

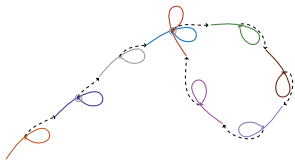
# Memory Efficient Attacks on Small LWE Keys

Andre Esser <sup>1</sup>   Rahul Girme <sup>2</sup>   Arindam Mukherjee <sup>2</sup>   Santanu Sarkar <sup>2</sup>

<sup>1</sup>Technology Innovation Institute, UAE

<sup>2</sup>Indian Institute of Technology Madras, India

Asiacrypt 2023, 7 December 2023



# Motivation

- Used in NTRU, Kyber, Dilithium.
- Hybrid Attack (Nick Howgrave-Graham, 2007).
- May's combinatorial attack (Crypto 2021).
- Enormous memory required.

This work: New memoryless algorithm and time-memory trade-off.

## Definition (Ternary LWE problem)

Given:  $q = \text{poly}(n)$ ,  $w \in \mathbb{N}$ ,  $\mathbf{A} \in \mathbb{Z}_q^{n \times n}$ ,  $\mathbf{b} \in \mathbb{Z}_q^n$ , satisfying  $\mathbf{A}\mathbf{s} = \mathbf{b} + \mathbf{e} \pmod{q}$ , where  $\mathbf{s}, \mathbf{e} \in \{-1, 0, 1\}^n$  and  $\text{wt}(\mathbf{s}) = w$ .

Find:  $\mathbf{s} \in \{-1, 0, 1\}^n$ .

- Simple linear algebra if  $\mathbf{e}$  is known.
- If  $\mathbf{A}\mathbf{s} - \mathbf{b} \in \{-1, 0, 1\}^n$ , then output  $\mathbf{s}$ . Brute-force in  $3^n$  with polynomial memory.
- For simplicity assume  $\mathbf{s}$  has equal number of 1 and  $-1$ .
- For the rest of the talk  $\text{wt}(\mathbf{s}) = \frac{n}{2}$ .

# Basics of Collision Search

For a random function  $f : S \rightarrow S$ ,  $(y_1, y_2) \in S^2$  with  $f(y_1) = f(y_2)$  can be found using  $\mathcal{O}(\sqrt{|S|})$  evaluations of  $f$  and polynomial memory.

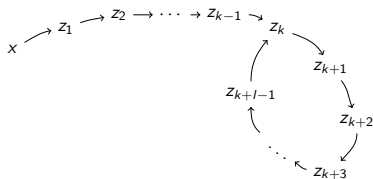
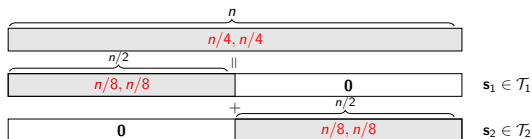


Figure:  $f^i(x)$  is denoted by  $z_i$

Procedure can be extended to two random functions  $f_1$  and  $f_2$ , namely  $\text{RHO}(f_1, f_2, x)$ , where  $x$  is random starting point. Collision is unique (depends on the starting point).

# Solving LWE via Collision Search (van Vredendaal 2016)

Recall  $\mathbf{As} = \mathbf{b} + \mathbf{e} \pmod q$ . Split  $\mathbf{s} = \mathbf{s}_1 + \mathbf{s}_2$ .



$$\mathbf{As}_1 = \mathbf{b} + \mathbf{e} - \mathbf{As}_2$$

Guess lower  $\ell$  coordinates of  $\mathbf{e}$  (May 2021). Small, Get for free, Not enough for linear algebra.

$$\underbrace{\pi_\ell(\mathbf{As}_1)}_{f_1(\mathbf{s}_1)} = \underbrace{\pi_\ell(\mathbf{b} + \mathbf{e} - \mathbf{As}_2)}_{f_2(\mathbf{s}_2)}$$

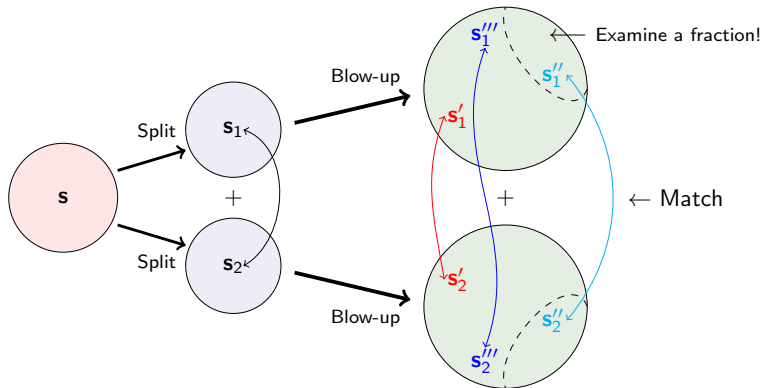
Search for collisions between  $f_1$  and  $f_2$ .

$$T = \tilde{O}(\#\text{Collisions} \cdot T_{\text{Rho}}) = \boxed{2^{1.125n}}$$

# Representation Technique (Howgrave-Graham, Joux 2010)

$$(1, 0, -1, 0, -1, 1) =$$

$$\begin{array}{cccc} (1, 0, -1, 0, 0, 0) & (1, 0, 0, 0, -1, 0) & (0, 0, -1, 0, 0, 1) & (0, 0, 0, 0, -1, 1) \\ + & + & + & \\ (0, 0, 0, 0, -1, 1) & (0, 0, -1, 0, 0, 1) & (1, 0, 0, 0, -1, 0) & (1, 0, -1, 0, 0, 0) \end{array}$$



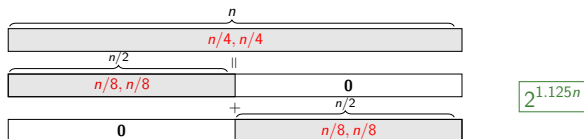
# Impact of representations

Search space goes up but representations take care of it.

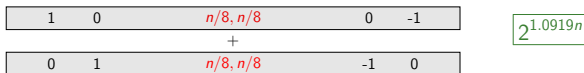
$$T = \tilde{O}\left(\frac{\#Collisions}{\#Representations} \cdot T_{\text{Rho}}\right).$$

# Basic Collision Search Instantiations

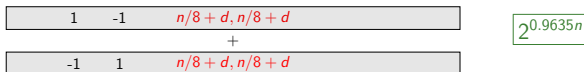
## 1 van Vredendaal:



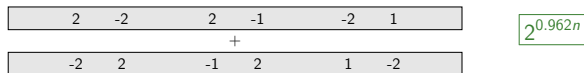
## 2 May's REP-0:



## 3 May's REP-1:



## 4 May's REP-2:



Our result:  $2^{0.8425n}$



# Nested-Collision-Search (DDKS 2016)

$$\mathbf{s} = \mathbf{s}_1 + \mathbf{s}_2 + \mathbf{s}_3 + \mathbf{s}_4.$$

$$\mathbf{A}(\mathbf{s}_1 + \mathbf{s}_2) = \mathbf{b} - \mathbf{A}(\mathbf{s}_3 + \mathbf{s}_4) + \mathbf{e} \pmod{q}.$$

Guess the first  $2\ell$  coordinates of  $\mathbf{e}$ . (Small, Get for free and Sufficient to identify  $\mathbf{s}$  uniquely!)

$$\pi_{2\ell}(\mathbf{A}(\mathbf{s}_1 + \mathbf{s}_2)) = \pi_{2\ell}(\mathbf{b} + \mathbf{e}) - \pi_{2\ell}(\mathbf{A}(\mathbf{s}_3 + \mathbf{s}_4)) \pmod{q},$$

Randomly choose  $\mathbf{r} := \pi_{2\ell}(\mathbf{A}(\mathbf{s}_1 + \mathbf{s}_2))$ .

$$\underbrace{\pi_{2\ell}(\mathbf{A}\mathbf{s}_1)}_{f_1(\mathbf{s}_1)} = \underbrace{\mathbf{r} - \pi_{2\ell}(\mathbf{A}\mathbf{s}_2)}_{f_2(\mathbf{s}_2)} \pmod{q}$$

$$\underbrace{\pi_{2\ell}(\mathbf{A}\mathbf{s}_3)}_{f_3(\mathbf{s}_3)} = \underbrace{\pi_{2\ell}(\mathbf{b} + \mathbf{e}) - \mathbf{r} - \pi_{2\ell}(\mathbf{A}\mathbf{s}_4)}_{f_4(\mathbf{s}_4)} \pmod{q}.$$

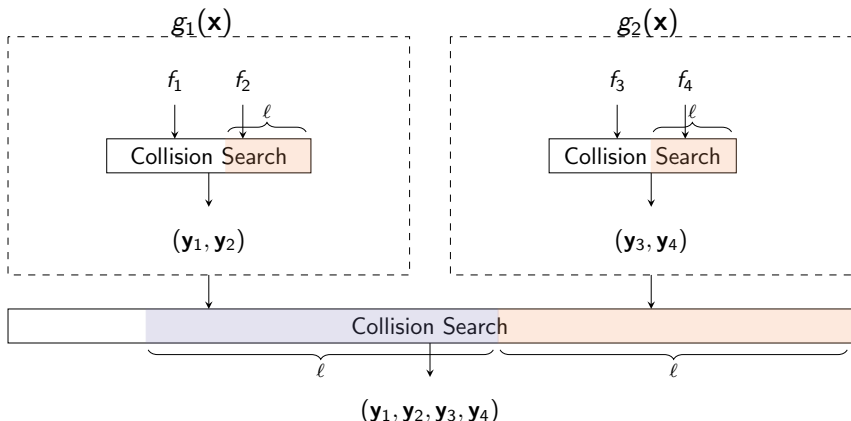
# Nested-Collision-Search

Let  $\vartheta_\ell(\mathbf{x}) := (x_{\ell+1}, \dots, x_{2\ell})$ .

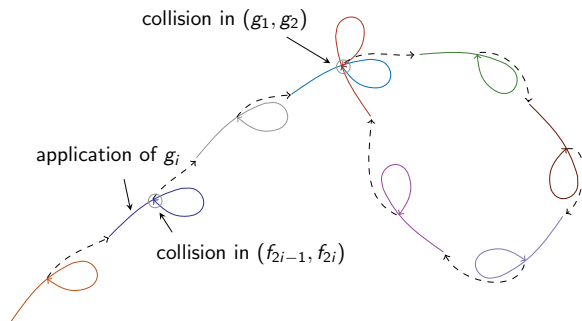
$g_1: \mathbf{x} \mapsto \vartheta_\ell(\mathbf{A}(\mathbf{y}_1 + \mathbf{y}_2))$  , where  $(\mathbf{y}_1, \mathbf{y}_2) = \text{RHO}(f_1, f_2, \mathbf{x})$  and

$g_2: \mathbf{x} \mapsto \vartheta_\ell(\mathbf{b}') - \vartheta_\ell(\mathbf{A}(\mathbf{y}_3 + \mathbf{y}_4))$ , where  $(\mathbf{y}_3, \mathbf{y}_4) = \text{RHO}(f_3, f_4, \mathbf{x})$ .

Now just search for collisions between  $g_1, g_2$ .

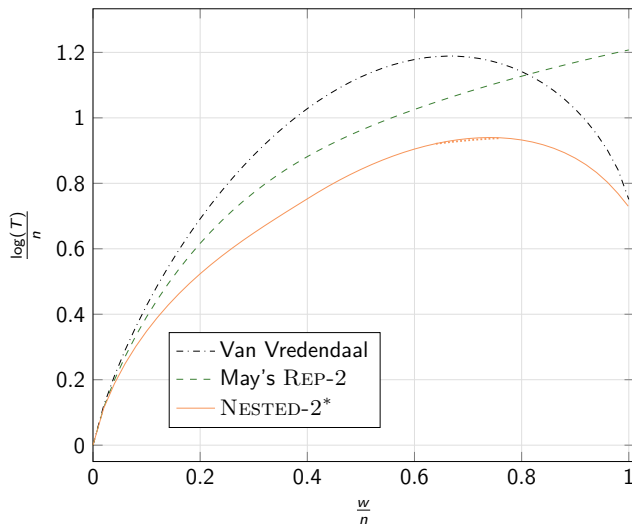


# Time-Complexity of Nested-Collision-Search



$$T = \underbrace{\frac{\# \text{Collisions}}{\# \text{Representations}}}_{\text{Less}} \cdot \underbrace{T_{\text{Nested-Rho}}}_{\text{More}} = \tilde{O}(2^{0.8425n})$$

# Comparing our Memoryless Algorithm

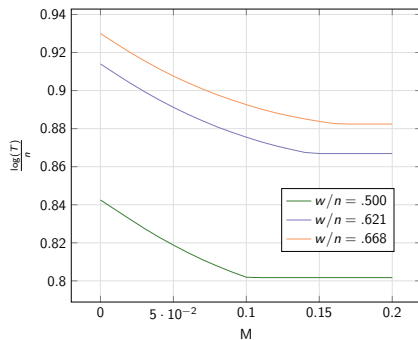


# Time-Memory Trade-off using PCS

## Theorem (Parallel Collision Search, Oorschot, Wiener 1999)

Finds  $M$  collisions between  $f_1$  and  $f_2$  using on expectation  $\tilde{O}\left(\sqrt{M \cdot |S|}\right)$  function evaluations and  $\tilde{O}(M)$  units of memory.

Maximum memory spent  $\leq \#$  needed collisions (small for optimal instantiation)  
Idea: Incorporate the PCS speedup in Time complexity and re-optimize.



# Conclusion

- Improved memoryless algorithm for ternary LWE keys.
- Time-memory Trade-off for a small exponential memory.
- More in the paper:
  - Adapting our technique for small max-norms 2 and 3.
  - Using techniques from information set decoding to improve the uniform-secrets case.

<https://eprint.iacr.org/2023/243>

<https://github.com/arindamIITM/Small-LWE-Keys>

**Thank You.**