

RUHR-UNIVERSITÄT BOCHUM

Quantitative Fault Injection Analysis

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CASA
CYBER SECURITY IN THE AGE
OF LARGE-SCALE ADVERSARIES

RUHR
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BOCHUM

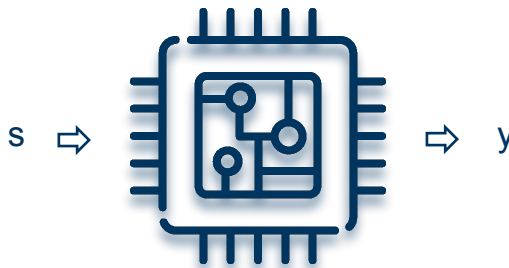
RUB

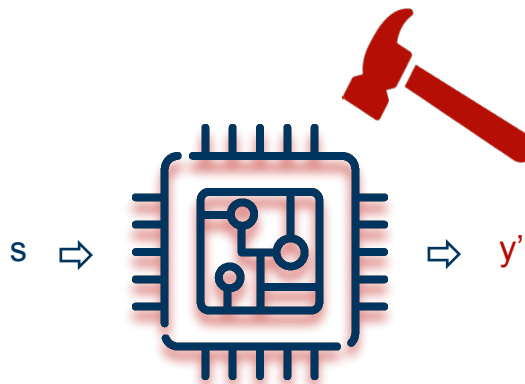


WPI

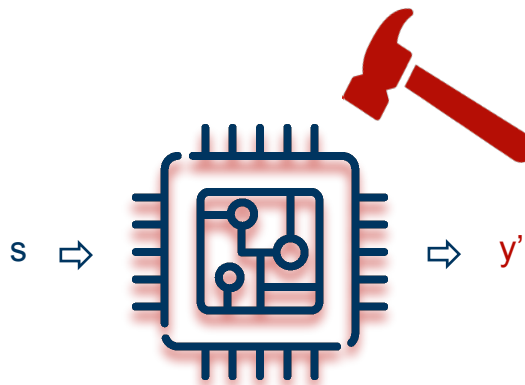
Chair for Security Engineering
Faculty of Computer Science
Ruhr University Bochum





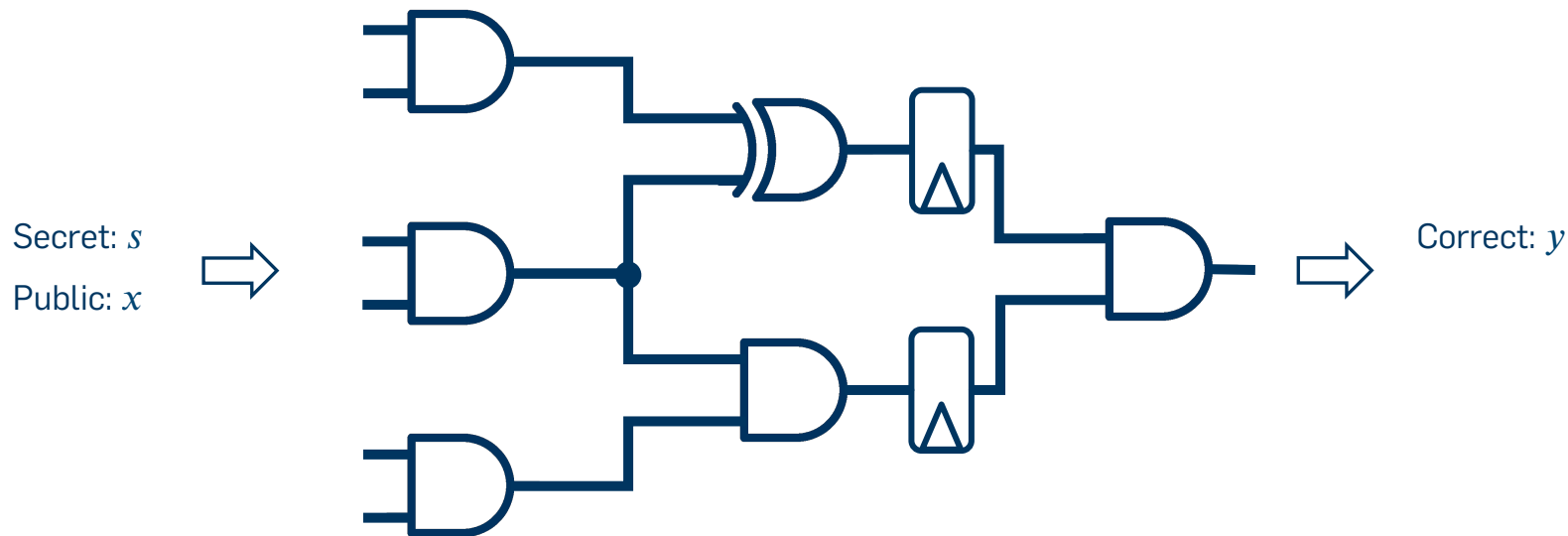


Fault-Injection Attacks



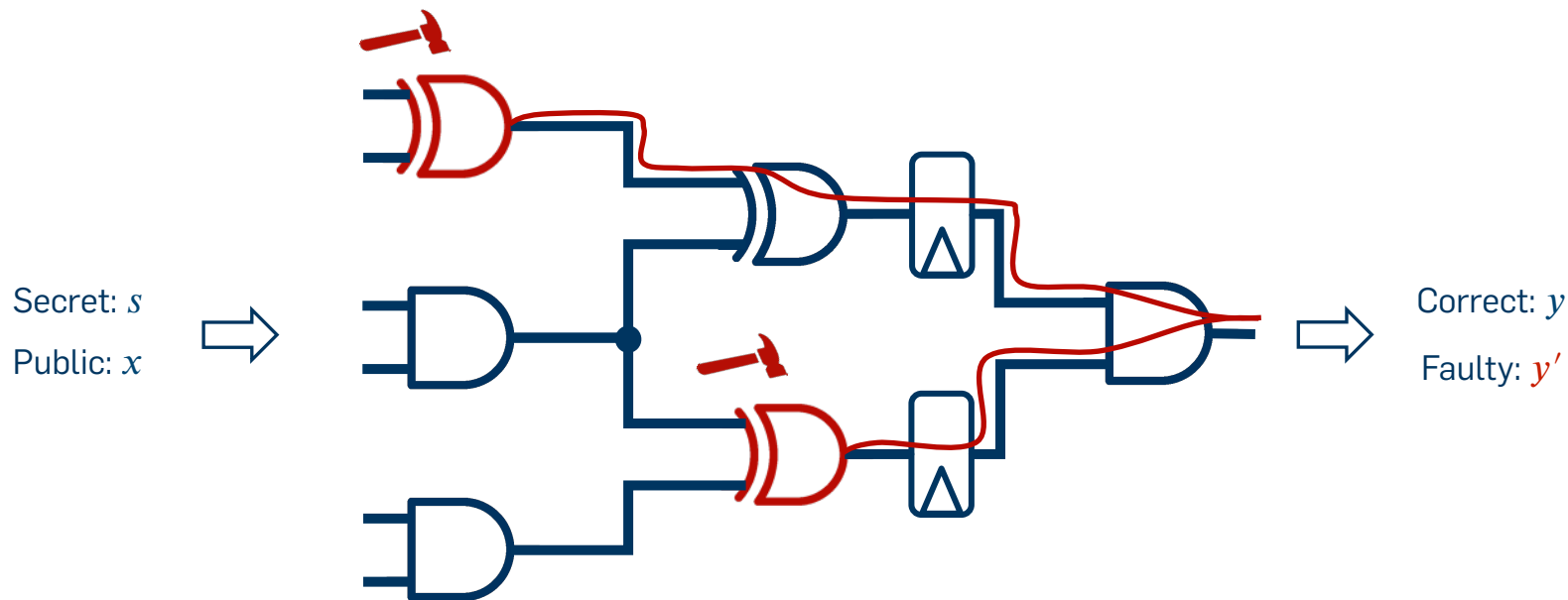
Fault-Injection Attacks

How much information about a secret s can an adversary learn by injecting a fault?



Fault Model:

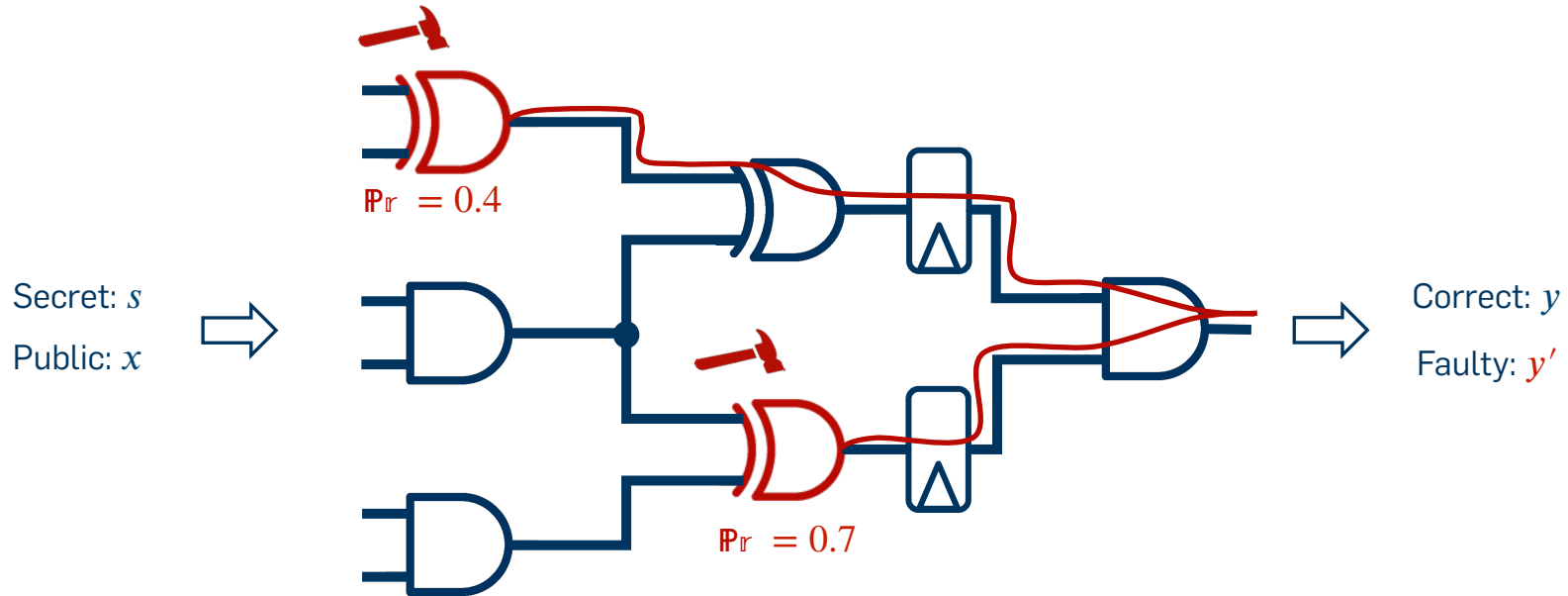
Predefined set of gate transformations.



Fault Model:

Predefined set of gate transformations.

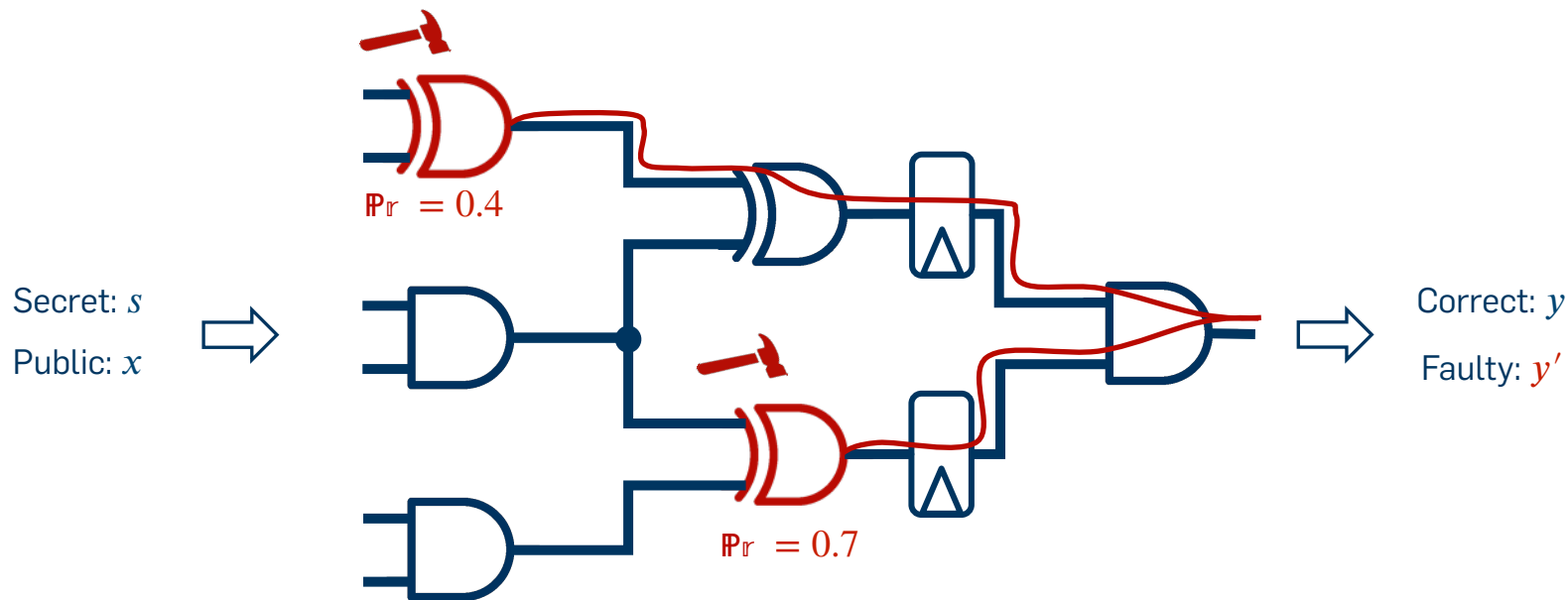
Adversary Model



Fault Model:

Distribution over a predefined set of gate transformations.

Adversary Model



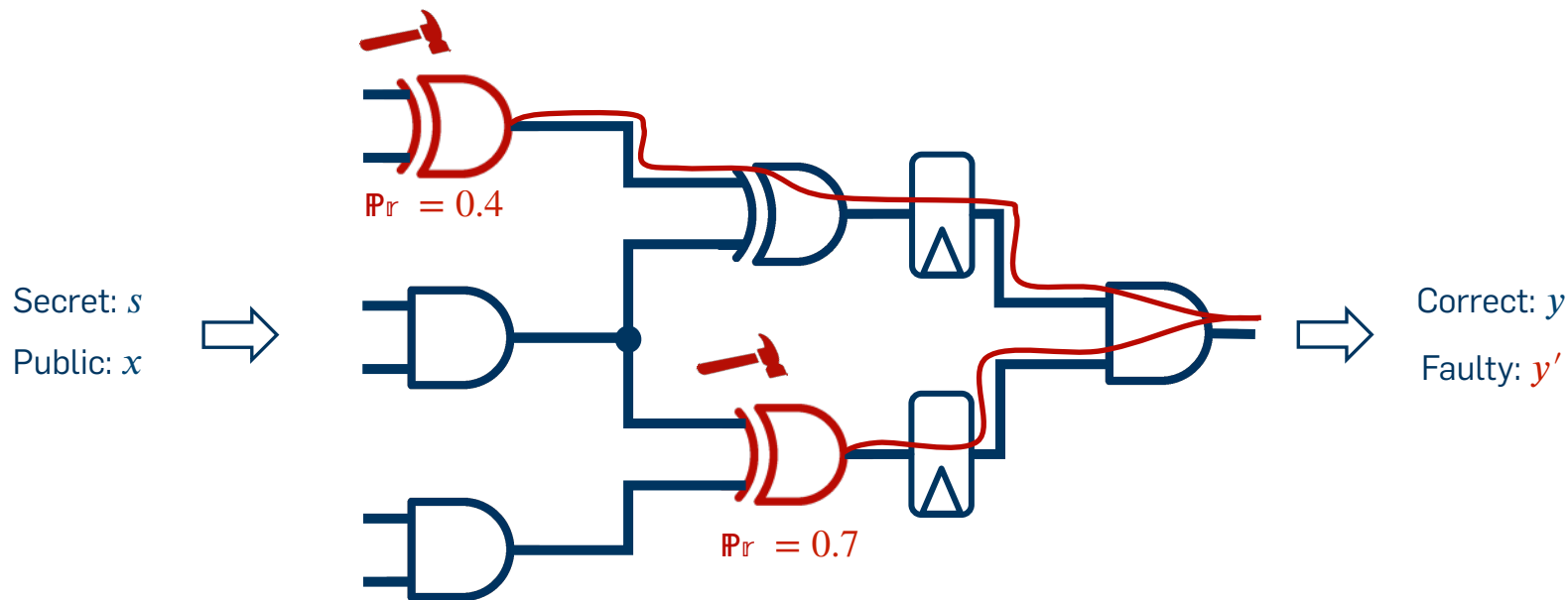
View of Adversary:

$\mathbb{D}_S \mathbb{D}_X$

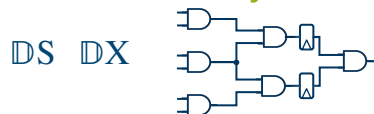
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Adversary Model



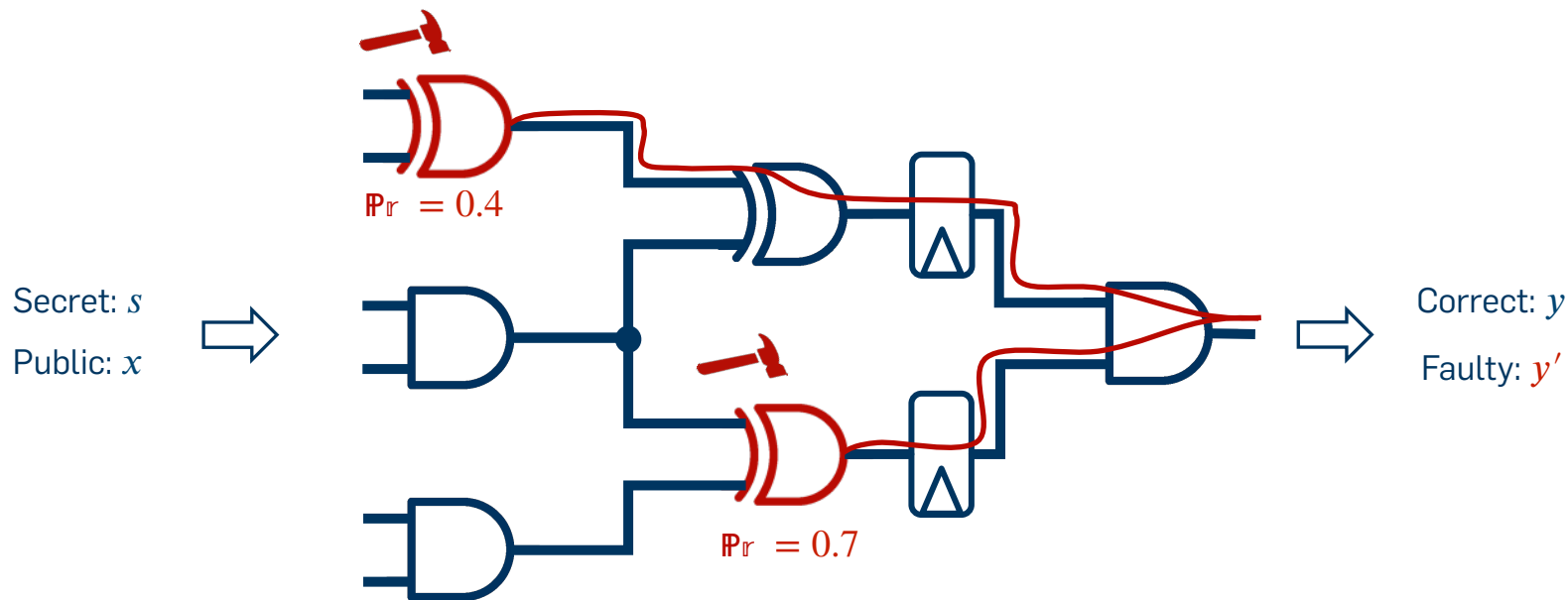
View of Adversary:



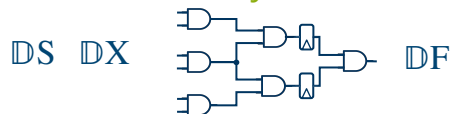
Fault Model:

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Adversary Model



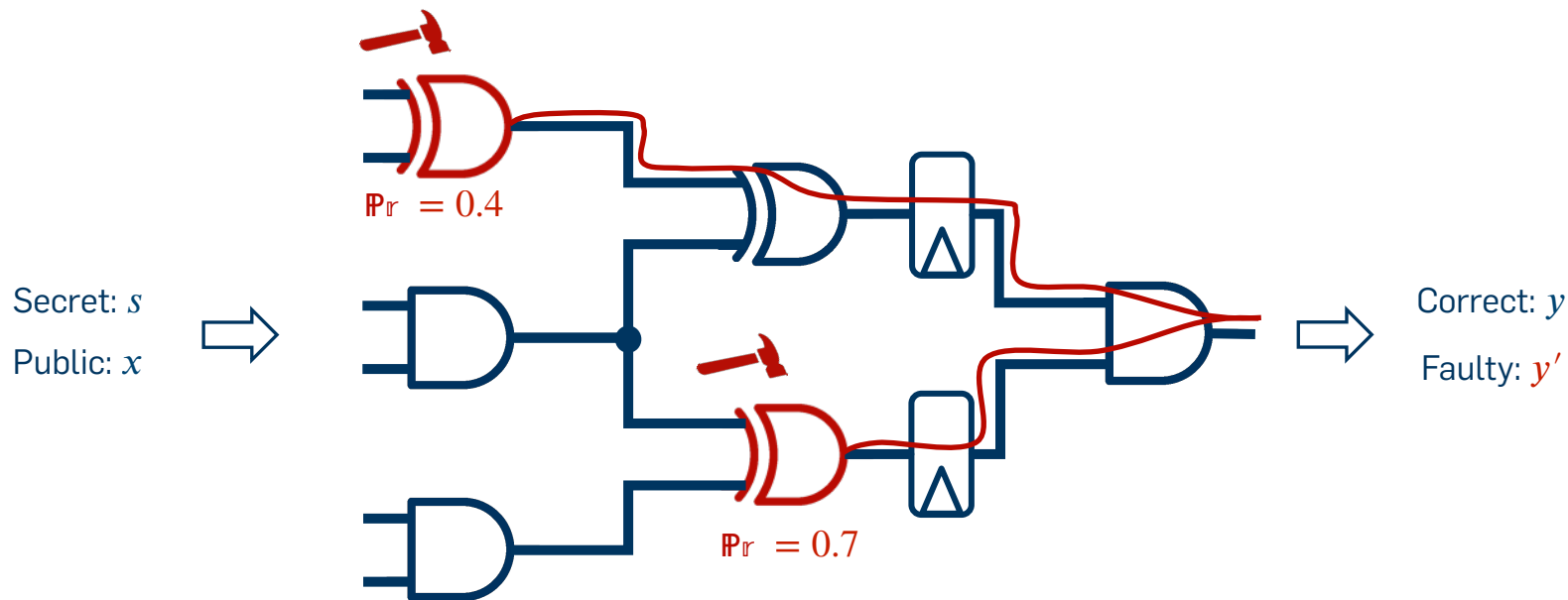
View of Adversary:



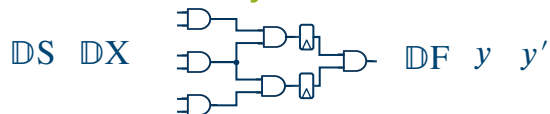
Fault Model:

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Adversary Model



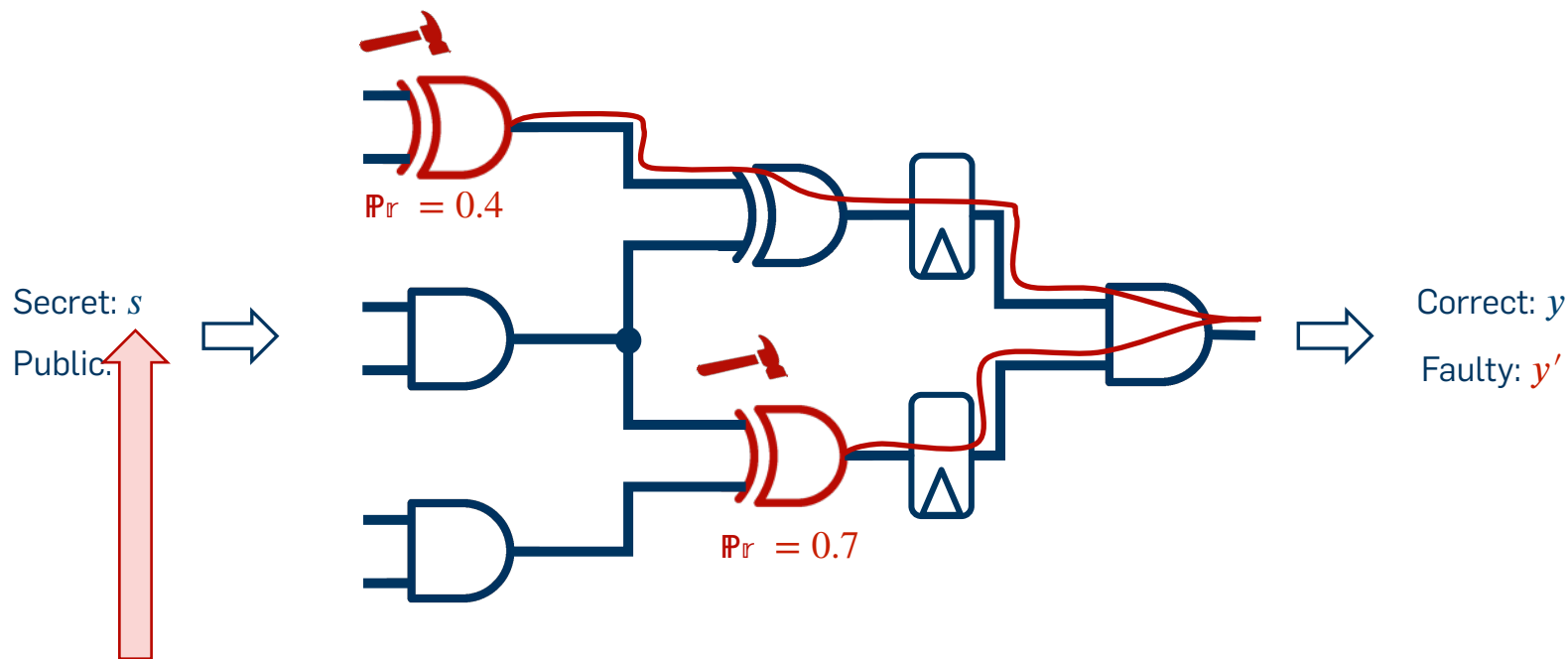
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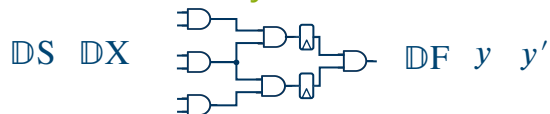
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Distribution over a predefined set of gate transformations.

Adversary Model

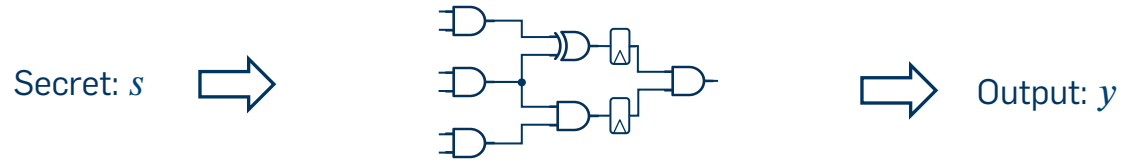


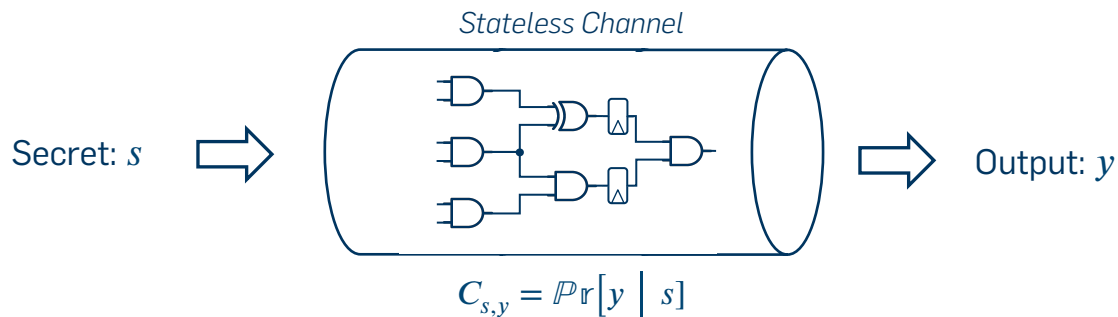
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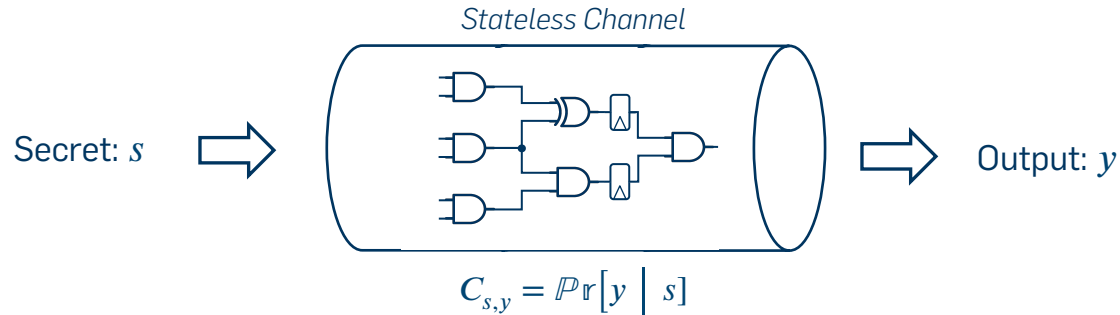


Fault Model:

Distribution over a predefined set of gate transformations.







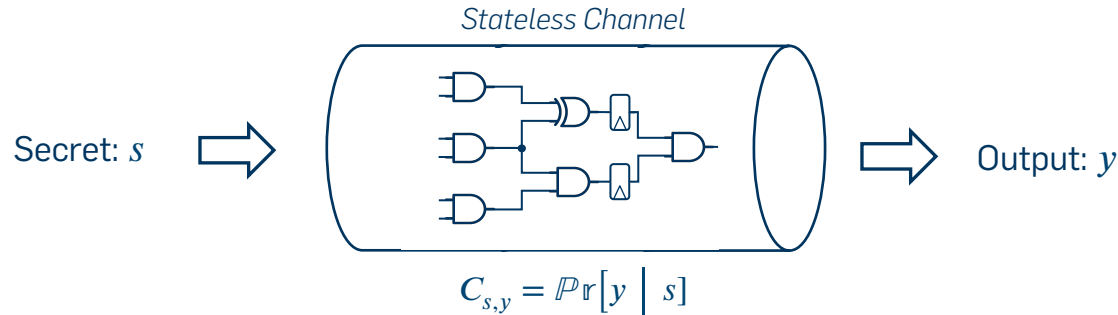
Vulnerability:

Expected probability that an adversary can guess a secret s .

$$V[S] = \max_{s \in S} (\Pr[S = s])$$

$$V[S \mid Y] = \sum_{y \in Y} \Pr[Y = y] \cdot \max_{s \in S} (\Pr[S = s \mid Y = y])$$

Min-Entropy

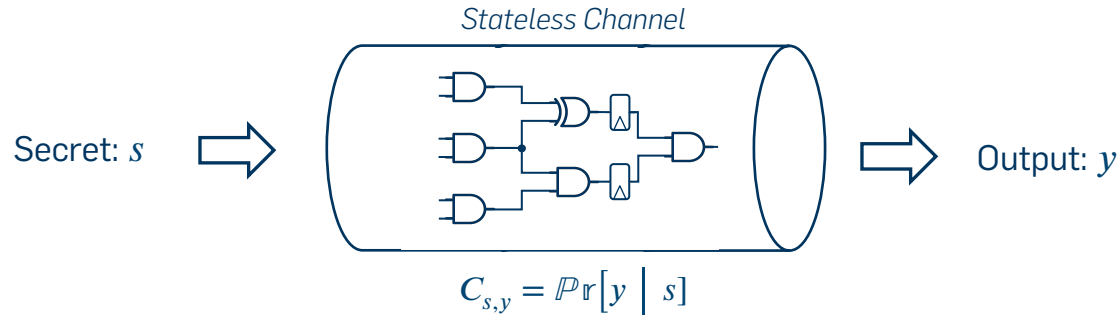


Min-Entropy:

Remaining uncertainty about the secret in bits.

$$H_{\infty}[S] = \log_2\left(\frac{1}{V[S]}\right)$$

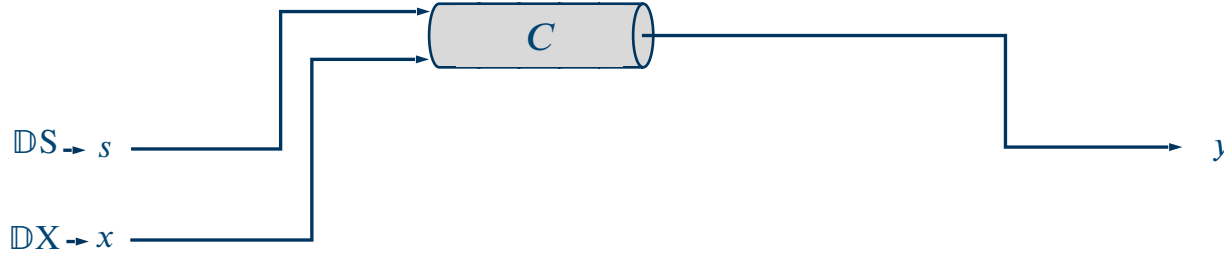
$$H_{\infty}[S | Y] = \log_2\left(\frac{1}{V[S | Y]}\right)$$

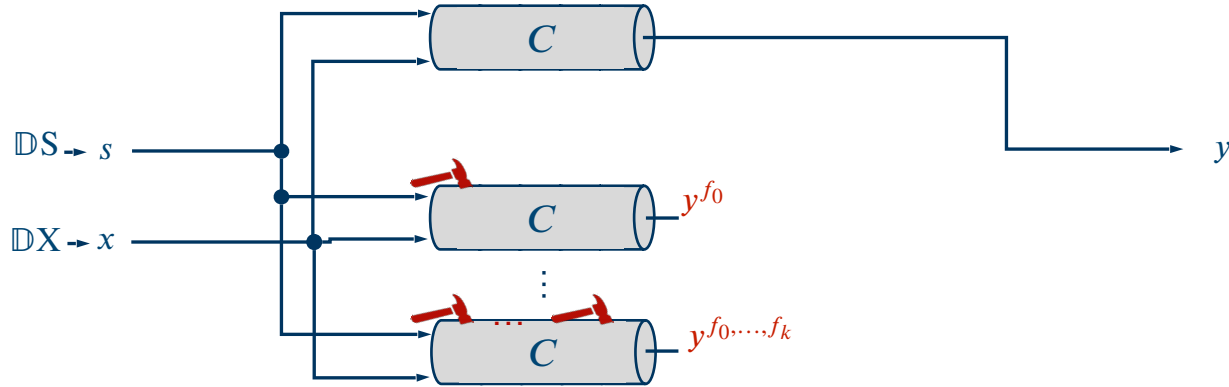


Leakage:

How many bits does an adversary learn about a secret s by observing some output y .

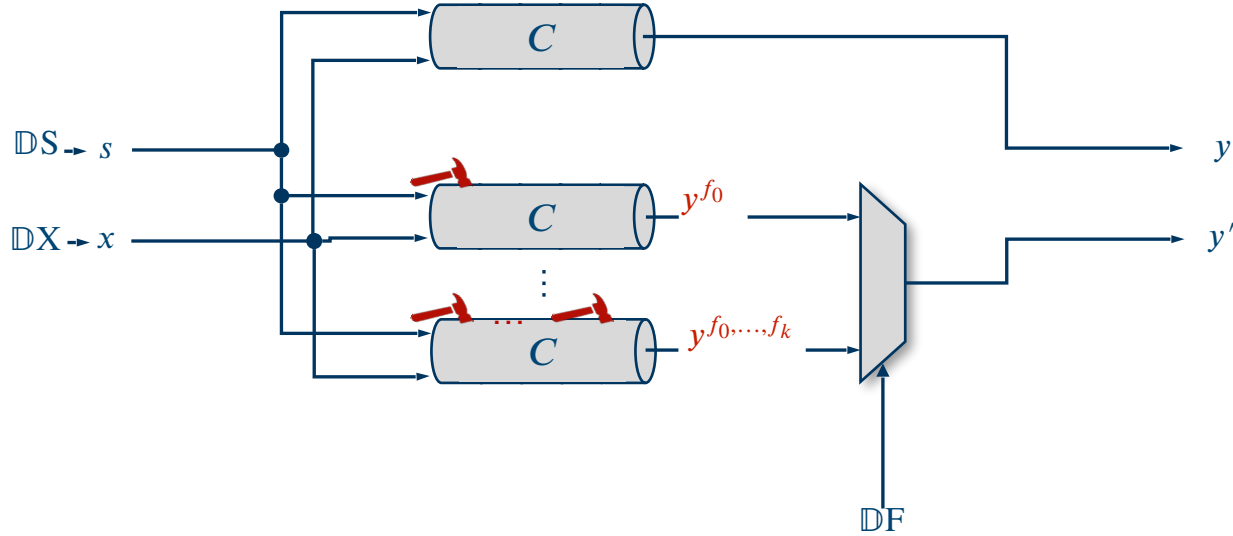
$$L[S \mid Y] = H_{\infty}[S] - H_{\infty}[S \mid Y]$$

Stateless Channels

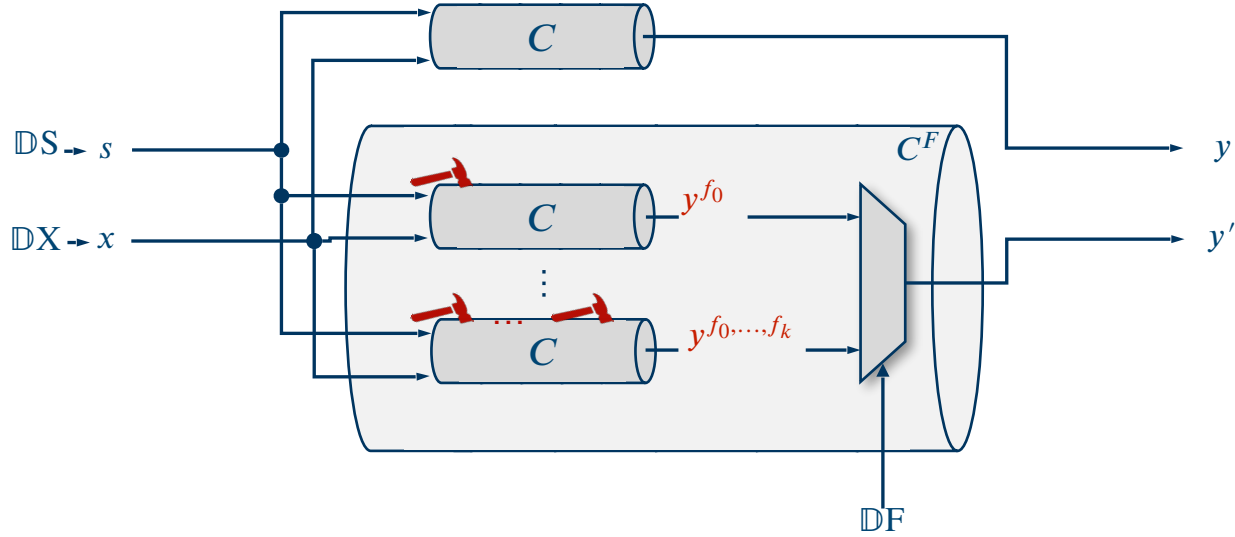


Construction

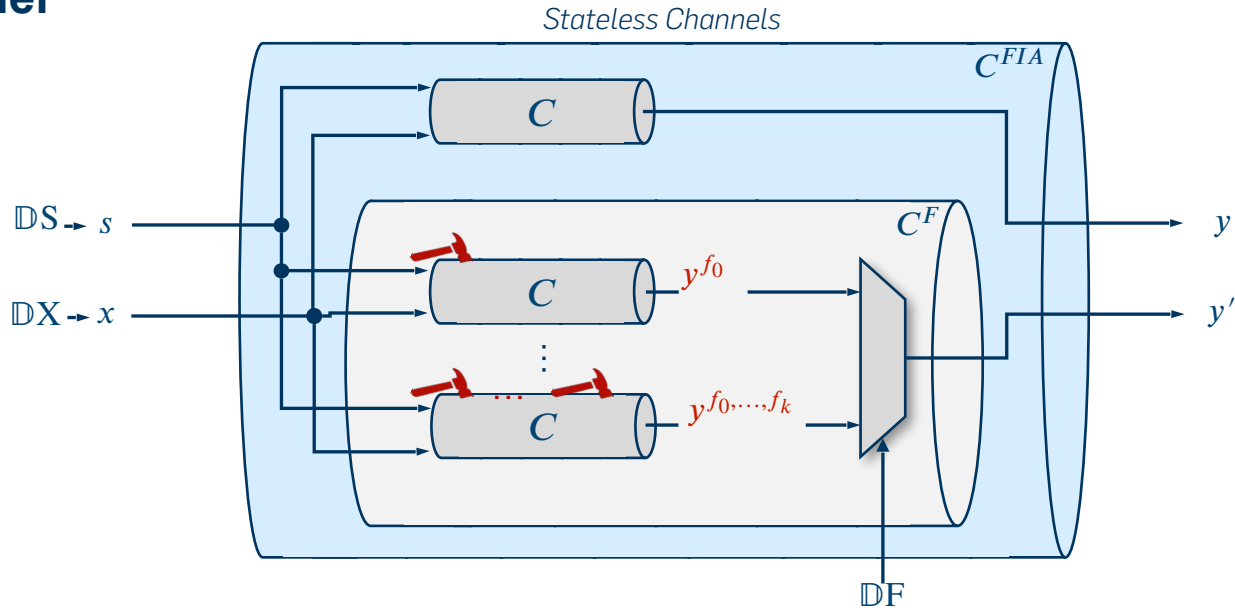
Stateless Channels



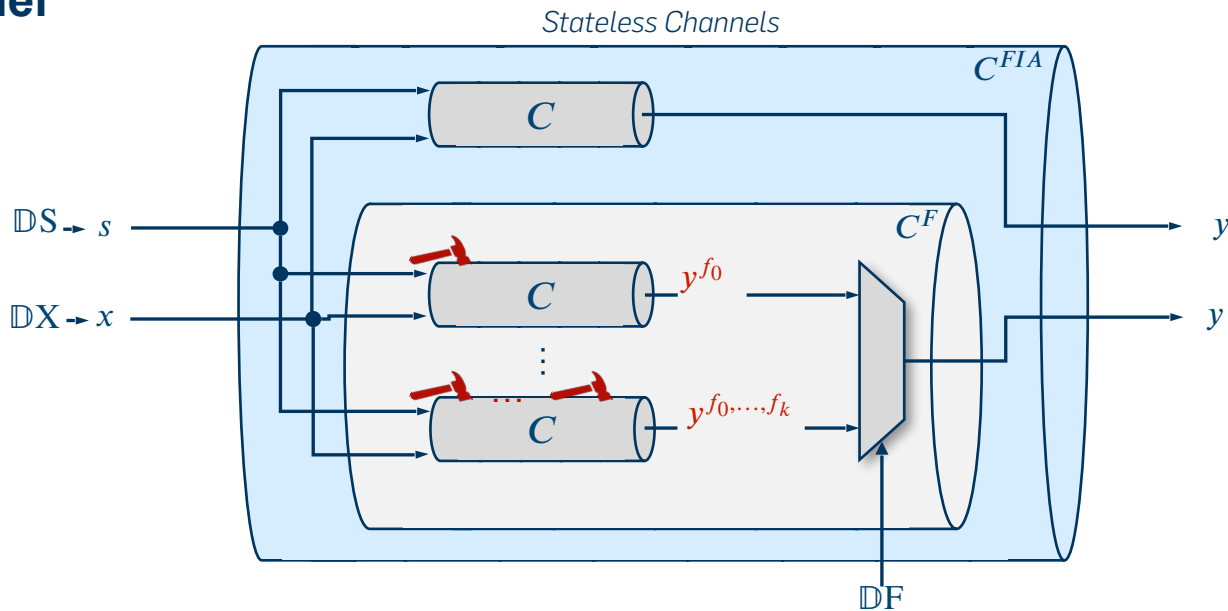
Stateless Channels



Construction

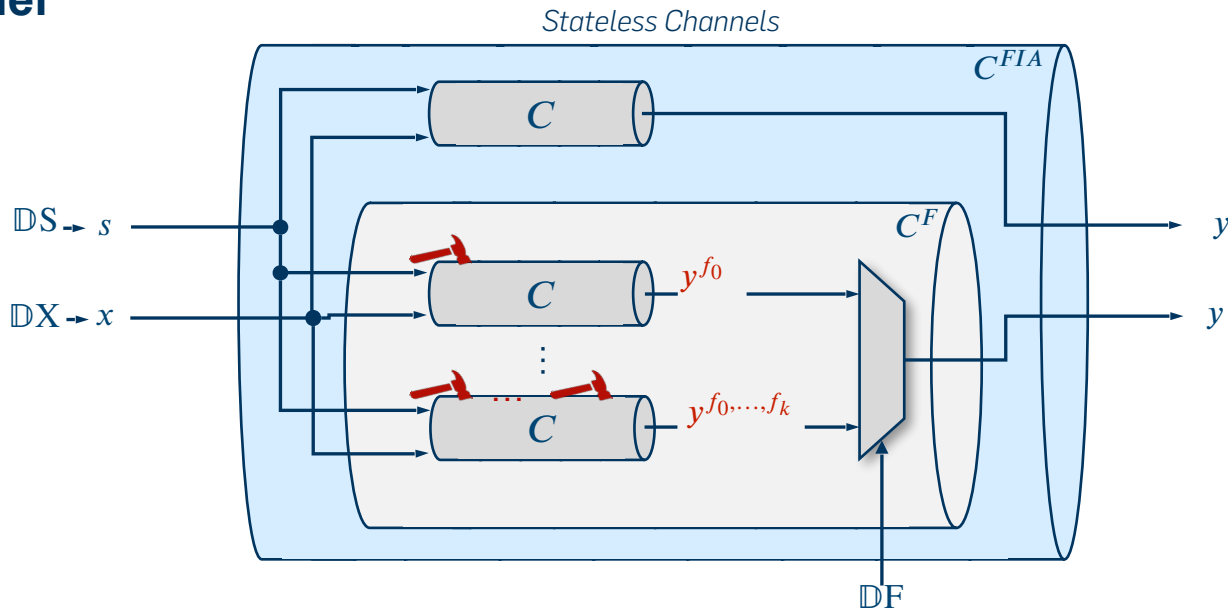


Construction



$$C_{(x,s),(y,y')}^{FIA} = C_{(x,s),y} \sum_{f \in F} \Pr[f] C_{(x,s),y'}^f$$

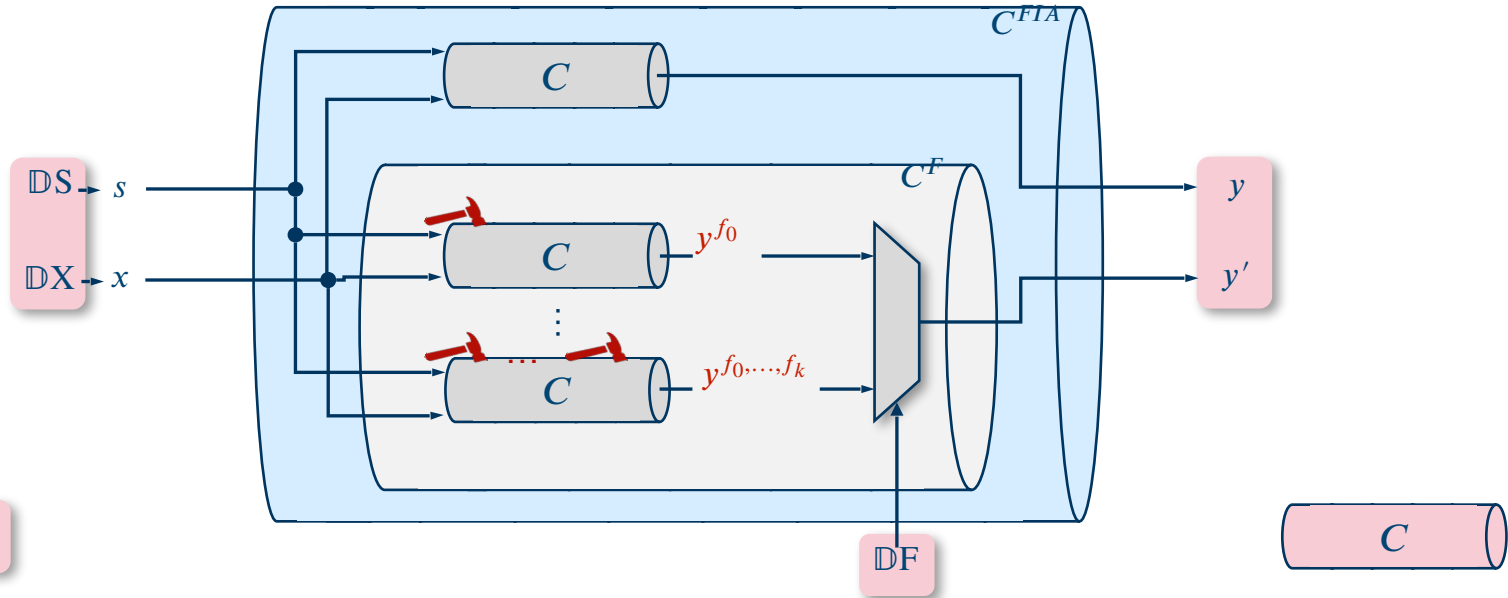
Construction



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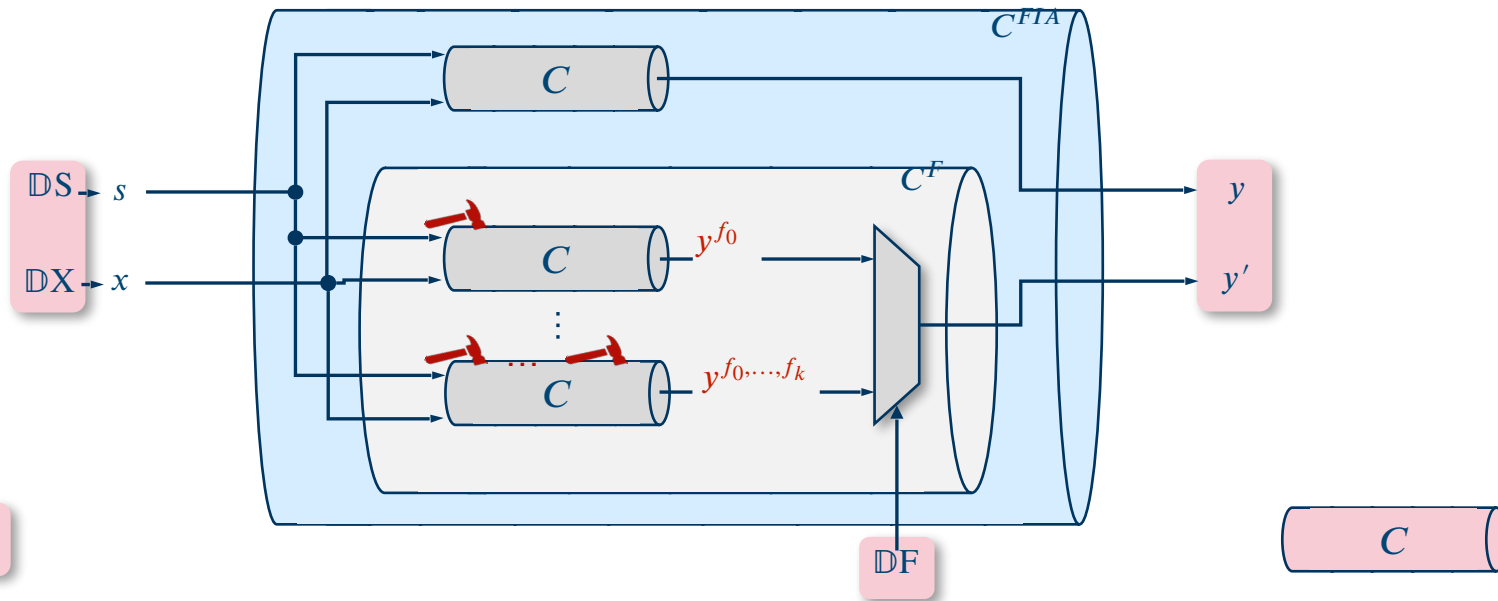
$$V[S | Y, Y'] = \sum_{y,y'} \max_s \left(\sum_x \Pr[s] \Pr[x] \Pr[y | x, s] \sum_f \Pr[f] \Pr[y' | x, s] \right)$$

Stateless Channels



View of Adv

Stateless Channels

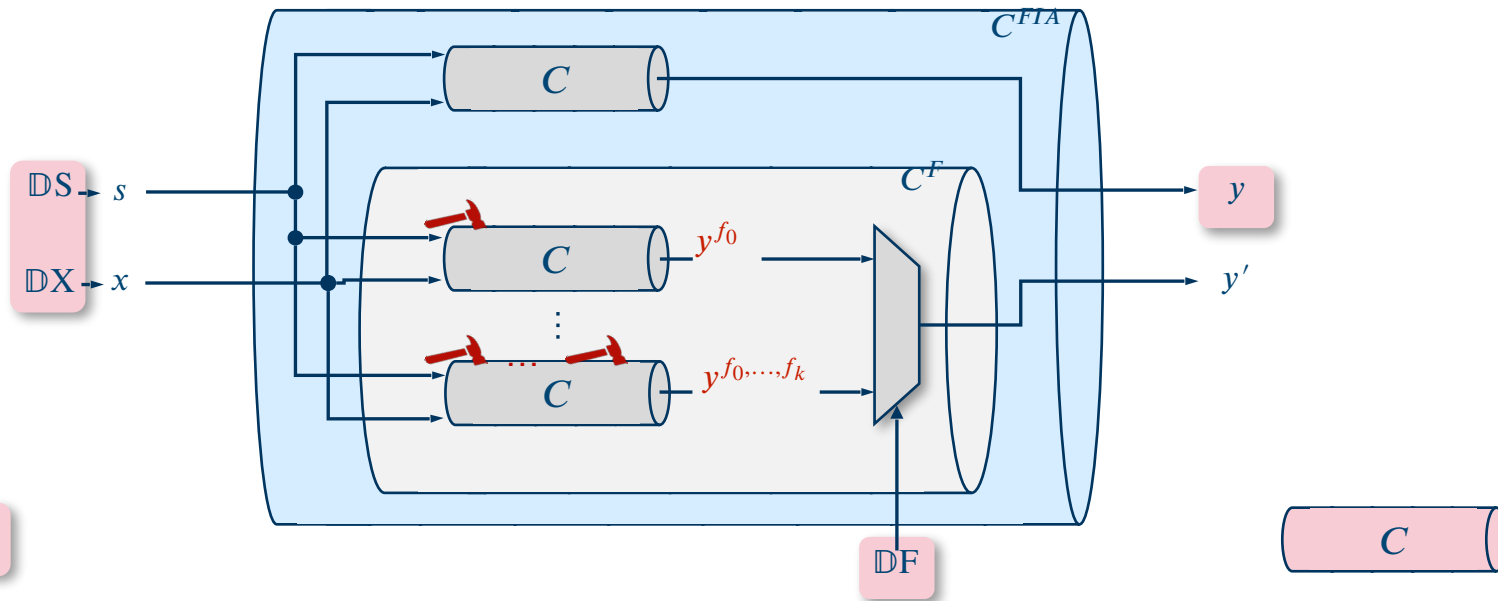


View of Adv

✓ Adv has access to pair (y, y') .

Coverage

Stateless Channels

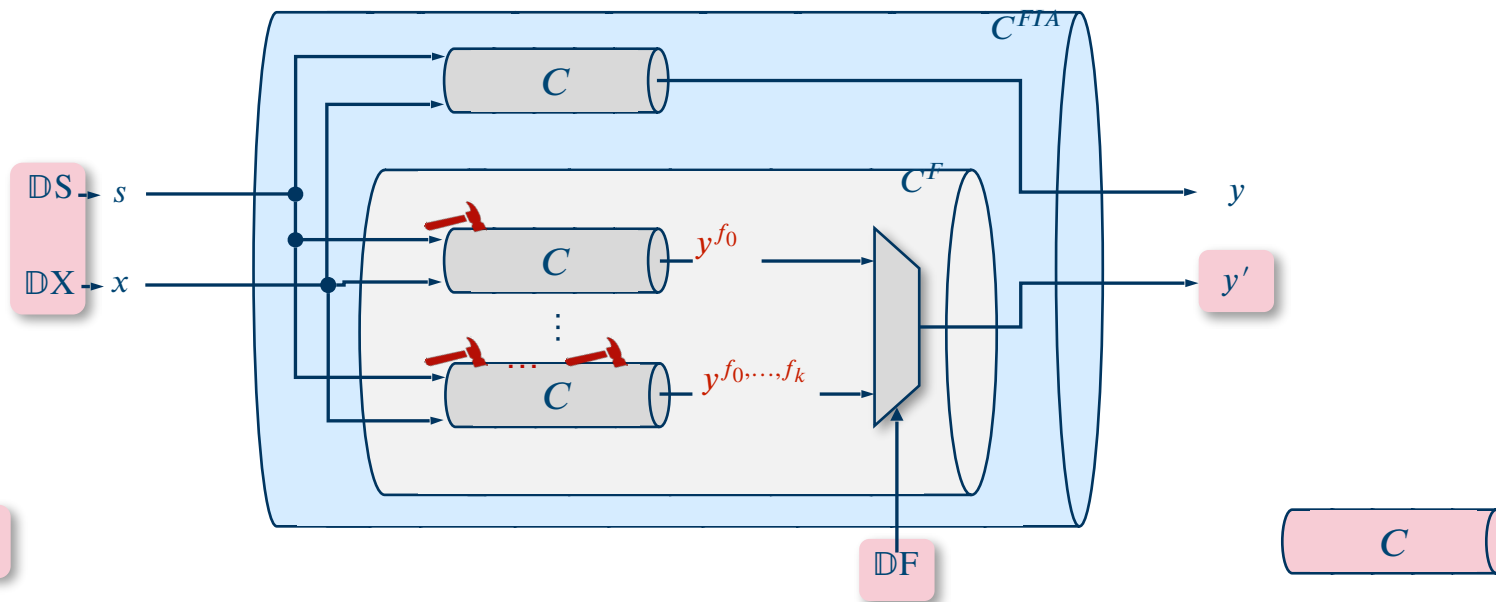


View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .

Coverage

Stateless Channels

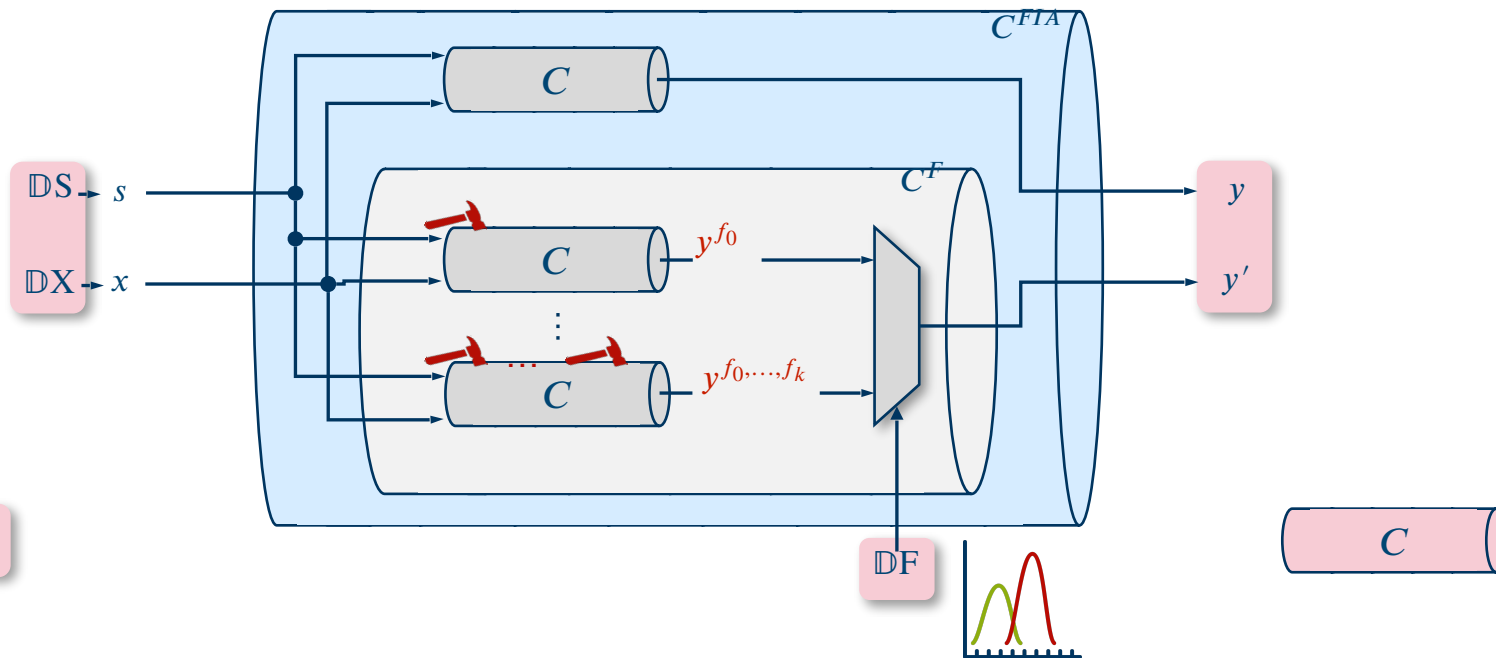


View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .

Coverage

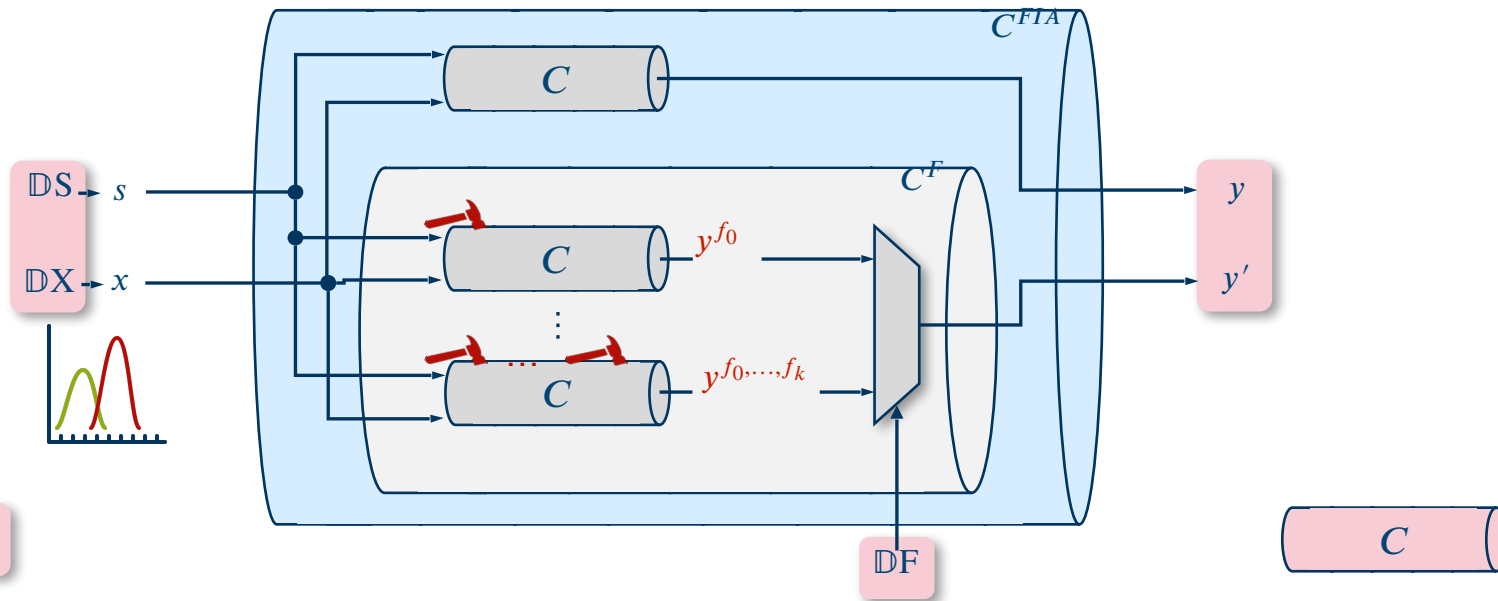
Stateless Channels



View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .
- ✓ Precise/imprecise faults.

Stateless Channels

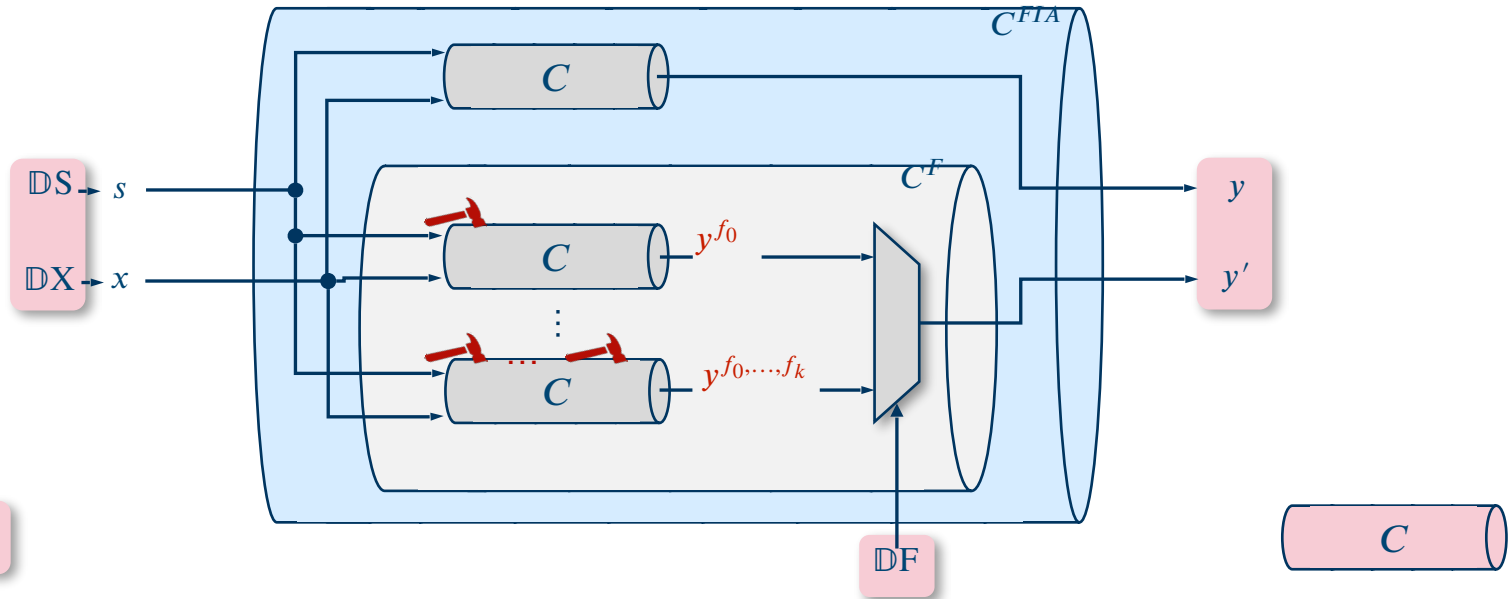


View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .
- ✓ Precise/imprecise faults.
- ✓ Known/unknown "public" input.

Coverage

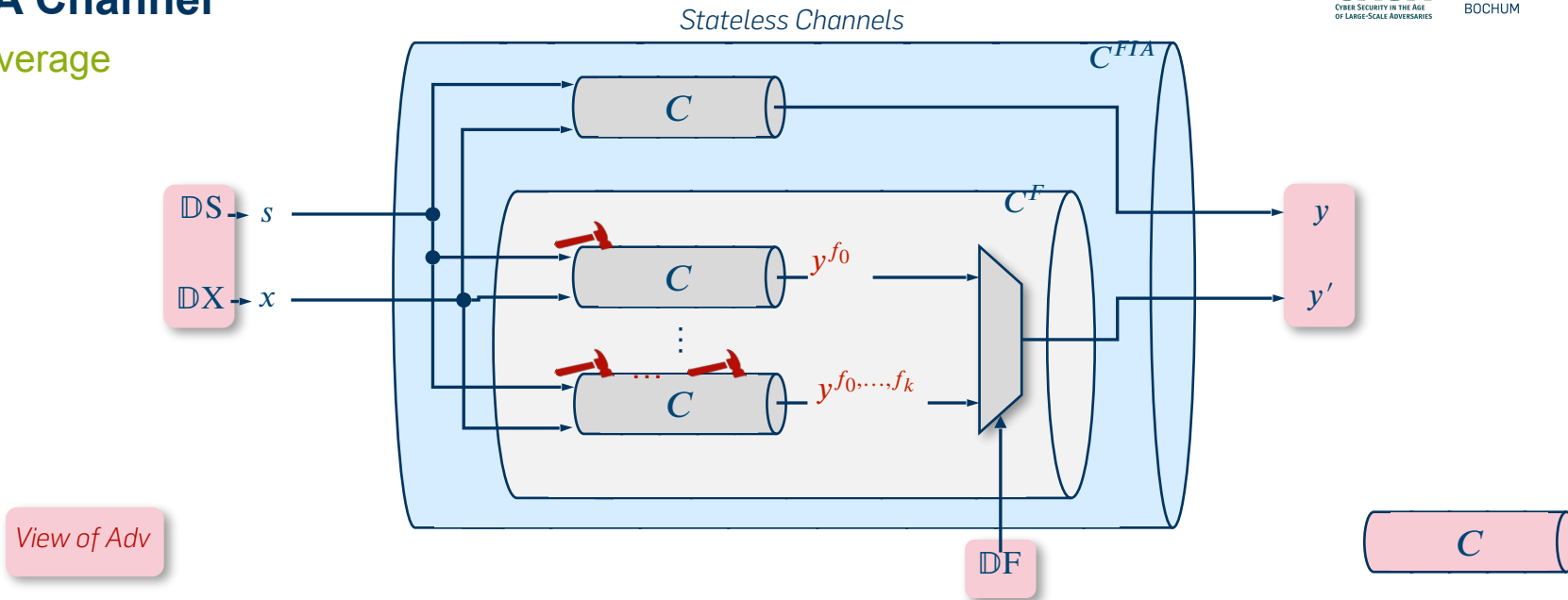
Stateless Channels



View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .
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- ✓ Known/unknown "public" input.
- ✗ Adv has access to multiple pairs (y_i, y'_i) .

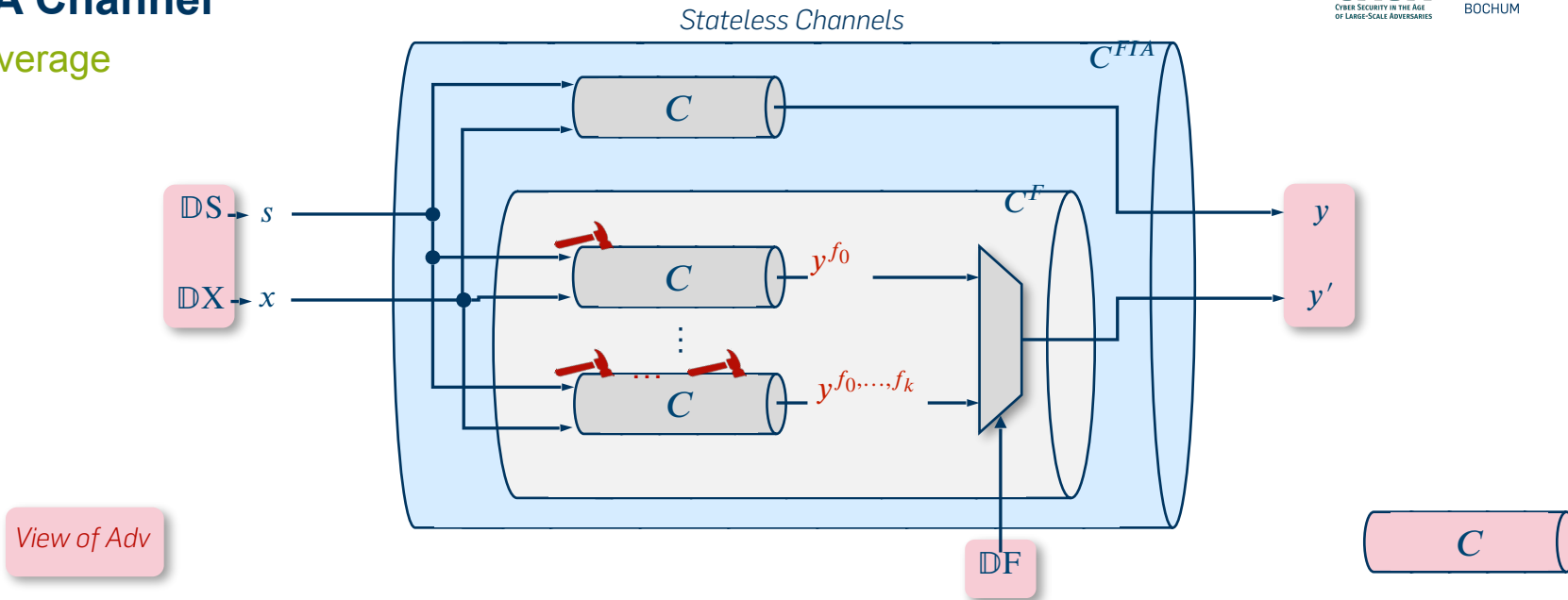
Coverage



View of Adv

- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .
- ✓ Precise/imprecise faults.
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Coverage



- ✓ Adv has access to pair (y, y') .
- ✓ Adv has access to y .
- ✓ Adv has access to y' .
- ✓ Precise/imprecise faults.
- ✓ Known/unknown “public” input.
- ✗ Adv has access to multiple pairs (y_i, y'_i) .
- ✗ Adv has access to multiple y'_i .
- ✗ Countermeasures that rely on the state of C .

Computation

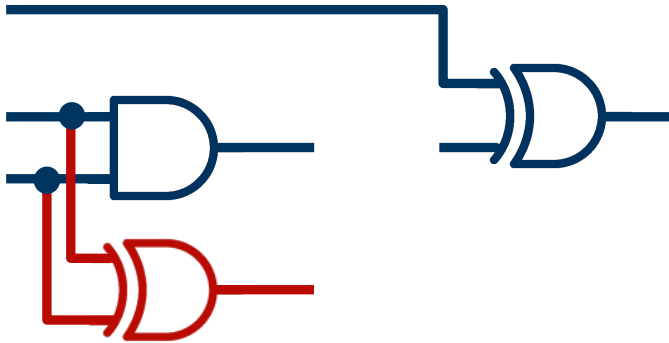
Circuit Transformation



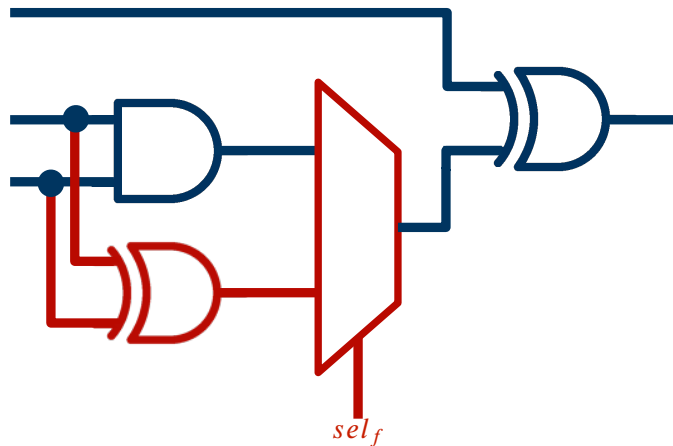
Circuit Transformation



Circuit Transformation

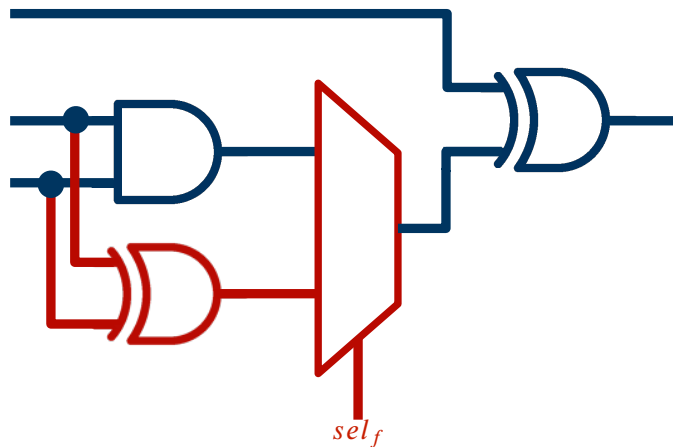


Circuit Transformation



Input signals for fault selection.

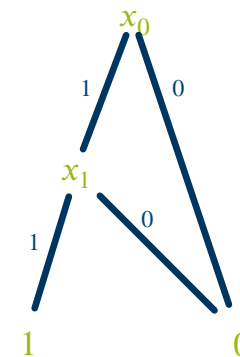
Circuit Transformation



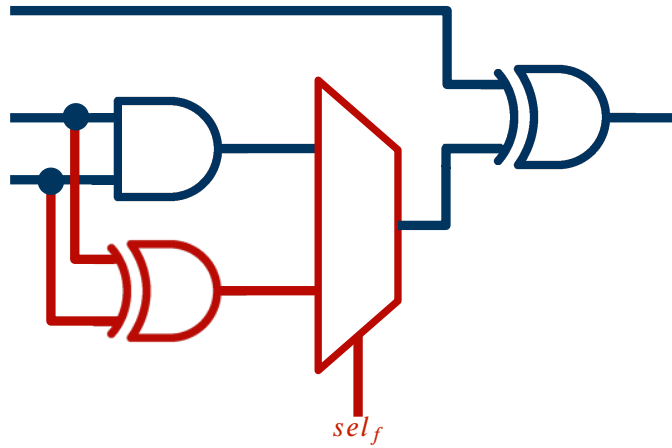
Input signals for fault selection.

Circuit as BDD

Inputs: $x_0 \wedge x_1$



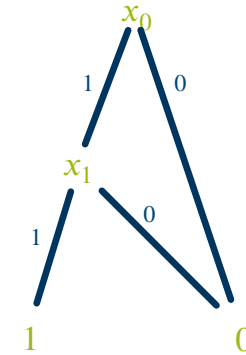
Circuit Transformation



Input signals for fault selection.

Circuit as BDD

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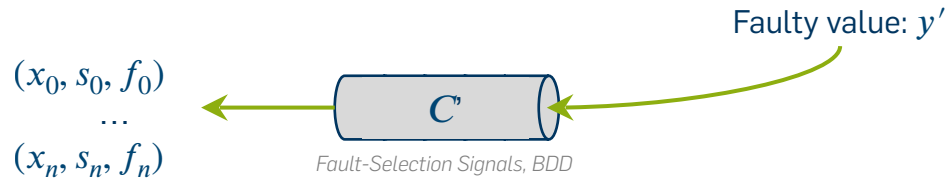


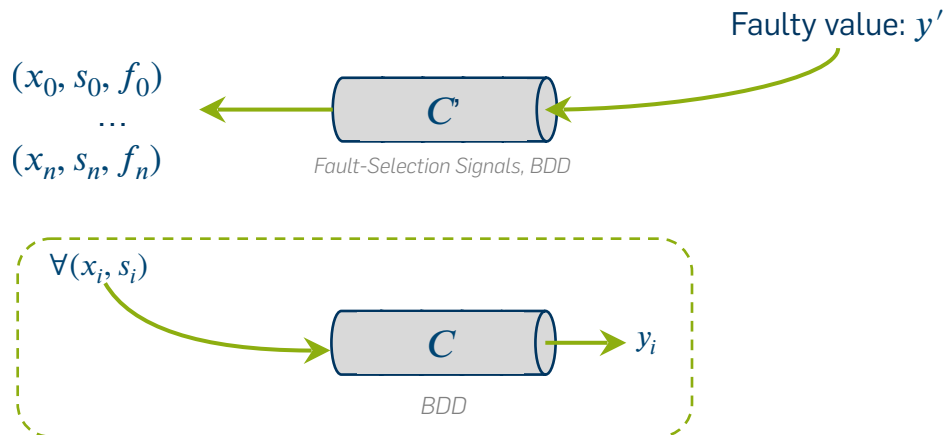
Easy retrieval of satisfying assignments.

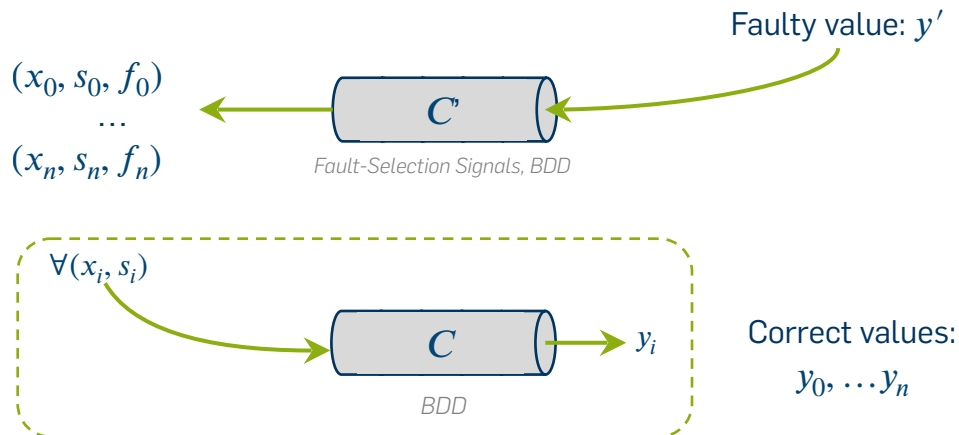
Vulnerability Computation

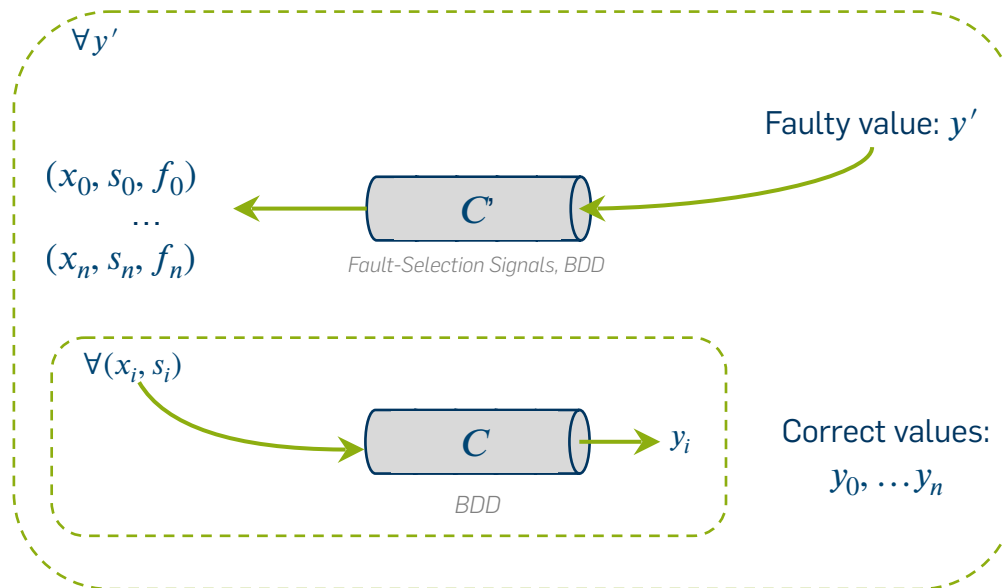
Based on BBD

Faulty value: y'



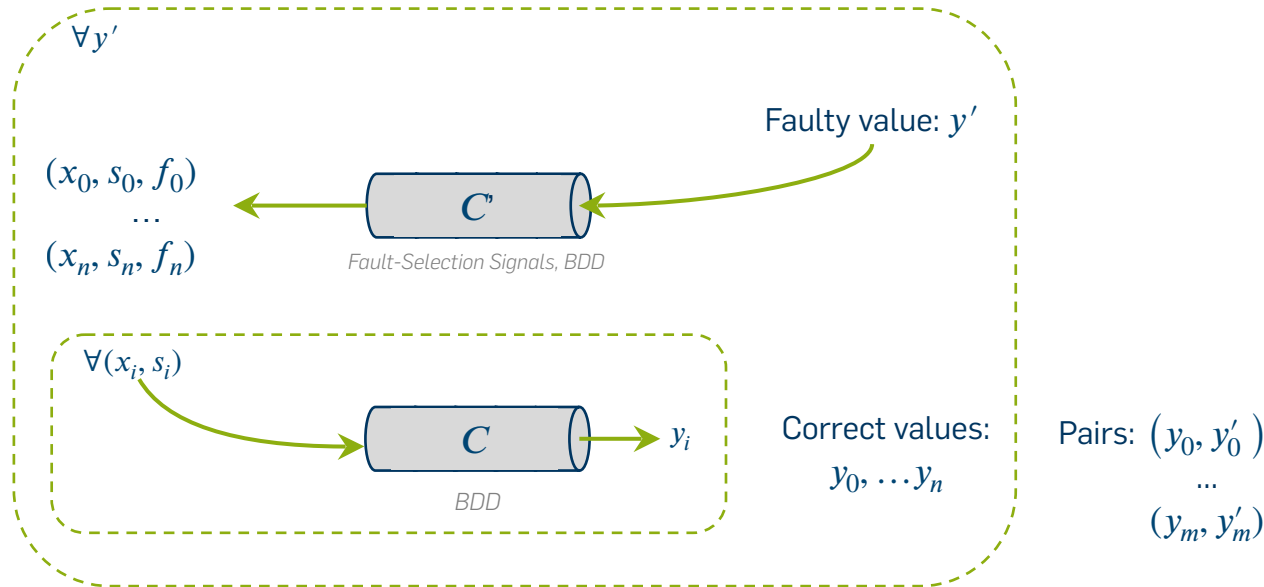






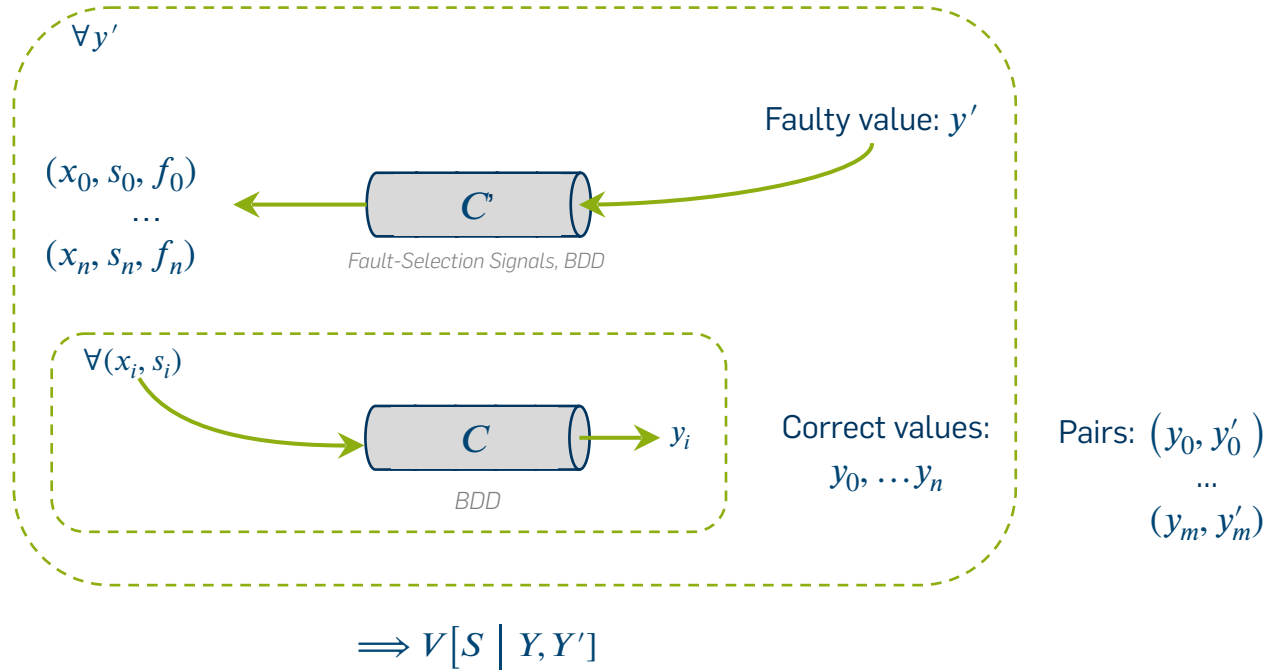
Vulnerability Computation

Based on BDD

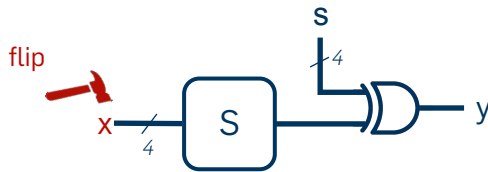


Vulnerability Computation

Based on BDD

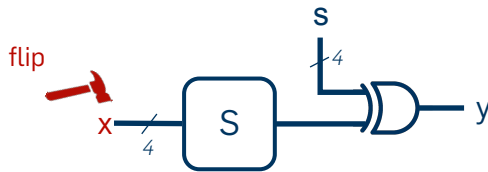


Evaluation



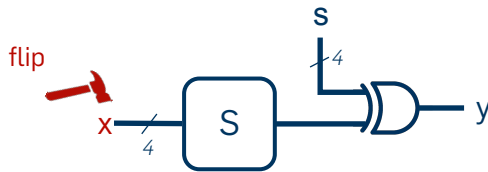
Fault	PRESENT		DEFAULT		
	location	L	Key Candidates	L	Key Candidates
-		0.000	256×16	0.000	256×16
$x_0 x_1 x_2 x_3$		2.000	256×4	0.000	256×16
x_0		2.000	256×4	1.000	256×8
$x_0 x_3$		2.585	$128 \times 2, 128 \times 4$	0.000	256×16
$x_1 x_2$		2.585	$128 \times 2, 128 \times 4$	0.000	256×16
$x_0 x_1 x_2$		2.585	$128 \times 2, 128 \times 4$	1.000	256×8
x_3		2.585	$128 \times 2, 128 \times 4$	1.000	256×8
x_1	input	2.807	$192 \times 2, 64 \times 4$	1.000	256×8
x_2		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_0 x_1$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
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$x_0 x_2 x_3$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_1 x_2 x_3$		3.000	256×2	1.000	256×8

Theoretical maximum: $L_{PRESENT}^{max} = 4, L_{DEFAULT}^{max} = 4.$



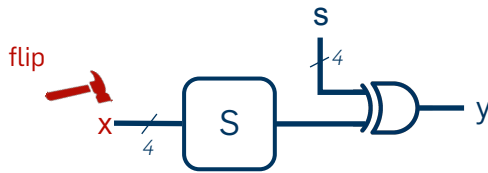
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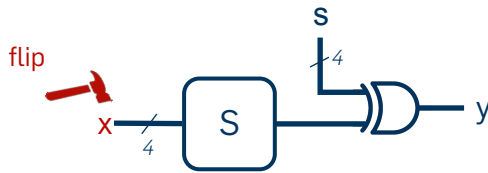
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$x_0 x_1 x_3$		2.807	192 × 2, 64 × 4	1.000	256 × 8
$x_0 x_2 x_3$		2.807	192 × 2, 64 × 4	1.000	256 × 8
$x_1 x_2 x_3$		3.000	256 × 2	1.000	256 × 8

Theoretical maximum: $L_{PRESENT}^{max} = 4$, $L_{DEFAULT}^{max} = 4$.



Fault	PRESENT		DEFAULT		
	location	L	Key Candidates	L	Key Candidates
-		0.000	256×16	0.000	256×16
$x_0 x_1 x_2 x_3$		2.000	256×4	0.000	256×16
x_0		2.000	256×4	1.000	256×8
$x_0 x_3$		2.585	$128 \times 2, 128 \times 4$	0.000	256×16
$x_1 x_2$		2.585	$128 \times 2, 128 \times 4$	0.000	256×16
$x_0 x_1 x_2$		2.585	$128 \times 2, 128 \times 4$	1.000	256×8
x_3		2.585	$128 \times 2, 128 \times 4$	1.000	256×8
x_1	input	2.807	$192 \times 2, 64 \times 4$	1.000	256×8
x_2		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_0 x_1$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_0 x_2$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_1 x_3$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_2 x_3$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_0 x_1 x_3$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_0 x_2 x_3$		2.807	$192 \times 2, 64 \times 4$	1.000	256×8
$x_1 x_2 x_3$		3.000	256×2	1.000	256×8

Theoretical maximum: $L_{PRESENT}^{max} = 4, L_{DEFAULT}^{max} = 4.$



Fault		Metric L					Correction
		Plain	Detection (both - y , δ)	Detection (no flag - y)	Detection (flag only - δ)		
location	type						
input max	x_2	set	3.000	1.000	0.954	0.000	0.000
	x_2	reset	3.000	1.000	0.954	0.000	0.000
	x_2	flip	2.807	0.000	0.000	0.000	0.000
internal max	$\text{inv}(x_1)$	set	3.000	1.000	0.954	0.000	0.000
	$\text{inv}(x_1)$	reset	3.000	1.000	0.954	0.000	0.000
	$\text{and}(x_2, \bar{x}_1)$	flip	3.000	1.000	0.954	0.000	0.000

Theoretical maximum: $L_{PRESENT}^{max} = 4$.



Fault		Metric L					Correction
		location	type	Plain	Detection (both - y, δ)	Detection (no flag - y)	
input max	x_2	set	3.000	1.000	0.954	0.000	0.000
	x_2	reset	3.000	1.000	0.954	0.000	0.000
	x_2	flip	2.807	0.000	0.000	0.000	0.000
internal max	$\text{inv}(x_1)$	set	3.000	1.000	0.954	0.000	0.000
	$\text{inv}(x_1)$	reset	3.000	1.000	0.954	0.000	0.000
	$\text{and}(x_2, \bar{x}_1)$	flip	3.000	1.000	0.954	0.000	0.000

Theoretical maximum: $L_{PRESENT}^{max} = 4.$



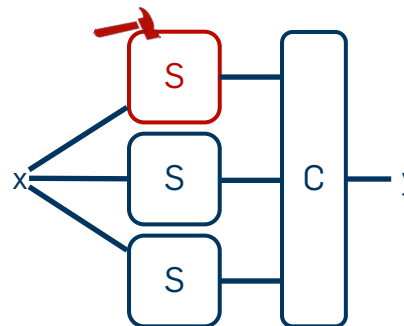
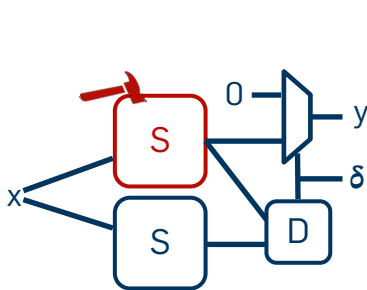
Fault		Metric L					
		location	type	Plain	Detection (both - y, δ)	Detection (no flag - y)	Detection (flag only - δ)
input max	x_2	set	3.000	1.000	0.954	0.000	0.000
	x_2	reset	3.000	1.000	0.954	0.000	0.000
	x_2	flip	2.807	0.000	0.000	0.000	0.000
internal max	$\text{inv}(x_1)$	set	3.000	1.000	0.954	0.000	0.000
	$\text{inv}(x_1)$	reset	3.000	1.000	0.954	0.000	0.000
	$\text{and}(x_2, \bar{x}_1)$	flip	3.000	1.000	0.954	0.000	0.000

Theoretical maximum: $L_{PRESENT}^{max} = 4.$



Fault			Metric L				
	location	type	Plain	Detection (both - y, δ)	Detection (no flag - y)	Detection (flag only - δ)	Correction
input max	x_2	set	3.000	1.000	0.954	0.000	0.000
	x_2	reset	3.000	1.000	0.954	0.000	0.000
	x_2	flip	2.807	0.000	0.000	0.000	0.000
internal max	$\text{inv}(x_1)$	set	3.000	1.000	0.954	0.000	0.000
	$\text{inv}(x_1)$	reset	3.000	1.000	0.954	0.000	0.000
	$\text{and}(x_2, \bar{x}_1)$	flip	3.000	1.000	0.954	0.000	0.000

Theoretical maximum: $L_{PRESENT}^{max} = 4.$

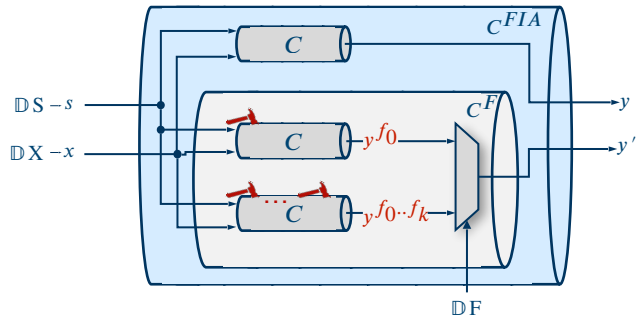


Fault		Metric L					
		location	type	Plain	Detection (both - y, δ)	Detection (no flag - y)	Detection (flag only - δ)
input max	x_2	set	3.000	1.000	0.954	0.000	0.000
	x_2	reset	3.000	1.000	0.954	0.000	0.000
	x_2	flip	2.807	0.000	0.000	0.000	0.000
internal max	$inv(x_1)$	set	3.000	1.000	0.954	0.000	0.000
	$inv(x_1)$	reset	3.000	1.000	0.954	0.000	0.000
	$and(x_2, \bar{x}_1)$	flip	3.000	1.000	0.954	0.000	0.000

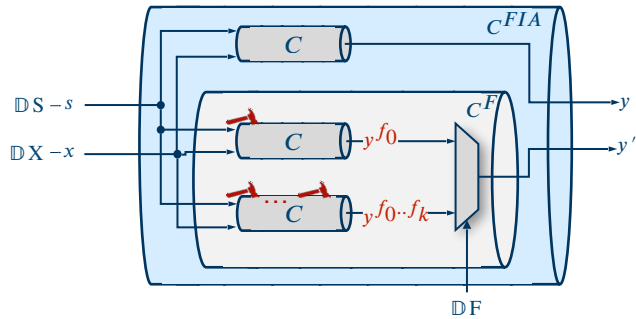
Theoretical maximum: $L_{PRESENT}^{max} = 4.$

SIFA Leakage with Independent Detection Flag
 Contradicting Hadzic et al., 2021

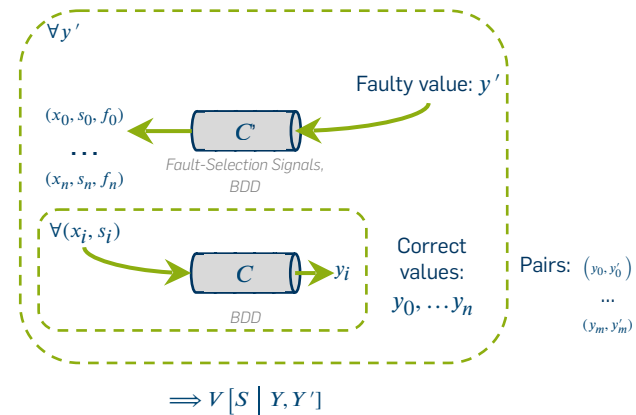
Channel for Fault Analysis

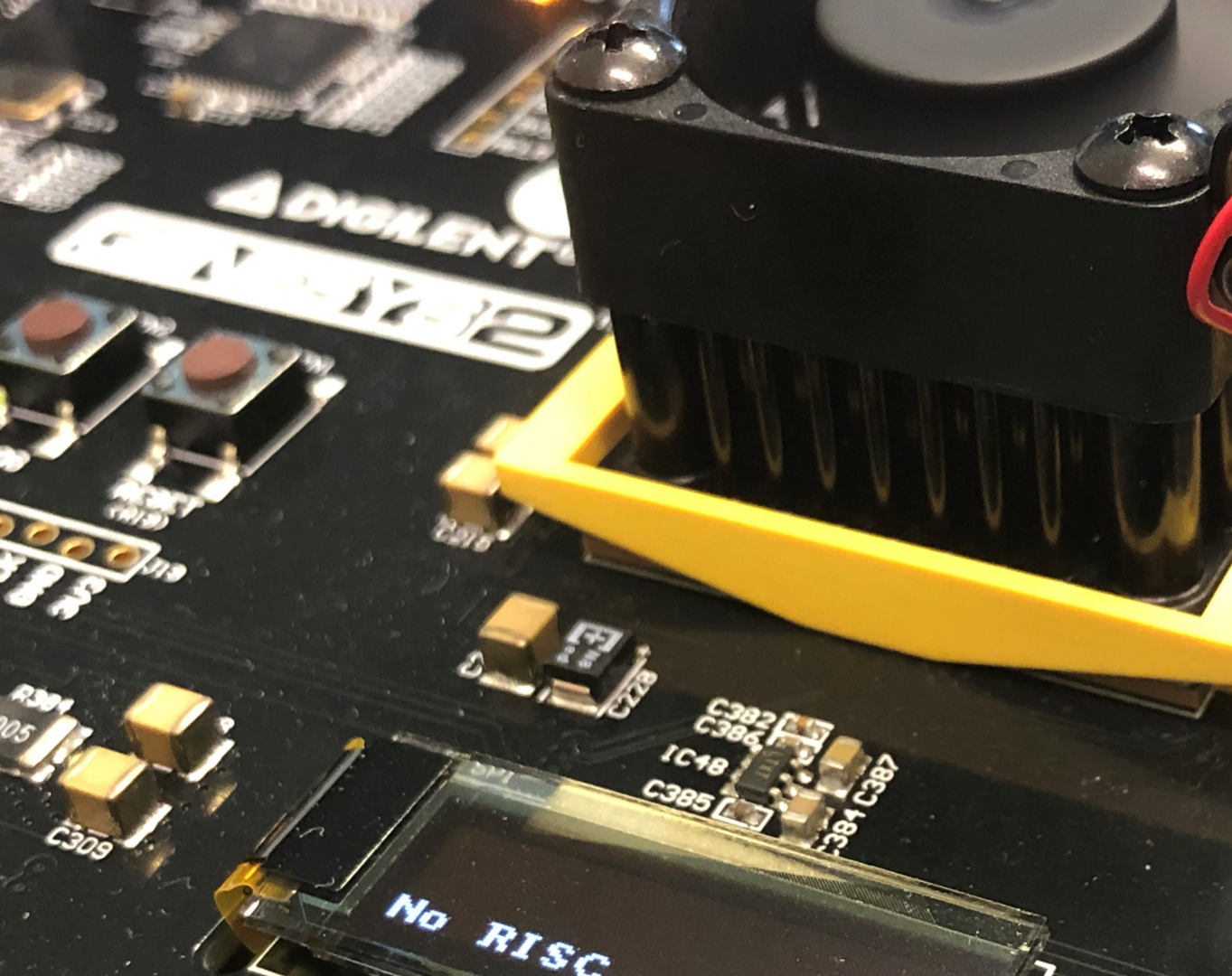


Channel for Fault Analysis



Vulnerability Computation





Thank you!



VERICA

Jakob Feldtkeller

Chair for Security Engineering
Faculty of Computer Science
Ruhr University Bochum

