On the Semidirect Discrete Logarithm Problem in Finite Groups

Analysis of a candidate problem in post-quantum cryptography

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- 5. [Sporadic Groups](#page-44-0)

[Introduction to SDLP](#page-2-0)

Semidirect Product

Let *G* be a finite group and *Aut*(*G*) its group of automorphisms. We define $G \rtimes Aut(G)$ to be the group of pairs in $G \times Aut(G)$ equipped with the following multiplication:

 $(g, \phi)(h, \psi) := (g\phi(h), \phi \circ \psi)$

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(g,\phi)(h,\psi):=(g\phi(h),\phi\circ\psi)
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Definitions

$\rho_{g, \phi}$

Fix
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(g, \phi) \in G \rtimes \text{Aut}(G)
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. Define $\rho_{g,\phi} : G \to G$ by

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\rho_{g,\phi}(h) = g\phi(h)
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We have seen that

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SDLP

Fix *G* \times *Aut*(*G*) and a pair (g,ϕ). Suppose we are given $\rho_{g,\phi}^{\chi}(1_{G})$ for some *x ∈* Z. The Semidirect Discrete Logarithm Problem is to recover *x*.

- Natural; outside the mainstream; feasibly post-quantum
- Turns out semidirect product cryptography can be described via commutative group actions*
- Commutative group actions give us Diffie-Hellman-style key exchanges (NIKEs)† , and digital signatures‡
- Recent fast algorithms for SDLP in certain classes of group[§]

^{*}B. et al. [2023a.](#page-57-0)

 $[†]$ Habeeb et al. [2013.](#page-58-0)</sup>

[‡]B. et al. [2023b.](#page-57-1)

[§]Mendelsohn et al. [2023;](#page-59-0) Imran and Ivanyos [2024.](#page-58-1)

[Reduction to Simple Groups](#page-8-0)

Intuition

Imran and Ivanyos [2024](#page-58-1), Theorem 3

Consider SDLP with respect to a pair $(g, \phi) \in G \rtimes Aut(G)$. Given a *ϕ*-invariant normal subgroup *N* of *G*, the solutions of SDLP are a linear combination of solutions of an instance of SDLP in *G/N* and an instance of SDLP in *N*.

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• Our contribution: reduce an arbitrary instance of SDLP in a finite group to instances of SDLP in simple groups, then solve those with the Classification. Requires a couple of (justified) computational group theory oracles.

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- Our contribution: reduce an arbitrary instance of SDLP in a finite group to instances of SDLP in simple groups, then solve those with the Classification. Requires a couple of (justified) computational group theory oracles.
- To complete the reduction need to compute invariant subgroups and check the recursion terminates.

Computing the Invariant Subgroup

Figure 1: The *ϕ*-invariant subgroup cannot be smaller than the characteristic subgroup.

- Suppose we can compute a maximal normal subgroup of *G*, say *N*.
- Imran and Ivanyos [2024](#page-58-1) show that the intersection

N ∩ *ϕ*(*N*) ∩ ... ∩ $\phi^{i}(N)$ ∩ ...

stabilises with a *ϕ*-invariant subgroup*^a*

- The algorithm doesn't terminate in the trivial subgroup if *N* contains a characteristic subgroup *C* (see left)
- We show there is a characteristic subgroup if and only if *every* maximal normal subgroup contains a characteristic subgroup.

*^a*No proof that this is not the trivial subgroup.

Characteristically Simple Groups

Figure 2: An automorphism of S^3 .

- Well-known that groups with no characteristic subgroups (characteristically simple groups) are exactly of the form *S k* for some simple group *S*.
- We show the algorithm for computing *ϕ*-invariant normal subgroups terminates in the identity exactly when $G = S^k$ and ϕ acts transitively on these components.
- In turn this gives us *k* ² SDLP instances in *S* to solve.

Recursion to (Characteristically) Simple Groups

At each step of the recursion if the *ϕ*-invariant subgroup algorithm outputs trivial subgroup, call a simple/characteristically simple SDLP solver on that group.

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Correspondence theorem: the subgroups of *G/N* are of the form *N ′/N* $W \subset N' \triangleleft G$; and $(G/N)/(N'/N) \cong G/N'$

Figure 3: A recursion tree whose nodes are simple or characteristically simple.

[Simple Groups Analysis](#page-18-0)

Simple Groups

Theorem (Classification of Finite Simple Groups) Every finite simple group is isomorphic to a member of one of four infinite classes:

- 1. the cyclic groups of prime order,
- 2. the alternating groups of degree at least 5,
- 3. the classical groups of Lie type,
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or one of 26 groups called the sporadic groups.

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The Semidirect Discrete Logarithm Problem (SDLP) in any finite group is not a secure assumption for quantum resistant primitives. Let *G* be a cyclic group of prime order, then for any *g ∈ G* and *ϕ ∈* Aut(*G*) we have *ϕ*(*g*) = *g a* for some *a ∈* N, so:

$$
\mathsf{s}_{g,\phi(\mathsf{x})} = g\phi(g) \cdots \phi^\mathsf{x}(g) = g \cdot g^a \cdots g^{a^\mathsf{x}} = g^{\sum_{i=0}^\mathsf{x} a^i}
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$$

With a Quantum Computer we can recover

$$
\sum_{i=0}^{x} a^{i} = \frac{a^{x+1} - 1}{a - 1}
$$

then use again it again to solve SDLP.

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[Linear Groups Analysis](#page-24-0)

Matrix Power Problem

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Nice Fact: Thanks to Kannan and Lipton [1986](#page-59-1) the problem can be reduced to a discrete logarithm over GL(*W*) for *W* subspace of *V*. Result: We can do the same for projective linear groups *G ≤* PGL.

Theorem (Kohl [2003\)](#page-59-2)

If *G* is a non-abelian finite simple group, then for all *ϕ ∈* Aut(*G*) $\mathsf{there\ exists\ an\ integer}\ x \leq \mathsf{log}_2|\mathsf{G}| \text{ such that } \phi^\mathsf{x} \in \mathsf{Inn}(\mathsf{G}).$

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Memo: by Imran and Ivanyos [2024,](#page-58-1) we can solve SDLP(*G, ϕ*) by solving most *y* instances of SDLP(*G, ϕ^y*).

Consequence

We can limit ourselves to solve SDLP for inner authormorphism, i.e. conjugations.

Simple Groups

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- 3. the classical groups of Lie type, <- Linear
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Like for DLOG with division over Z*/p*Z, this do not directly implies that SDLP is broken.

Constructive Recognition Problem

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Since Lie groups and alternating groups are defined as (projective) linear groups the SDLP reduces to the following:

Constructive Recognition Problem, Babai and Beals [1999](#page-57-2)

Given a simple black-box group *G*, the problem require to find a computationally efficient isomorphism between *G* and an explicitly defined simple group.
Theorem (Classification of Finite Simple Groups) Every finite simple group is isomorphic to a member of one of four infinite classes:

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		- 3.2 solved for any BBG, up to DLOG in Borovik and Yalçınkaya [2020](#page-58-2)
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 $G_2(q), q \geqslant 3; F_4(q); E_6(q); {}^2E_6(q); {}^3D_4(q); E_7(q); E_8(q)$

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In Kantor and Magaard [2013](#page-59-1) and 2015 reduce the problem to PSL(2*, q*), using *number theory oracles*.

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*solved if q is odd 19

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- 3. the other are referred as the six *pariahs*, and have cardinality *≤* 2 67

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- 4. For *G* in the happy family *b*(*G*) *≤* 2 *·* 119² *≈* 2 15;
- 5. For G one of the six pariahs $b(\mathsf{G}) = 67^2 \approx 2^{13};$

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Meme

Thank you for your attention! <eprint.iacr.org/2024/905>

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[Additional Material](#page-61-0)

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However, this branch of literature typically wishes to achieve much stronger results and are thwarted by DLOG computation - we do not impose this limitation since we assume QCs.

1. if we know the particular structure of the group *G*, we can use it to construct for any subgroup *S* the smallest normal subgroup containing *⟨S G ⟩* in linear time, as explained in Babai et al. [1991](#page-57-1).

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	- 3.2 or abelian, so we can use point 1 to get the maximal normal subgroup $A_1 \triangleleft G/G_1$ and A_1G_1 will be a maximal normal in G by the correspondence theorem.

[¶]we need *G/G*¹ to have the unique encoding property

SDLP on Matrix Groups (Imran and Ivanyos [2024](#page-58-3))

Consider *G ≤* GL*n*(F) and *ϕ ∈* Inn(*G*) such that *ϕ*(G) = SGS*−*¹ , then:

*s*_{G,∅}(*x*) = G · SGS^{−1} · S²GS^{−2} · · · S^{x−1}GS^{−x+1} · S^xGS^{−x} =

SDLP on Matrix Groups (Imran and Ivanyos [2024](#page-58-3))

Consider *G ≤* GL*n*(F) and *ϕ ∈* Inn(*G*) such that *ϕ*(G) = SGS*−*¹ , then:

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s_{G,\phi}(x)=G\cdot SGS^{-1}\cdot S^2\overbrace{GS^{-2}\cdots S^{x-1}GS^{-x+1}\cdot S^x}^{S}S^{-x}=
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s_{G,\phi}(x) = G \cdot SGS^{-1} \cdot S^{z} \overbrace{GS^{-2}}^{S} \cdots S^{x-1}GS^{-x+1} \cdot S^{x} \overbrace{GS^{-x}}^{S} = \\ = GS \cdot GS \cdot GS \cdot SS \cdots SG \cdot S^{-x} = (GS)^{x} \cdot G \cdot S^{-x}
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$$
\text{vec}(s_{G,\phi}(x)) = \text{vec}((GS)^x \cdot G \cdot S^{-x})
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$$
\begin{aligned} \text{vec}(s_{G,\phi}(x)) &= \text{vec}\left(\left(\text{GS}\right)^x \cdot \text{G} \cdot \text{S}^{-x}\right) \\ &= \text{vec}\left(\left(\text{GS}\right) \cdot \left(\text{GS}\right)^{x-1} \cdot \text{G} \cdot \text{S}^{-(x-1)} \cdot \text{S}^{-1}\right) \end{aligned}
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&= \text{vec}\left((GS) \cdot S_{G,\phi}(x-1) \cdot S^{-1}\right) \\
&= \left[(GS) \otimes S^{-1}\right] \text{vec}(S_{G,\phi}(x-1)) \\
&\text{...repeating the argument } x - 1 \text{ more times...} \\
&= \left[(GS) \otimes S^{-1}\right]^x \text{vec}(G)\n\end{aligned}
$$