# On the Semidirect Discrete Logarithm Problem in Finite Groups

Analysis of a candidate problem in post-quantum cryptography

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### Outline

- 1. Introduction to SDLP
- 2. Reduction to Simple Groups
- 3. Simple Groups Analysis
- 4. Linear Groups Analysis
- 5. Sporadic Groups

# Introduction to SDLP

### Semidirect Product

Let G be a finite group and Aut(G) its group of automorphisms. We define  $G \rtimes Aut(G)$  to be the group of pairs in  $G \times Aut(G)$  equipped with the following multiplication:

 $(g,\phi)(h,\psi) := (g\phi(h),\phi\circ\psi)$ 

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# Definitions

#### $ho_{{\mathcal G},\phi}$

Fix 
$$(g,\phi) \in G 
times Aut(G)$$
. Define  $ho_{g,\phi}: G 
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### SDLP

Fix  $G \rtimes Aut(G)$  and a pair  $(g, \phi)$ . Suppose we are given  $\rho_{g,\phi}^{x}(1_{G})$  for some  $x \in \mathbb{Z}$ . The Semidirect Discrete Logarithm Problem is to recover x.

- Natural; outside the mainstream; feasibly post-quantum
- Turns out semidirect product cryptography can be described via commutative group actions\*
- Commutative group actions give us Diffie-Hellman-style key exchanges (NIKEs)<sup>†</sup>, and digital signatures<sup>‡</sup>
- Recent fast algorithms for SDLP in certain classes of group  ${}^{\$}$

<sup>\*</sup>B. et al. 2023a.

<sup>&</sup>lt;sup>†</sup>Habeeb et al. 2013.

<sup>&</sup>lt;sup>‡</sup>B. et al. 2023b.

<sup>&</sup>lt;sup>§</sup>Mendelsohn et al. 2023; Imran and Ivanyos 2024.

# Reduction to Simple Groups

# Intuition



### Imran and Ivanyos 2024, Theorem 3

Consider SDLP with respect to a pair  $(g, \phi) \in G \rtimes Aut(G)$ . Given a  $\phi$ -invariant normal subgroup N of G, the solutions of SDLP are a linear combination of solutions of an instance of SDLP in G/N and an instance of SDLP in N.

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- Our contribution: reduce an arbitrary instance of SDLP in a finite group to instances of SDLP in simple groups, then solve those with the Classification. Requires a couple of (justified) computational group theory oracles.
- To complete the reduction need to compute invariant subgroups and check the recursion terminates.

# Computing the Invariant Subgroup



**Figure 1:** The  $\phi$ -invariant subgroup cannot be smaller than the characteristic subgroup.

- Suppose we can compute a maximal normal subgroup of *G*, say *N*.
- Imran and Ivanyos 2024 show that the intersection

# $N \cap \phi(N) \cap \ldots \cap \phi^i(N) \cap \ldots$

stabilises with a  $\phi$ -invariant subgroup<sup>a</sup>

- The algorithm doesn't terminate in the trivial subgroup if *N* contains a characteristic subgroup *C* (see left)
- We show there is a characteristic subgroup if and only if *every* maximal normal subgroup contains a characteristic subgroup.

<sup>&</sup>lt;sup>a</sup>No proof that this is not the trivial subgroup.

# Characteristically Simple Groups



Figure 2: An automorphism of S<sup>3</sup>.

- Well-known that groups with no characteristic subgroups (characteristically simple groups) are exactly of the form S<sup>k</sup> for some simple group S.
- We show the algorithm for computing  $\phi$ -invariant normal subgroups terminates in the identity exactly when  $G = S^k$  and  $\phi$  acts transitively on these components.
- In turn this gives us  $k^2$  SDLP instances in *S* to solve.

# Recursion to (Characteristically) Simple Groups

At each step of the recursion if the  $\phi$ -invariant subgroup algorithm outputs trivial subgroup, call a simple/characteristically simple SDLP solver on that group.

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Correspondence theorem: the subgroups of G/N are of the form N'/N where  $N \subset N' \triangleleft G$ ; and  $(G/N)/(N'/N) \cong G/N'$ 



Figure 3: A recursion tree whose nodes are simple or characteristically simple.

Simple Groups Analysis

# Simple Groups

**Theorem (Classification of Finite Simple Groups)** Every finite simple group is isomorphic to a member of one of four infinite classes:

- 1. the cyclic groups of prime order,
- 2. the alternating groups of degree at least 5,
- 3. the classical groups of Lie type,
- 4. the exceptional groups of Lie type

or one of 26 groups called the sporadic groups.

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### Corollary

The Semidirect Discrete Logarithm Problem (SDLP) in any finite group is **not a secure assumption** for quantum resistant primitives.

Let G be a cyclic group of prime order, then for any  $g \in G$  and  $\phi \in Aut(G)$  we have  $\phi(g) = g^a$  for some  $a \in \mathbb{N}$ , so:

$$\mathsf{s}_{g,\phi(x)} = g\phi(g)\cdots\phi^{x}(g) = g\cdot g^{a}\cdots g^{a^{x}} = g^{\sum_{i=0}^{x}a^{i}}$$

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With a Quantum Computer we can recover

$$\sum_{i=0}^{x} a^{i} = \frac{a^{x+1} - 1}{a - 1}$$

then use again it again to solve SDLP.

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Linear Groups Analysis

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Given vectors  $\mathbf{a}, \mathbf{b} \in V$  and a matrix  $\mathbf{T} \in GL(V)$  find  $x \in \mathbb{N}$  such that:

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**Nice Fact:** Thanks to Kannan and Lipton 1986 the problem can be reduced to a discrete logarithm over GL(W) for W subspace of V. Result: We can do the same for projective linear groups  $G \leq \mathbb{P}GL$ .

### Theorem (Kohl 2003)

If G is a non-abelian finite simple group, then for all  $\phi \in Aut(G)$ there exists an integer  $x \leq \log_2 |G|$  such that  $\phi^x \in Inn(G)$ .

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**Memo:** by Imran and Ivanyos 2024, we can solve SDLP( $G, \phi$ ) by solving most y instances of SDLP( $G, \phi^y$ ).

#### Consequence

We can limit ourselves to solve SDLP for inner authormorphism, i.e. conjugations.

# Simple Groups

**Theorem (Classification of Finite Simple Groups)** Every finite simple group is isomorphic to a member of one of four infinite classes:

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- 3. the classical groups of Lie type, <- Linear
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Like for DLOG with division over  $\mathbb{Z}/p\mathbb{Z}$ , this <u>do not directly</u> implies that SDLP is broken.

# Constructive Recognition Problem

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Since Lie groups and alternating groups are defined as (projective) linear groups the SDLP reduces to the following:

### Constructive Recognition Problem, Babai and Beals 1999

Given a simple black-box group *G*, the problem require to find a computationally efficient isomorphism between *G* and an explicitly defined simple group.
**Theorem (Classification of Finite Simple Groups)** Every finite simple group is isomorphic to a member of one of four infinite classes:

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  - use number theory oracles
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- 3.2 solved for any BBG, up to DLOG in Borovik and Yalçınkaya 2020
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 $G_2(q), q \ge 3; F_4(q); E_6(q); {}^2E_6(q); {}^3D_4(q); E_7(q); E_8(q)$ 

 $^{2}B_{2}(2^{2n+1}), n \ge 1; {}^{2}G_{2}(3^{2n+1}), n \ge 1; {}^{2}F_{4}(2^{2n+1}), n \ge 1$ 

or one of 26 groups called the **sporadic groups** and  ${}^{2}F_{4}(2)'$ .

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In Kantor and Magaard 2013 and 2015 reduce the problem to  $\mathbb{P}SL(2, q)$ , using number theory oracles.

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\*solved if q is odd

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1. The largest of the 26 *sporadic* groups is the Fischer-Griess monster group M of cardinality:

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 $\approx 2^{179.07}$ 

There are 26 finite simple groups:

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2. of the remaining 19 (+ 1) are part of the *happy family*, i. e., they are subquotients of M,

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- 2. of the remaining 19 (+ 1) are part of the *happy family*, i. e., they are subquotients of M,
- 3. the other are referred as the six pariahs, and have cardinality  $\leq 2^{67}$

1. **Result:** Baby-Step Giant-Step algorithm can be adapted to SDLP, cutting the bit security of M to 89.6;

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- 2. Actually if *G* is a sporadic group clearly we can restrict without loss of generality to

$$X \leq \max_{g \in G} (\operatorname{ord}(g)) \cdot \max_{\phi \in \operatorname{Aut}(G)} (\operatorname{ord}(\phi)) =: b(G);$$

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3. For M we have  $b(G) = 119^2 \approx 2^{14}$ ;

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- 4. For G in the happy family  $b(G) \le 2 \cdot 119^2 \approx 2^{15}$ ;

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- 3. For M we have  $b(G) = 119^2 \approx 2^{14}$ ;
- 4. For G in the happy family  $b(G) \le 2 \cdot 119^2 \approx 2^{15}$ ;
- 5. For G one of the six pariahs  $b(G) = 67^2 \approx 2^{13}$ ;

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#### Meme



# Thank you for your attention! eprint.iacr.org/2024/905

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## Additional Material

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We can solve it via computing a composition series:

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However, this branch of literature typically wishes to achieve much stronger results and are thwarted by DLOG computation - we do not impose this limitation since we assume QCs.

 if we know the particular structure of the group G, we can use it to construct for any subgroup S the smallest normal subgroup containing (S<sup>G</sup>) in linear time, as explained in Babai et al. 1991.

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- 2. Use Imran and Ivanyos 2024, but requires that every non-Abelian composition factor of *G* possesses a faithful small permutation representation;
- 3. Otherwise, with Babai and Beals 1999 and a QC we can find  $G_1 \leq G$ , with  $G/G_1$ :

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  - 3.1 simple and nonabelian, so  $G_1$  is Maximal Normal Subgroup;
  - 3.2 or abelian, so we can use point 1 to get the maximal normal subgroup  $A_1 \triangleleft G/G_1^{\P}$  and  $A_1G_1$  will be a maximal normal in G by the correspondence theorem.

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Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(G) = SGS^{-1}$ , then:

 $\overline{\mathsf{S}_{\mathsf{G},\phi}(x)} = \mathbf{G} \cdot \mathsf{S}\mathsf{G}\mathsf{S}^{-1} \cdot \mathsf{S}^2 \mathsf{G}\mathsf{S}^{-2} \cdots \mathsf{S}^{x-1} \mathsf{G}\mathsf{S}^{-x+1} \cdot \mathsf{S}^x \mathsf{G}\mathsf{S}^{-x} =$ 

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$$s_{\mathbf{G},\phi}(x) = \mathbf{G} \cdot \mathbf{S}\mathbf{G}\mathbf{S}^{-1} \cdot \mathbf{S}^2 \mathbf{G}\mathbf{S}^{-2} \cdots \mathbf{S}^{x-1} \mathbf{G}\mathbf{S}^{-x+1} \cdot \mathbf{S}^x \mathbf{G}\mathbf{S}^{-x} =$$

#### SDLP on Matrix Groups (Imran and Ivanyos 2024)

Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(G) = SGS^{-1}$ , then:

$$s_{G,\phi}(x) = \mathbf{G} \cdot \mathbf{S}\mathbf{G}\mathbf{S}^{-1} \cdot \mathbf{S}^{2}\mathbf{G}\mathbf{S}^{-2} \cdots \mathbf{S}^{x-1}\mathbf{G}\mathbf{S}^{-x+1} \cdot \mathbf{S}^{x}\mathbf{G}\mathbf{S}^{-x} =$$
$$= \mathbf{G}\mathbf{S} \cdot \mathbf{G}\mathbf{S} \cdot \mathbf{G}\mathbf{S} \cdots \mathbf{S}\mathbf{G} \cdot \mathbf{S}^{-x} = (\mathbf{G}\mathbf{S})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x}$$
Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(\overline{G}) = SGS^{-1}$ , then:

$$s_{\mathbf{G},\phi}(x) = \mathbf{G} \cdot \mathbf{S}\mathbf{G}\mathbf{S}^{-1} \cdot \mathbf{S}^{2}\mathbf{G}\mathbf{S}^{-2} \cdots \mathbf{S}^{x-1}\mathbf{G}\mathbf{S}^{-x\pm 1} \cdot \mathbf{S}^{x}\mathbf{G}\mathbf{S}^{-x} =$$
$$= \mathbf{G}\mathbf{S} \cdot \mathbf{G}\mathbf{S} \cdot \mathbf{G}\mathbf{S} \cdots \mathbf{S}\mathbf{G} \cdot \mathbf{S}^{-x} = (\mathbf{G}\mathbf{S})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x}$$

$$\operatorname{vec}(s_{\mathbf{G},\phi}(x)) = \operatorname{vec}((\mathbf{GS})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x})$$

Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(\overline{G}) = SGS^{-1}$ , then:

$$s_{G,\phi}(x) = G \cdot SGS^{-1} \cdot S^2 GS^{-2} \cdots S^{x-1}GS^{-x \pm 1} \cdot S^x GS^{-x} =$$
  
= GS \cdot GS \cdot GS \cdot SG \cdot S^{-x} = (GS)^x \cdot G \cdot S^{-x}

$$\operatorname{vec}(s_{\mathbf{G},\phi}(x)) = \operatorname{vec}\left((\mathbf{GS})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x}\right)$$
$$= \operatorname{vec}\left((\mathbf{GS}) \cdot (\mathbf{GS})^{x-1} \cdot \mathbf{G} \cdot \mathbf{S}^{-(x-1)} \cdot \mathbf{S}^{-1}\right)$$

Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(\overline{G}) = SGS^{-1}$ , then:

$$s_{G,\phi}(x) = G \cdot SGS^{-1} \cdot S^{2}GS^{-2} \cdots S^{x-1}GS^{-x+1} \cdot S^{x}GS^{-x} =$$
  
= GS \cdot GS \cdot GS \cdot SG \cdot S^{-x} = (GS)^{x} \cdot G \cdot S^{-x}

$$\operatorname{vec}(s_{G,\phi}(x)) = \operatorname{vec}\left((GS)^{x} \cdot G \cdot S^{-x}\right)$$
$$= \operatorname{vec}\left((GS) \cdot (GS)^{x-1} \cdot G \cdot S^{-(x-1)} \cdot S^{-1}\right)$$
$$= \operatorname{vec}\left((GS) \cdot s_{G,\phi}(x-1) \cdot S^{-1}\right)$$

Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(G) = SGS^{-1}$ , then:

$$s_{G,\phi}(x) = G \cdot SGS^{-1} \cdot S^2 GS^{-2} \cdots S^{x-1}GS^{-x \pm 1} \cdot S^x GS^{-x} =$$
  
= GS \cdot GS \cdot GS \cdot SG \cdot S^{-x} = (GS)^x \cdot G \cdot S^{-x}

$$\operatorname{vec}(s_{G,\phi}(x)) = \operatorname{vec}\left((GS)^{x} \cdot G \cdot S^{-x}\right)$$
$$= \operatorname{vec}\left((GS) \cdot (GS)^{x-1} \cdot G \cdot S^{-(x-1)} \cdot S^{-1}\right)$$
$$= \operatorname{vec}\left((GS) \cdot s_{G,\phi}(x-1) \cdot S^{-1}\right)$$
$$= \left[(GS) \otimes S^{-1}\right] \operatorname{vec}(s_{G,\phi}(x-1))$$

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$$\operatorname{vec}(s_{\mathbf{G},\phi}(x)) = \operatorname{vec}\left((\mathbf{GS})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x}\right)$$
$$= \operatorname{vec}\left((\mathbf{GS}) \cdot (\mathbf{GS})^{x-1} \cdot \mathbf{G} \cdot \mathbf{S}^{-(x-1)} \cdot \mathbf{S}^{-1}\right)$$
$$= \operatorname{vec}\left((\mathbf{GS}) \cdot \mathbf{s}_{\mathbf{G},\phi}(x-1) \cdot \mathbf{S}^{-1}\right)$$
$$= \left[(\mathbf{GS}) \otimes \mathbf{S}^{-1}\right] \operatorname{vec}(\mathbf{s}_{\mathbf{G},\phi}(x-1))$$
$$= \operatorname{repeating the argument} x - 1 \text{ more times}$$

Consider  $G \leq GL_n(\mathbb{F})$  and  $\phi \in Inn(G)$  such that  $\phi(\overline{G}) = SGS^{-1}$ , then:

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$$\operatorname{vec}(s_{\mathbf{G},\phi}(x)) = \operatorname{vec}\left((\mathbf{GS})^{x} \cdot \mathbf{G} \cdot \mathbf{S}^{-x}\right)$$
$$= \operatorname{vec}\left((\mathbf{GS}) \cdot (\mathbf{GS})^{x-1} \cdot \mathbf{G} \cdot \mathbf{S}^{-(x-1)} \cdot \mathbf{S}^{-1}\right)$$
$$= \operatorname{vec}\left((\mathbf{GS}) \cdot s_{\mathbf{G},\phi}(x-1) \cdot \mathbf{S}^{-1}\right)$$
$$= \left[(\mathbf{GS}) \otimes \mathbf{S}^{-1}\right] \operatorname{vec}(s_{\mathbf{G},\phi}(x-1))$$
$$...repeating the argument x - 1 more times...$$
$$= \left[(\mathbf{GS}) \otimes \mathbf{S}^{-1}\right]^{x} \operatorname{vec}(\mathbf{G})$$