
public: $[Mk]_1$

private: $k \leftarrow \$$

$\pi := x[Mk]_1$



$\pi \stackrel{?}{=} [y]_1 k$



completeness. $(xM)k = x(Mk)$

our construction

P

$([M]_1, [y]_1) : y = xM$

V

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private: $k \leftarrow \$$

$\pi := x[Mk]_1$

$\pi \stackrel{?}{=} [y]_1 k$

y

k

zero-knowledge

our construction

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$$([M]_1, [y]_1) : y = xM$$

public: $[Mk]_1$

V

private: $k \leftarrow \$$



y

$\notin \text{span}$

M

our construction

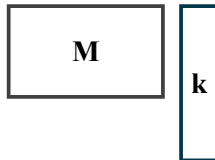
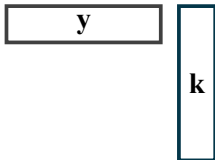
P

$$([M]_1, [y]_1) : y = xM$$

public: $[Mk]_1$

V

private: $k \leftarrow \$$



our construction

P

$([M]_1, [y]_1) : y = xM$

public: $[MK]_1$

V

private: $K \leftarrow \$$

$\pi := x[MK]_1$



$\pi \stackrel{?}{=} [y]_1 K$

private \mapsto public

(I) $k \mapsto K$

our construction

P

$$([M]_1, [y]_1) : y = xM$$

V

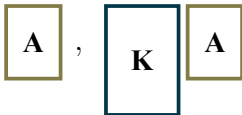
public: $[MK]_1, [A]_2, [KA]_2$

$$\pi := x[MK]_1 \longrightarrow \pi \stackrel{?}{=} [y]_1 K$$

private \mapsto public

(1) $k \mapsto K$

(2) publish $([A]_2, [KA]_2)$ in crs



our construction

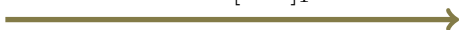
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$$([M]_1, [y]_1) : y = xM$$

V

public: $[MK]_1, [A]_2, [KA]_2$

$$\pi := x[MK]_1$$



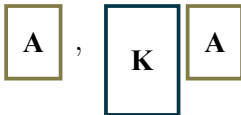
$$\pi \stackrel{?}{=} [y]_1 K$$

private \mapsto public

$$\pi \quad A \quad \stackrel{?}{=} \quad [y]_1 \quad KA$$

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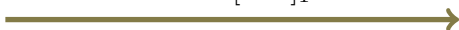
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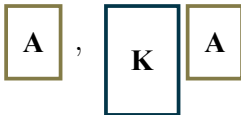
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$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

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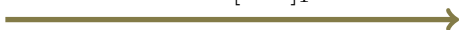
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$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

completeness. $x(MK)A = (xM)(KA)$

zero-knowledge. $\pi = [y]_1 K$

our construction

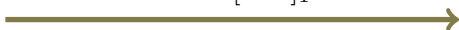
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$$\pi := x[MK]_1$$



$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

soundness.

cheating proof $([y]_1, \pi)$ for public-verifier

\Rightarrow cheating proof $([y]_1, \pi)$ for private-verifier

our construction

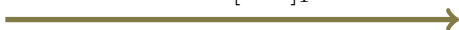
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$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

soundness.

$$e(\pi, [A]_2) = e([y]_1, [KA]_2)$$

$$\Rightarrow \pi = [y]_1 K$$

our construction

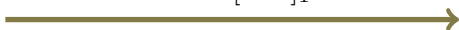
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$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

soundness.

$$\pi \cdot A = [y]_1 \cdot KA$$

$$\Rightarrow \pi = [y]_1 K$$

our construction

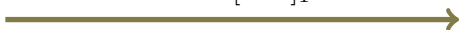
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$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

soundness.

$$(\pi - [y]_1 K)A = 0$$

$$\Rightarrow \pi = [y]_1 K$$

our construction

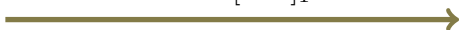
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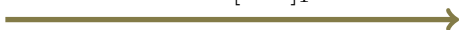
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$$\pi \stackrel{?}{=} [y]_1 K$$

$$e(\pi, [A]_2) \stackrel{?}{=} e([y]_1, [KA]_2)$$

simulation-soundness.

– **one-time.** replace K by $K_0 + \tau K_1$ (w.r.t. tag τ)

our construction

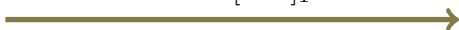
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simulation-soundness.

- **one-time.** replace K by $K_0 + \tau K_1$ (w.r.t. tag τ)
- **unbounded.** (randomized) PRF from IBE [BKPI4, CGW15]

conclusion

better identity-based encryption (IBE)

private \mapsto public via pairings

 **better** quasi-adaptive nizk