

Analysis of RIPEMD-160: New Collision Attacks and Finding Characteristics with MILP

Fukang Liu^{1,2}, Gaoli Wang^{3,4}, Santanu Sarkar⁵, Ravi Anand²,
Willi Meier⁶, Yingxin Li³, Takanori Isobe^{2,7}

¹Tokyo Institute of Technology, Tokyo, Japan

²University of Hyogo, Hyogo, Japan

³East China Normal University, Shanghai, China

⁴State Key Laboratory of Cryptology, Beijing, China

⁵Indian Institute of Technology Madras, Chennai, India

⁶FHNW, Windisch, Switzerland

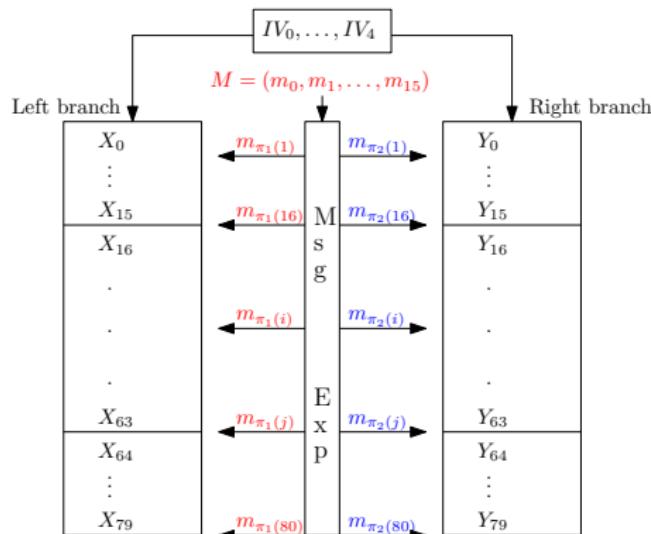
⁷NICT, Tokyo, Japan

Overview

- 1** Background
 - RIPEMD-160
 - Difficulty to Analyze RIPEMD-160
 - Finding Trails
- 2** Our MILP-based Method
 - Problem Analysis
 - Modelling
 - Application
- 3** Summary and Open Questions

RIPEMD-160

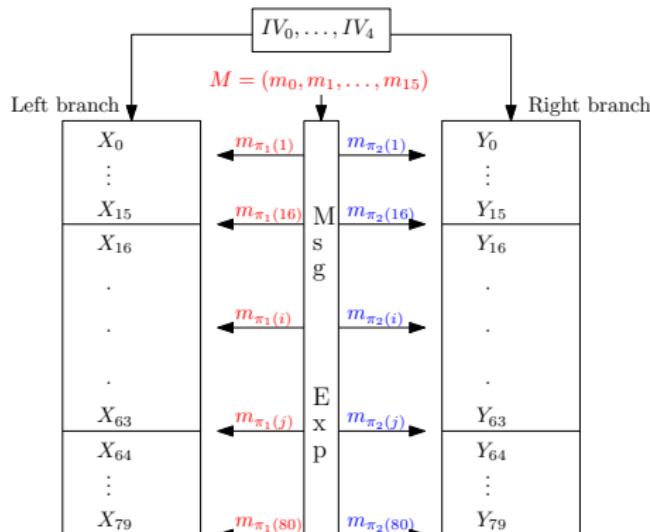
- FSE 1996 by Dobbertin et al.
- Strengthens MD5 (double branches, complex round function)
- Bitcoin address (with SHA-256)
- ISO/IEC standard



Round Function of RIPEMD-160

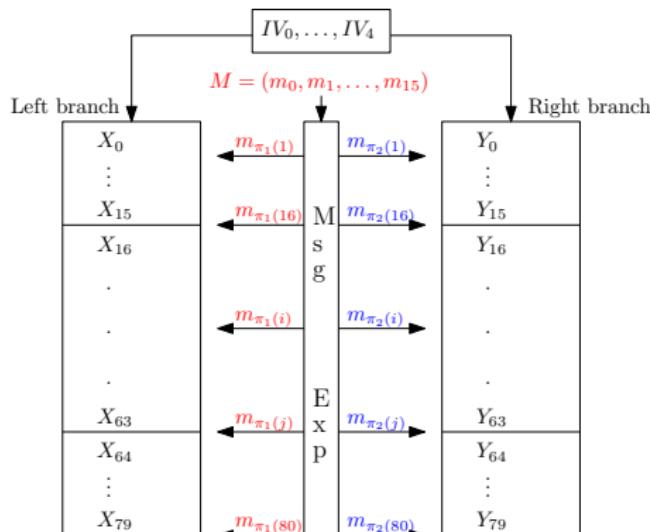
■ Round function (left branch as an example)

$$\begin{aligned} Q_i &= X_{i-5} \lll 10 \boxplus F_i(X_{i-1}, X_{i-2}, X_{i-3} \lll 10) \boxplus m_{\pi(i)} \boxplus K_i, \\ X_i &= X_{i-4} \lll 10 \boxplus Q_i \lll s_i. \end{aligned}$$



Difficulty to Analyze RIPEMD-160

- Difficulty to analyze RIPEMD-160
 - Finding valid differential trails
 - Finding conforming message pairs
 - Constructing better local collisions



Finding Trails for RIPEMD-160

- Finding valid differential trails
 - Bit conditions by the Boolean functions
 - Extra conditions on Q_i

$$(Q_i \boxplus \alpha_i) \lll s_i = Q_i \lll s_i \boxplus \beta_i,$$

where α_i, β_i are constants derived from the differential trail.

Finding Trails for RIPEMD-160

- Where are the contradictions?

- Boolean functions¹:

$$F_{i+1}(\textcolor{red}{X}_i, X_{i-1}, X_{i-2} \lll 10), \quad (1)$$

$$F_{i+2}(X_{i+1}, \textcolor{red}{X}_i, X_{i-1} \lll 10), \quad (2)$$

$$F_{i+3}(X_{i+2}, X_{i+1}, \textcolor{red}{X}_i \lll 10). \quad (3)$$

- Extra conditions on Q_i

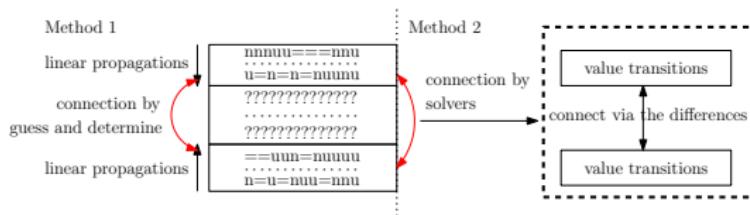
$$(Q_i \boxplus \alpha_i) \lll s_i = Q_i \lll s_i \boxplus \beta_i, \quad (4)$$

$$X_i = Q_i \lll s_i \boxplus X_{i-4} \lll 10 \quad (5)$$

¹e.g., $F(x, y, z) = ONX(x, y, z) = (x \vee \bar{y}) \oplus z$.

Finding Trails for RIPEMD-160

- Finding differential trails: guess-and-determine technique
 - Linearly propagate the difference: sparse part
 - Connect two sparse parts: dense part (**difficult!!!**)



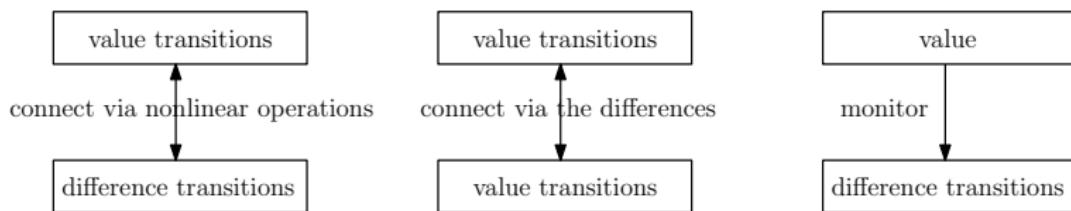
- Not open-sourced (Method 1)

- 1 But, we can still access the tools by contacting the authors.
- 2 But, **can we have an alternative choice (maybe a different approach with new potential?)** e.g. MILP/SAT/SMT solvers?
- 3 I want to have my own tool (personal interest)

Finding Trails for RIPEMD-160

■ Our method (and comparison with other methods)

- left: CRYPTO 2020 (Gimli)
- middle: SAT 2006, CRYPTO 2017 (MD4, SHA-1)
- right: ours



■ Highlight the difference

- Encode the difference transitions into the model
- Remove the expensive value transitions
- A light method (monitoring variables) to detect contradictions

Our Method

- Analysis of the target problem
 - How to describe the following difference transitions²?

$$(\nabla d_i, \nabla d_{i+1}, \nabla d_{i+2}, \nabla d_{i+3}, \nabla d_{i+4}, \nabla m) \rightarrow \nabla d_{i+5}$$

where

$$d_{i+5} = d_{i+1} \lll 10$$

$$\boxplus (F(d_{i+4}, d_{i+3}, d_{i+2} \lll 10) \boxplus (d_i \lll 10) \boxplus m \boxplus c) \lll s.$$

² ∇a : signed difference, δa : modular difference

Our Method

- Equivalent problem (bit-level)
 - How to describe the following difference transitions?

$$(\nabla a_0, \nabla a_1, \nabla a_2, \nabla a_3, \nabla a_4, \nabla m) \rightarrow \nabla a_5$$

where

$$a_5 = a_1 \boxplus (F(a_4, a_3, a_2) \boxplus a_0 \boxplus m \boxplus c) \lll s.$$

Our Method

- Introduce intermediate variables

$$\begin{aligned} b_0 &= m \boxplus c, \\ b_1 &= F(a_4, a_3, a_2), \\ b_2 &= b_0 \boxplus b_1, \\ b_3 &= b_2 \boxplus a_0, \\ b_4 &= b_3 \lll s, \\ b_5 &= a_1 \boxplus b_4, \\ a_5 &= b_5. \end{aligned}$$

- Note 1: basically, we do not need b_0 because $\nabla b_0 = \nabla m$.
- Note 2: m is a free variable

Our Method

■ Main Idea:

- Deterministically compute the signed difference transitions for $b_0 = m \boxplus c$, $b_2 = b_0 \boxplus b_1$ and $b_3 = b_2 \boxplus a_0$. Specifically, for each given $(\nabla x, \nabla y)$, uniquely compute one ∇z such that $\delta z = \delta x \boxplus \delta y$, even though there are many such possible ∇z .
- Compute the signed difference transitions for $b_1 = F(a_4, a_3, a_2)$, where F is a boolean function.
- Compute a possible value of ∇b_5 for $b_4 = b_3 \lll s$ and $b_5 = a_1 \boxplus b_4$.
- Expand ∇b_5 to get all possible ∇a_5 such that the modular differences satisfy $\delta b_5 = \delta a_5$.

Our Method

- The problems to address:

- Model $\nabla z = \nabla x \boxplus \nabla y$ where we only need to ensure $\delta z = \delta x \boxplus \delta y$.
- Model $\nabla b_1 = F(\nabla a_4, \nabla a_3, \nabla a_2)$.
- Model how to expand ∇b_5 to get all possible ∇a_5 such that the modular differences satisfy $\delta b_5 = \delta a_5$.

Describing the Signed Difference

- Three status: $\{n, u, =\}$
 - Method 1: use one ternary variable (inefficient for F^3)

$$v \in \{-1, 0, 1\}$$

- Method 2: use two binary variables (v, d)

$$(v, d) \in \{(0, 1), (1, 1), (0, 0)\},$$

where $(1, 1)$ is not allowed.

³e.g., $F(x, y, z) = ONX(x, y, z) = (x \vee \bar{y}) \oplus z$.

Modelling the Modular Addition

- Target: $\nabla z = \nabla x \boxplus \nabla y$
 - Use an intermediate variable c to represent the carry
 - No branches

Table: Propagation rules for $(\nabla x[i], \nabla y[i], \nabla c[i]) \rightarrow (\nabla z[i], \nabla c[i + 1])$

$[== \rightarrow ==]$, $[==n \rightarrow n=]$, $[==u \rightarrow u=]$, $[=n= \rightarrow n=]$,
 $[=u= \rightarrow u=]$, $[=nn \rightarrow =n]$, $[=un \rightarrow ==]$, $[=nu \rightarrow ==]$,
 $[=uu \rightarrow =u]$, $[n== \rightarrow n=]$, $[u== \rightarrow u=]$, $[n=n \rightarrow =n]$,
 $[u=n \rightarrow ==]$, $[n=u \rightarrow ==]$, $[u=u \rightarrow =u]$, $[nn= \rightarrow =n]$,
 $[nu= \rightarrow ==]$, $[un= \rightarrow ==]$, $[uu= \rightarrow =u]$, $[nnn \rightarrow nn]$,
 $[nun \rightarrow n=]$, $[unn \rightarrow n=]$, $[nnu \rightarrow n=]$, $[uun \rightarrow u=]$,
 $[unu \rightarrow u=]$, $[nuu \rightarrow u=]$, $[uuu \rightarrow uu]$

Modelling the Modular Addition

Table: Propagation rules for $(\nabla x[i], \nabla y[i], \nabla c[i]) \rightarrow (\nabla z[i], \nabla c[i + 1])$

$[== \rightarrow ==]$, $[==n \rightarrow n=]$, $[==u \rightarrow u=]$, $[=n= \rightarrow n=]$,
$[=u= \rightarrow u=]$, $[=nn \rightarrow =n]$, $[=un \rightarrow ==]$, $[=nu \rightarrow ==]$,
$[=uu \rightarrow =u]$, $[n== \rightarrow n=]$, $[u== \rightarrow u=]$, $[n=n \rightarrow =n]$,
$[u=n \rightarrow ==]$, $[n=u \rightarrow ==]$, $[u=u \rightarrow =u]$, $[nn= \rightarrow =n]$,
$[nu= \rightarrow ==]$, $[un= \rightarrow ==]$, $[uu= \rightarrow =u]$, $[nnn \rightarrow nn]$,
$[nun \rightarrow n=]$, $[unn \rightarrow n=]$, $[nnu \rightarrow n=]$, $[uun \rightarrow u=]$,
$[unu \rightarrow u=]$, $[nuu \rightarrow u=]$, $[uuu \rightarrow uu]$

Linear inequalities (with LogicFriday):

$$\mathcal{H}_{\text{ADD}} \cdot V_{\text{ADD}}^T \geq \mathcal{C}_{\text{ADD}},$$

$$V_{\text{ADD}} = (x_v[i], x_d[i], y_v[i], y_d[i], c_v[i], c_d[i], z_v[i], z_d[i], c_v[i+1], c_d[i+1]).$$

Modelling the Modular Addition

$$\mathcal{H}_{\text{ADD}} | \mathcal{C}_{\text{ADD}} = \left[\begin{array}{cccccccc|c} 0 & 1 & 0 & 1 & 0 & 1 & 0 & -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & -1 & 0 & -1 & 0 & 1 & 0 & 0 & -2 \\ 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 \\ -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 & -1 \\ 1 & 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & -1 & -1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & -1 & 1 & 0 & -1 & 0 & 0 & 0 & -1 \\ 1 & 0 & 1 & 0 & -1 & 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & -1 & 0 & 1 & 0 & -1 & 0 & -1 & 0 & 0 & -2 \\ 0 & -1 & -1 & 0 & 0 & 1 & 0 & -1 & 0 & 0 & -2 \\ 0 & 1 & 0 & -1 & 0 & -1 & 0 & -1 & 0 & 0 & -2 \\ 0 & -1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & -1 & 1 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & -1 \\ 0 & 0 & -1 & 0 & -1 & 0 & 1 & 0 & 1 & 0 & -1 \\ 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & -1 & -1 \\ 1 & -1 & 1 & -1 & 1 & 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 & -1 & 0 & -1 \\ 1 & 0 & 1 & 0 & 1 & -1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & -1 & 0 & -1 & -1 \\ -1 & 0 & 0 & 0 & -1 & 0 & 1 & 0 & 0 & 1 & -1 \\ -1 & 0 & -1 & 0 & 0 & 0 & 1 & 0 & 0 & 1 & -1 \\ 0 & 1 & -1 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & -1 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & -1 & 0 & 0 & -1 & -1 \\ -1 & 0 & 0 & 0 & 0 & 1 & 1 & -1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 & -1 & 0 & 1 & 0 & 0 & 0 & 0 \\ -1 & 0 & -1 & 0 & -1 & 0 & 0 & 0 & 1 & 1 & -2 \end{array} \right],$$

Modelling the Expansion

- Get all $\nabla \xi$ from ∇z such that $\delta \xi = \delta z$:
 - Use an intermediate variable c to represent the carry
 - Branches!!! (tree structure)

Table: Propagation rules for $(\nabla z[i], \nabla c[i]) \rightarrow (\nabla \xi[i], \nabla c[i + 1])$

$$\begin{aligned} & [\text{nn} \rightarrow \text{=n}], [\text{uu} \rightarrow \text{=u}], [\text{nu} \rightarrow \text{==}], [\text{un} \rightarrow \text{==}], \\ & [\text{n=} \rightarrow (\text{n=}, \text{un})], [\text{u=} \rightarrow (\text{u=}, \text{nu})], \\ & [\text{=n} \rightarrow (\text{n=}, \text{un})], [\text{=u} \rightarrow (\text{u=}, \text{nu})], \\ & [\text{==} \rightarrow \text{==}] \end{aligned}$$

Modelling the Boolean Function

- Example: $\nabla w = ONX(\nabla x, \nabla y, \nabla z)$ where

$$ONX(x, y, z) = (x \vee \bar{y}) \oplus z.$$

- List all possible cases!!!

Table: Valid values of $(\nabla x[i], \nabla y[i], \nabla z[i], \nabla w[i])$

[====],
[==u=], [==uu], [==un], [==n=], [==nn], [==nu],
[=n==], [=n=n], [=n=u], [=u==], [=u=u], [=u=n],
[n==u], [n==n], [u==n], [u==u],
[=nn=], [=uu=], [=nun], [=nuu], [=unn], [=unu],
[nn=u], [nn==], [nu=u], [nu==], [uu=n], [uu==], [un=n], [un==],
[n=nu], [n=n=], [n=uu], [n=u=], [u=nn], [u=n=], [u=un], [u=u=],
[nnnu], [nnu=], [nun=], [unnn], [uun=], [unu=], [nuuu], [uuun].

Detecting Contradictions in F

- Example: $\nabla w = ONX(\nabla x, \nabla y, \nabla z)$

- Introduce variables (x, y, z) representing the values into the model
- Each possible $(\nabla x, \nabla y, \nabla z, \nabla w)$ will impose certain bit conditions on (x, y, z) .
- List all possible cases.

Table: Valid values of $(\nabla x[i], \nabla y[i], \nabla z[i], \nabla w[i], x[i], y[i], z[i])$

[=====, *, *, *, *],
[==u=, *, 1, *, [==uu, 1, 0, *, [==un, 0, 0, *, [==n=, *, 1, *, [==nn, 1, 0, *, [==nu, 0, 0, *,
[=n==, *, *, 0], [=n=n, 0, *, 1], [=n=u, 1, *, 1], [=u==, *, *, 0], [=u=u, 0, *, 1], [=u=n, 1, *, 1],
[n==u, *, 1, *], [n==u, *, 0, 0], [n==n, *, 0, 1], [u==n, *, 1, *], [u==n, *, 0, 0], [u==u, *, 0, 1],
[=nn=, *, *, *, *], [=uu=, *, *, *, *], [=nun, 0, *, *, *], [=nuu, 1, *, *, *], [=unn, 1, *, *, *], [=unu, 0, *, *, *],
[nn=u, *, *, 0], [nn==, *, *, 1], [nu=u, *, *, 0], [nu==, *, *, 1], [uu=n, *, *, 0], [uu==, *, *, 1],
[un=n, *, *, 0], [un==, *, *, 1],
[n=nu, *, 1, *], [n=n=, *, 0, *], [n=uu, *, 1, *], [n=u=, *, 0, *], [u=nn, *, 1, *], [u=n=, *, 0, *],
[u=un, *, 1, *], [u=u=, *, 0, *],
[nnnu, *, *, *, *], [nnu=, *, *, *, *], [nun=, *, *, *, *], [unnn, *, *, *, *], [uun=, *, *, *, *], [unu=, *, *, *, *],
[nuuu, *, *, *, *], [uuun, *, *, *, *].

Detecting Contradictions in Q

- How to avoid contradictions between a_5 and a_1 ?
 - Modelling the following 3 conditions is sufficient ($\delta q = \delta b_4$)

$$\begin{aligned} q &= a_5 \boxplus a_1, \\ (\delta q \boxplus q)[0] &= (\delta b_3 \boxplus q \ggg s)[32 - s], \\ (\delta q \boxplus q)[s] &= (\delta b_3 \boxplus q \ggg s)[0]. \end{aligned}$$

Other Details

- Many other minor details (see the paper)
 - Model $b_4 = b_3 \lll s$ and $b_5 = a_1 \boxplus b_4$
 - A different way to model the expansion
 - Many optional parameters to control the searching strategies
(e.g. where to detect the contradictions)

The Differential Trail for 36-Round RIPEMD-160

Table 9: The 36-round differential characteristic, where $\delta m_0 = 2^3 \boxplus 2^{22}$, $\delta m_6 = 0 \boxplus 2^{15} \boxplus 2^{28}$ and $\delta m_9 = 2^2 \boxplus 2^{15}$.

The Differential Trail for 36-Round RIPEMD-160

Table 10: A partial solution for the 36-round differential characteristic

New Progress

Questions quickly arising:

- Is the technique really useful or efficient? (Other targets like SHA-2?)
- Can it beat ad-hoc dedicated tools? (evidence?)

Our new work⁴:

- The first practical collisions for 40-round RIPEMD-160
- The first practical SFS collisions for 39-round SHA-256
(previous record: 38 rounds at EC 2013 by Mendel et al.)

⁴New Records in Collision Attacks on RIPEMD-160 and SHA-256 (eprint 2023/285)

Summary

- Alternative methods to find trails for the MD-SHA hash family
- Further improve the efficiency?
- More applications? (SHA-256, SHA-512...)

https://github.com/LFKOKAMI/Find_RIPEMD_Trail