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Side Channel Cryptanalysis of a Higher Order Masking Scheme

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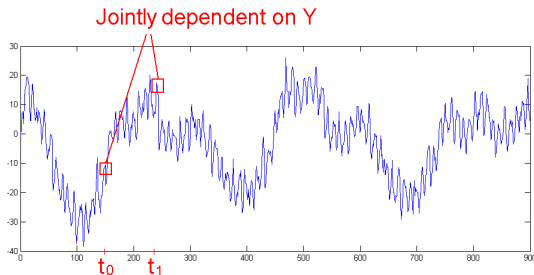
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- The **physical leakage** of the execution of any algorithm depends on the **intermediate variables**
- DPA exploits leakage on **sensitive variables** that depends on the secret key
- Common countermeasure: **masking**
 - ▶ A random value is added to every sensitive variable
 - ▶ \Rightarrow Instantaneous leakage independent of sensitive variables

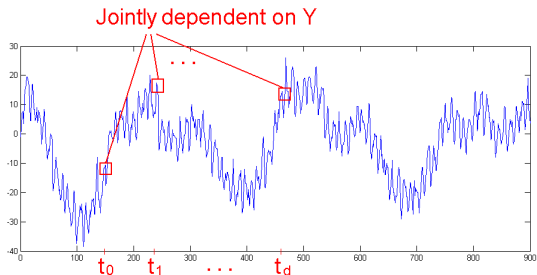
Higher Order DPA (HO-DPA) Against First Order Masking

- Y : sensitive variable, M : mask
 - ▶ $Y \oplus M$ processed at t_0
 - ▶ M processed at t_1
- First order DPA attack not feasible
- Second order DPA attack feasible



Higher Order DPA (HO-DPA) Against d -th Order Masking

- Y : sensitive variable, M_i 's: masks
 - ▶ $Y \oplus M_1 \oplus \dots \oplus M_d$ processed at t_0
 - ▶ M_i 's processed at t_i
- d -th order DPA attack not feasible
- $(d + 1)$ -th order DPA attack feasible



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- The complexity of an HO-DPA is **exponential** with its order (Chari *et al.* in CRYPTO'99)
- The order d is a good security parameter
- A generic masking scheme must
 - ▶ involve d random masks per sensitive variable
 - ▶ thwart d -th order DPA

Formalizing the security:

- **sensitive variable**: depends on both the plaintext and the secret key

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Formalizing the security:

- **sensitive variable**: depends on both the plaintext and the secret key
- **d -th order flaw**: a d -tuple of intermediate variables statistically dependent on a sensitive variable

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Formalizing the security:

- **sensitive variable**: depends on both the plaintext and the secret key
- **d -th order flaw**: a d -tuple of intermediate variables statistically dependent on a sensitive variable
- **security against d -th order DPA**: no d -th order flaw

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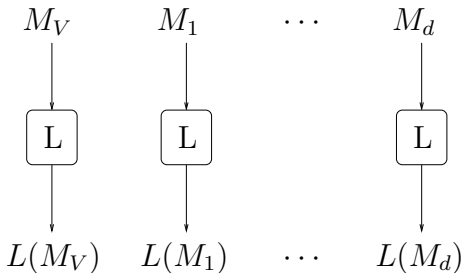
Conclusion

- Each sensitive variable Y is masked with d masks M_i 's
- **completeness:** the masked variable M_V and the masks M_i 's must always satisfy:

$$M_V \oplus M_1 \oplus \dots \oplus M_d = Y$$

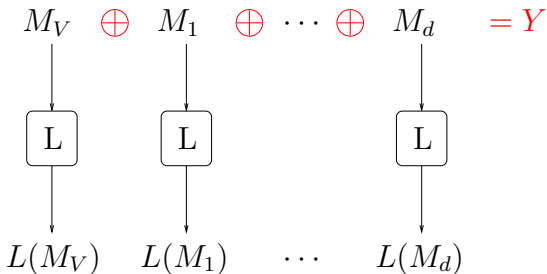
- **security:** M_V and all the M_i 's must be processed separately

- In network of linear layers and non-linear SBoxes
 - ▶ Propagation through a **linear layer**

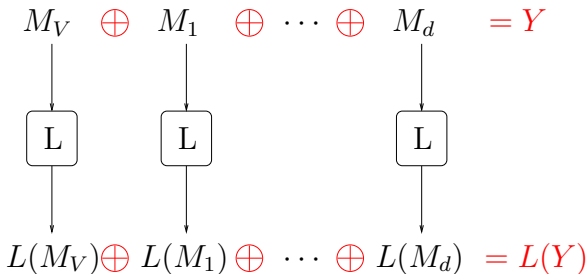


Higher Order Masking Schemes

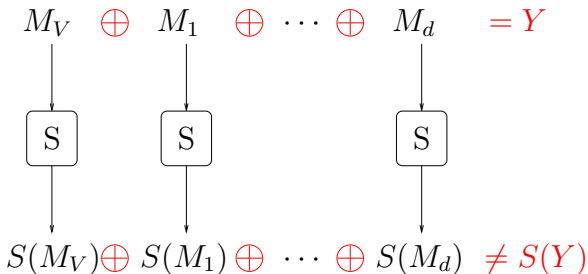
- In network of linear layers and non-linear SBoxes
 - ▶ Propagation through a **linear layer**



- In network of linear layers and non-linear SBoxes
 - ▶ Propagation through a **linear layer**



- In network of linear layers and non-linear SBoxes
 - ▶ Propagation through a **non-linear SBox**



- In network of linear layers and non-linear SBoxes
 - ▶ Propagation through a **non-linear SBox**

$$\begin{array}{ccccccc}
 M_V & \oplus & M_1 & \oplus & \dots & \oplus & M_d & = Y \\
 \downarrow & & \downarrow & & & & \downarrow & \\
 ?? & & ?? & & & & ?? & \\
 \downarrow & & \downarrow & & & & \downarrow & \\
 N_V & \oplus & N_1 & \oplus & \dots & \oplus & N_d & = S(Y)
 \end{array}$$

Problem

How to **securely** compute $(N_V, N_i's)$ from $(M_V, M_i's)$?

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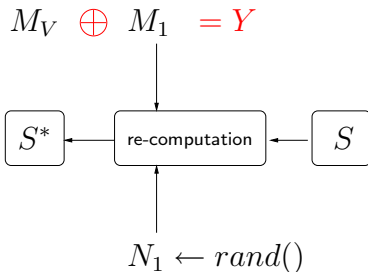
Conclusion

- Problem widely investigated for 1-st order masking
 - ▶ Efficient and widely used method: the **table re-computation**
- For d -th order masking: one single proposal in the Literature
 - ▶ [SP06] - K. Schramm and C. Paar, "Higher Order Masking of the AES" in CT-RSA 2006.
 - ▶ Principle: adapt the table re-computation method to d -th order masking
- Our paper: [SP06] is **broken by 3-rd order DPA** for any value of the masking order d

Table re-computation method

For 1-st order masking

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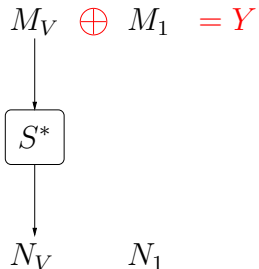


- For all x : $S^*(x) \leftarrow S(x \oplus M_1) \oplus N_1$

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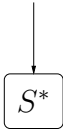
- For all x : $S^*(x) \leftarrow S(x \oplus M_1) \oplus N_1$
- $N_V \leftarrow S^*(M_V)$

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$$M_V \oplus M_1 = Y$$



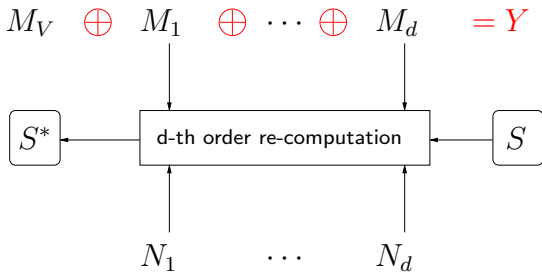
$$N_V \oplus N_1 = S(Y)$$

- For all x : $S^*(x) \leftarrow S(x \oplus M_1) \oplus N_1$
- $N_V \leftarrow S^*(M_V) = S(M_V \oplus M_1) \oplus N_1 = S(Y) \oplus N_1$

Table re-computation method

For d -th order masking [SP06]

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- For every x : $S^*(x) = S \left(x \oplus \bigoplus_{i=1}^d M_i \right) \oplus \bigoplus_{i=1}^d N_i$

Table re-computation method

For d -th order masking [SP06]

$$M_V \oplus M_1 \oplus \dots \oplus M_d = Y$$



$$N_V \oplus N_1 \oplus \dots \oplus N_d = S(Y)$$

- For every x : $S^*(x) = S\left(x \oplus \bigoplus_{i=1}^d M_i\right) \oplus \bigoplus_{i=1}^d N_i$

Table re-computation method

For d -th order masking [SP06]

$$M_V \oplus M_1 \oplus \dots \oplus M_d = Y$$



$$N_V \oplus N_1 \oplus \dots \oplus N_d = S(Y)$$

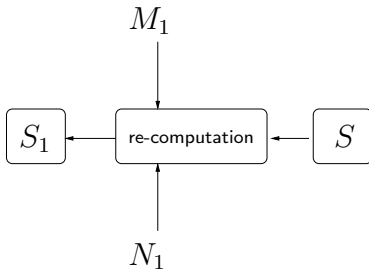
- For every x : $S^*(x) = S\left(x \oplus \bigoplus_{i=1}^d M_i\right) \oplus \bigoplus_{i=1}^d N_i$

Problem

How to **securely** compute S^* from $(S, M_i's, N_i's)$.

Process d successive table re-computations:

- $S_1(x) = S(x \oplus M_1) \oplus N_1$



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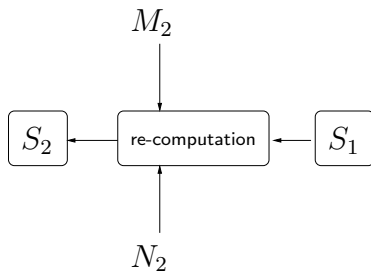
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Process d successive table re-computations:

- $S_1(x) = S(x \oplus M_1) \oplus N_1$
- $S_2(x) = S(x \oplus M_1 \oplus M_2) \oplus N_1 \oplus N_2$



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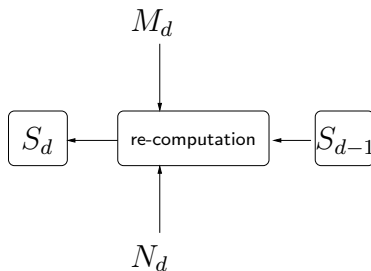
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Process d successive table re-computations:

- $S_1(x) = S(x \oplus M_1) \oplus N_1$
- $S_2(x) = S(x \oplus M_1 \oplus M_2) \oplus N_1 \oplus N_2$
- ...
- $S_d(x) = S(x \oplus M_1 \oplus M_2 \oplus \dots \oplus M_d) \oplus N_1 \oplus N_2 \oplus \dots \oplus N_d$



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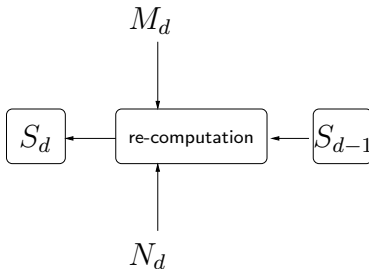
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Process d successive table re-computations:

- $S_1(x) = S(x \oplus M_1) \oplus N_1$
- $S_2(x) = S(x \oplus M_1 \oplus M_2) \oplus N_1 \oplus N_2$
- ...
- $S_d(x) = S^*(x)$



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- Let $M = \bigoplus_{i=1}^d M_i$ and $N = \bigoplus_{i=1}^d N_i$
- The masked variable M_V satisfies:
 - 1) $M_V = Y \oplus M$
- During the re-computation of table S_d :
 - 2) $S_d(0) = S(0 \oplus M) \oplus N$
 - 3) $S_d(1) = S(1 \oplus M) \oplus N$

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- Let $M = \bigoplus_{i=1}^d M_i$ and $N = \bigoplus_{i=1}^d N_i$
- The masked variable M_V satisfies:
 - 1) $M_V = Y \oplus M$
- During the re-computation of table S_d :
 - 2) $S_d(0) = S(0 \oplus M) \oplus N$
 - 3) $S_d(1) = S(1 \oplus M) \oplus N$
- The distribution of $(M_V, S_d(0), S_d(1))$ depends on Y
 - ▶ 3-rd order flaw!
 - ▶ thus a 3-rd order DPA theoretically feasible!

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- We have:

- 1) $M_V = Y \oplus M$

- 2) $S_d(0) = S(0 \oplus M) \oplus N$

- 3) $S_d(1) = S(1 \oplus M) \oplus N$

- $S_d(0) \oplus S_d(1) = S(M) \oplus S(M \oplus 1)$

 - ▶ depends on M

- Hence, $S_d(0) \oplus S_d(1)$ and M_V jointly depend on Y

- Hence, the 3-tuple $(M_V, S_d(0), S_d(1))$ depends on Y

- The attack also works for any 3-tuple ($a \neq b$):

$$\tau_{a,b} = (M_V, S_d(a), S_d(b))$$

iff $x \mapsto S(x) \oplus S(x \oplus a \oplus b)$ **is not constant**

- $\tau_{a,b}$ is independent of Y for every (a, b) iff S is affine
- Hence, S is non-affine $\Rightarrow \exists(a, b) : \tau_{a,b}$ depends of Y

- The attack also works for any 3-tuple ($a \neq b$):

$$\tau_{a,b} = (M_V, S_d(a), S_d(b))$$

iff $x \mapsto S(x) \oplus S(x \oplus a \oplus b)$ **is not constant**

- $\tau_{a,b}$ is independent of Y for every (a, b) iff S is affine
- Hence, S is non-affine $\Rightarrow \exists(a, b) : \tau_{a,b}$ depends of Y
- For every non-affine SBox, the generic scheme [SP06] admits a 3-rd order flaw!

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- The attack also works for any 3-tuple ($a \neq b$):

$$\tau_{a,b} = (M_V, S_d(a), S_d(b))$$

iff $x \mapsto S(x) \oplus S(x \oplus a \oplus b)$ **is not constant**

- $\tau_{a,b}$ is independent of Y for every (a, b) iff S is affine
- Hence, S is non-affine $\Rightarrow \exists(a, b) : \tau_{a,b}$ depends of Y
- The generic scheme [SP06] is broken by 3-rd order DPA for any masking order d !

Conclusion

The approach of processing d table re-computations is not sound to thwart d -th order DPA.

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- Generic scheme very costly
 - ▶ d table re-computations per S-Box access
- Proposed improvement [SP06]:
 - ▶ d table re-computations for the first SBox access
 - ▶ **1 single table re-computation** for each next SBox access
- How ?
 - ▶ each new masked SBox is derived from the previous one

- Let M_V and M'_V be two consecutive masked SBox inputs
 - ▶ $M_V = Y \oplus M_1 \oplus \dots \oplus M_d$
 - ▶ $M'_V = Y' \oplus M'_1 \oplus \dots \oplus M'_d$

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- Let M_V and M'_V be two consecutive masked SBox inputs
 - ▶ $M_V = Y \oplus M_1 \oplus \dots \oplus M_d$
 - ▶ $M'_V = Y' \oplus M'_1 \oplus \dots \oplus M'_d$
- Let S^* and S^*_{new} be the masked SBoxes:
 - ▶ $S^*(x) = S\left(x \oplus \bigoplus_{i=1}^d M_i\right) \oplus \bigoplus_{i=1}^d N_i$
 - ▶ $S^*_{new}(x) = S\left(x \oplus \bigoplus_{i=1}^d M'_i\right) \oplus \bigoplus_{i=1}^d N'_i$

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■ From:

$$\triangleright S^*(x) = S \left(x \oplus \bigoplus_{i=1}^d M_i \right) \oplus \bigoplus_{i=1}^d N_i$$

$$\triangleright S_{new}^*(x) = S \left(x \oplus \bigoplus_{i=1}^d M'_i \right) \oplus \bigoplus_{i=1}^d N'_i$$

■ we have:

$$S_{new}^*(x) = S^* \left(x \oplus \bigoplus_{i=1}^d M_i \oplus \bigoplus_{i=1}^d M'_i \right) \oplus \bigoplus_{i=1}^d N_i \oplus \bigoplus_{i=1}^d N'_i$$

■ $S_{new}^* \leftarrow \text{re-computation} \left(S^*, \bigoplus_{i=1}^d M_i \oplus \bigoplus_{i=1}^d M'_i, \right.$
 $\left. \bigoplus_{i=1}^d N_i \oplus \bigoplus_{i=1}^d N'_i \right)$

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■ From:

$$\triangleright S^*(x) = S \left(x \oplus \bigoplus_{i=1}^d M_i \right) \oplus \bigoplus_{i=1}^d N_i$$

$$\triangleright S_{new}^*(x) = S \left(x \oplus \bigoplus_{i=1}^d M'_i \right) \oplus \bigoplus_{i=1}^d N'_i$$

■ we have:

$$S_{new}^*(x) = S^* \left(x \oplus \bigoplus_{i=1}^d M_i \oplus \bigoplus_{i=1}^d M'_i \right) \oplus \bigoplus_{i=1}^d N_i \oplus \bigoplus_{i=1}^d N'_i$$

■ $S_{new}^* \leftarrow \text{re-computation}(S^*, \text{ICM}, \text{OCM})$

$$\triangleright \text{ICM} = \bigoplus_{i=1}^d M_i \oplus \bigoplus_{i=1}^d M'_i$$

$$\triangleright \text{OCM} = \bigoplus_{i=1}^d N_i \oplus \bigoplus_{i=1}^d N'_i$$

- The processing of **ICM** (*resp.* **OCM**) introduces a 3-rd order flaw
- ICM 3-rd order flaw:
 - 1) $M_V = Y \oplus M_1 \oplus \dots \oplus M_d$
 - 2) $M'_V = Y' \oplus M'_1 \oplus \dots \oplus M'_d$
 - 3) **ICM** = $M_1 \oplus \dots \oplus M_d \oplus M'_1 \oplus \dots \oplus M'_d$
- $M_V \oplus M'_V \oplus \mathbf{ICM} = Y \oplus Y'$

3-rd order flaws

- The processing of **ICM** (*resp.* **OCM**) introduces a 3-rd order flaw
- OCM 3-rd order flaw:
 - 1) $N_V = S(Y) \oplus N_1 \oplus \dots \oplus N_d$
 - 2) $N'_V = S(Y') \oplus N'_1 \oplus \dots \oplus N'_d$
 - 3) **OCM** = $N_1 \oplus \dots \oplus N_d \oplus N'_1 \oplus \dots \oplus N'_d$
- $N_V \oplus N'_V \oplus \text{OCM} = S(Y) \oplus S(Y')$

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- The processing of **ICM** (resp. **OCM**) introduces a 3-rd order flaw
- OCM 3-rd order flaw:
 - 1) $N_V = S(Y) \oplus N_1 \oplus \dots \oplus N_d$
 - 2) $N'_V = S(Y') \oplus N'_1 \oplus \dots \oplus N'_d$
 - 3) **OCM** = $N_1 \oplus \dots \oplus N_d \oplus N'_1 \oplus \dots \oplus N'_d$
- $N_V \oplus N'_V \oplus \text{OCM} = S(Y) \oplus S(Y')$
- The improved scheme [SP06] is broken by 3-rd order DPA for any masking order d !

Conclusion

The improvement of the scheme – that makes it efficient in a low resource environment – is not suitable.

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■ Attack simulations

- ▶ Known plaintext attacks on AES
- ▶ Hamming weight model with (low) Gaussian noise

■ Two attack strategies

- ▶ Combining 3O-DPA:
 - correlation attack on a combination of the 3 leakages
 - classical HO-DPA attack
- ▶ Profiling 3O-DPA:
 - Maximum likelihood test
 - strong adversarial model (requires the knowledge of the exact distribution of the 3 leakages)

■ See the paper for further details on the simulations

Implementation	Attack	Measurements
Generic scheme	combining 3O-DPA	6.10^6
Generic scheme	profiling 3O-DPA	2.10^3
Improved scheme	combining 3O-DPA	10^5
Improved scheme	profiling 3O-DPA	10^3

Table: Number of measurements required for a success rate of 50%.

- Our attacks are practical in a classical leakage model
- The profiling 3O-DPA is more efficient than the combining 3O-DPA
- The attacks are more efficient on the improved scheme

- The scheme [SP06] is vulnerable to 3-rd order DPA and is not suitable for d -th order DPA resistance
 - ▶ First attack: process d table re-computations not suitable
 - ▶ Second attack: proposed improvement not suitable
- Our attacks are practical in a weakly noisy environment
- The design of a Higher Order Masking Scheme is still an open issue